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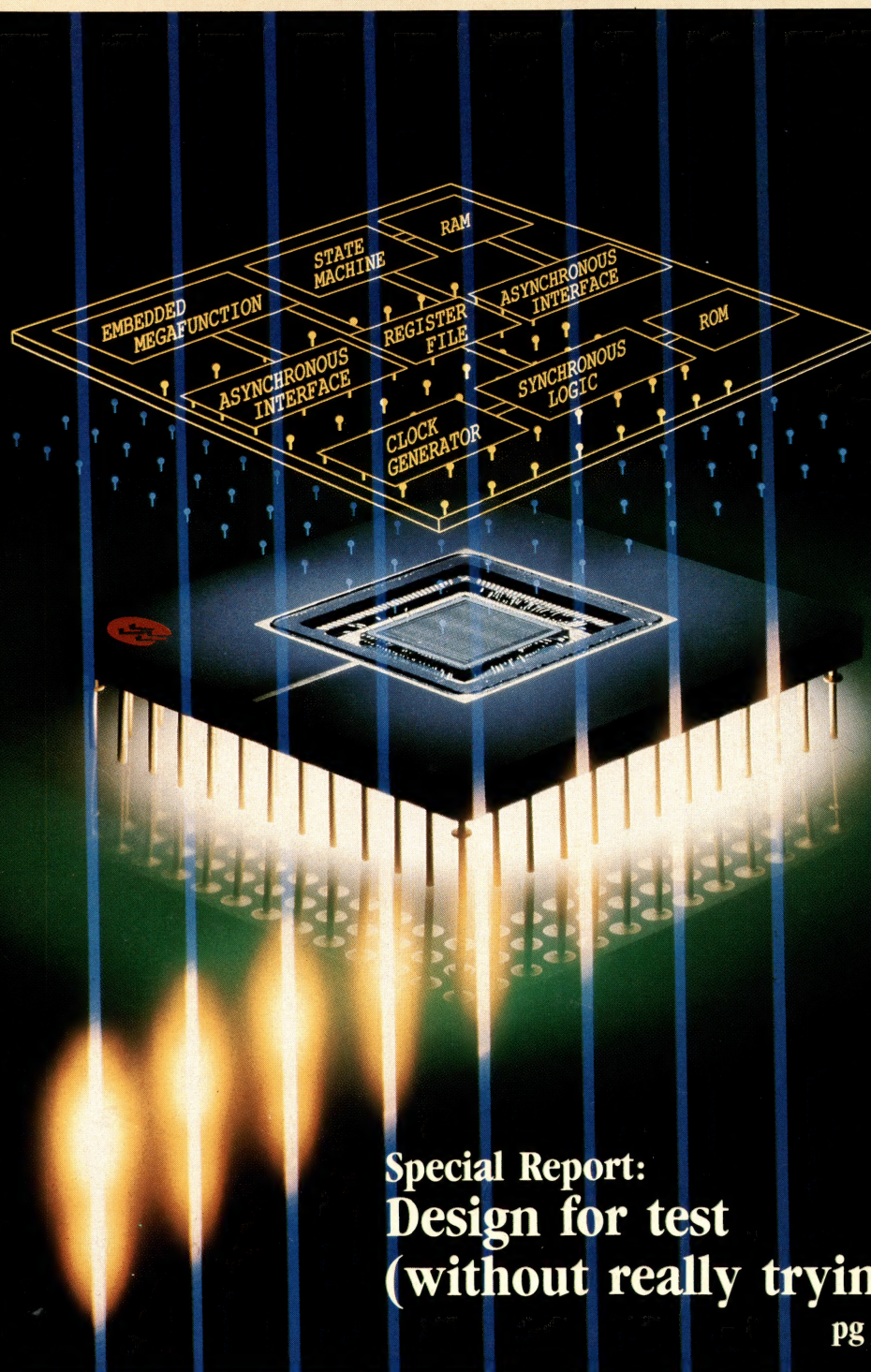
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18 Jan 1992

A CAHNERS PUBLICATION

February 17, 1992

ELECTRONIC TECHNOLOGY FOR ENGINEERS AND ENGINEERING MANAGERS WORLDWIDE



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(without really trying)
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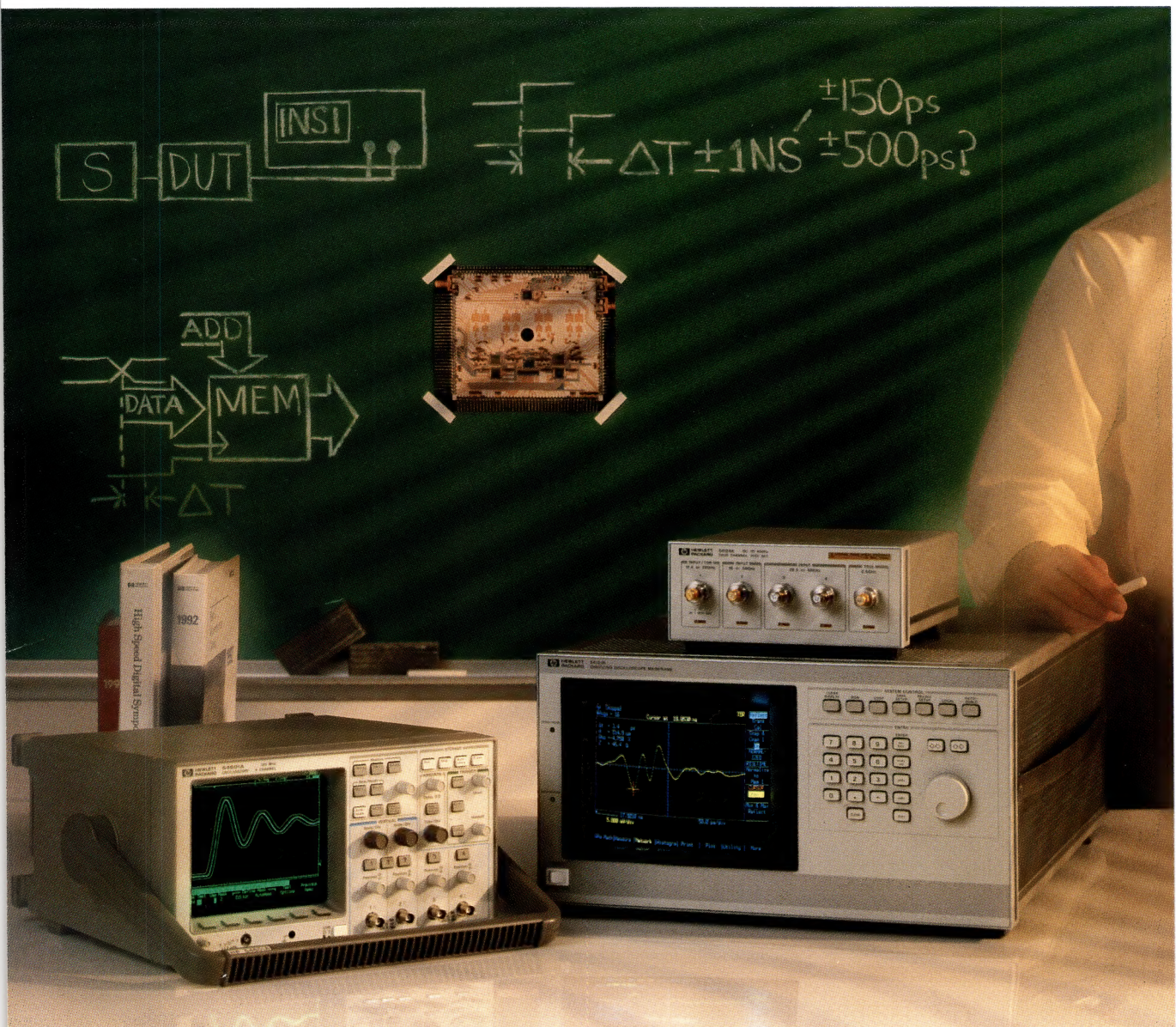
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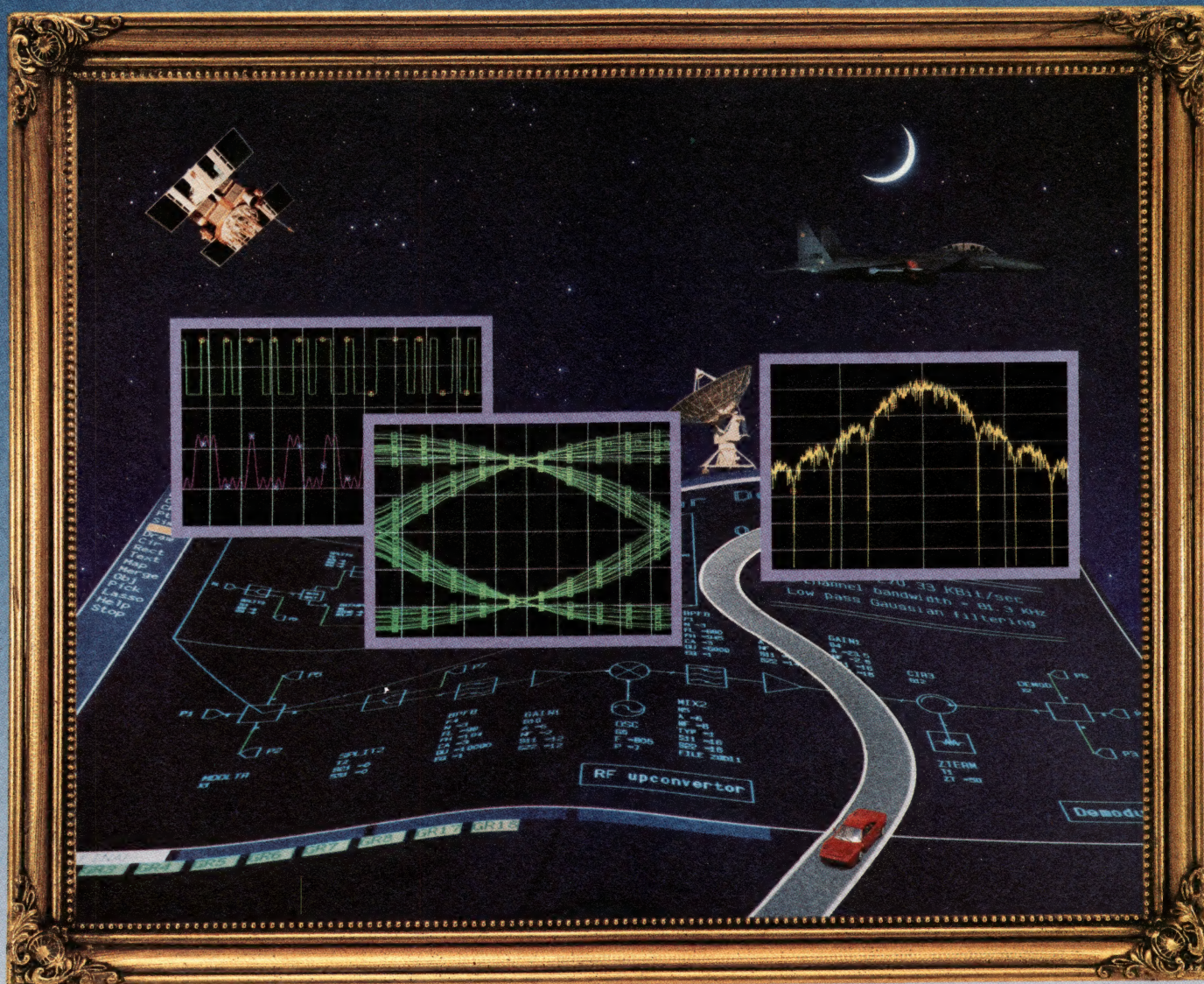
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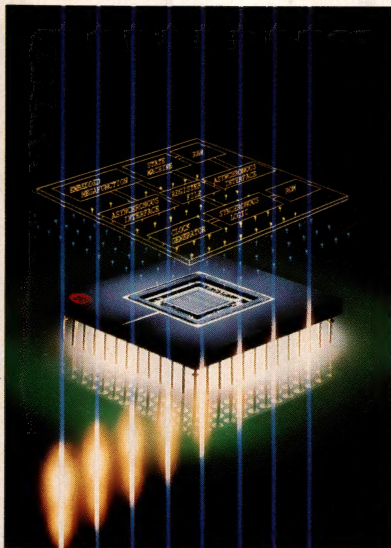
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CIRCLE NO. 5

February 17, 1992

VOLUME 37, NUMBER 4

ELECTRONIC TECHNOLOGY FOR ENGINEERS AND ENGINEERING MANAGERS WORLDWIDE



On the cover: Transparent test techniques inject testability into your ASIC designs, bypassing the typical time and expense limitations. (Photo courtesy Crosscheck Technology) **PAGE 114**

SPECIAL REPORT

Design for test (without really trying)

Despite the dangers of ignoring testability, subtle costs can make designing an ASIC for test prohibitively expensive. Testability tools provide construction techniques that lower the cost of designing for test.

—Michael C Markowitz, Technical Editor

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DESIGN FEATURES

Designer's guide to measuring op-amp distortion

—Jerald Graeme, Burr-Brown Corp

Part 1—Op-amp distortion measurement bypasses test-equipment limits

Part 1 of this 2-part series introduces the theory involved in measuring the low distortion levels of state-of-the-art op amps. It also provides simple methods for characterizing some low-distortion op amps.

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Part 2—Advanced techniques tackle advanced op amps' extremely low distortion

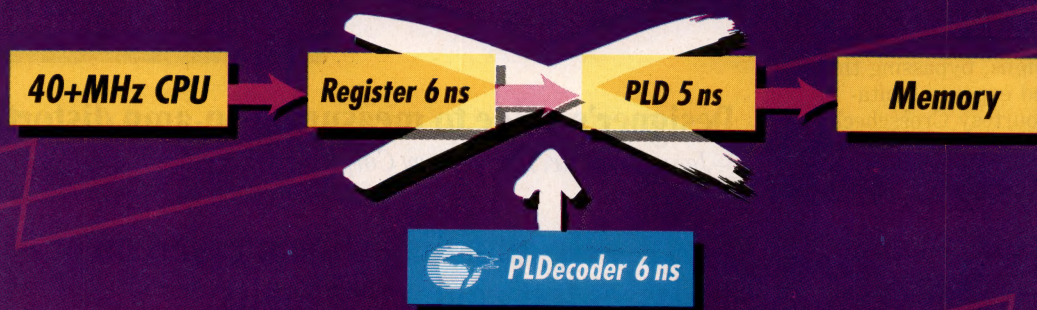
The second part of this 2-part series describes how to measure the distortion of more complex amplifier circuits and how to handle the highest-performance op amps.

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February 17, 1992

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When your circuit designs run up against data-book specification limits, turn to a dc parameter analyzer—it will accurately measure the performance limits of your components. **PAGE 65**

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TECHNOLOGY UPDATES

European manufacturing contractors encourage close relationships

European contract manufacturers want to contribute to the success of your product by becoming part of the business.—*Brian Kerridge, Technical Editor*

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Parameter analyzers give you a closer look at dc-circuit performance

Parameter analyzers based on source-measure units provide flexible and sensitive instruments for characterizing dc circuits.—*Doug Conner, Technical Editor*

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High-speed digital circuits: Timing techniques help signals stay in sync

You'll need a variety of practical skills and tools to tackle high-speed timing problems.—*Anne Watson Swager, Technical Editor*

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PROFESSIONAL ISSUES

Training with technology

Sports science and high-tech training equipment have helped our Olympic athletes, but a shortage of funds hinders the program.—*Jay Fraser, Associate Editor*

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Seekers of something for nothing can start their quest with Technical Editor Michael M Markowitz's Special Report "Design for test (without really trying)." Although you won't find a prescription for free testability in this article, you will find a realistic look at the true costs of design for test (DFT). You'll also find tools and techniques that make designing for test much easier than you might think. Be sure to check out the top-10 reasons for not using DFT methods in the same article.

Many engineers don't employ DFT techniques because some of these test methods degrade device performance. However, designers who use only the data-sheet specifications rarely know the true performance limits of the devices they incorporate in their designs. You'll find several articles on device characterization in this issue of EDN.

For starters, Technical Editor Doug Conner examines parameter analyzers. You might think parameter analyzers are primarily for incoming inspection, but you can also use these instruments to characterize device aspects not detailed in the manufacturer's spec sheets. If you need to develop or refine realistic simulation models, parameter

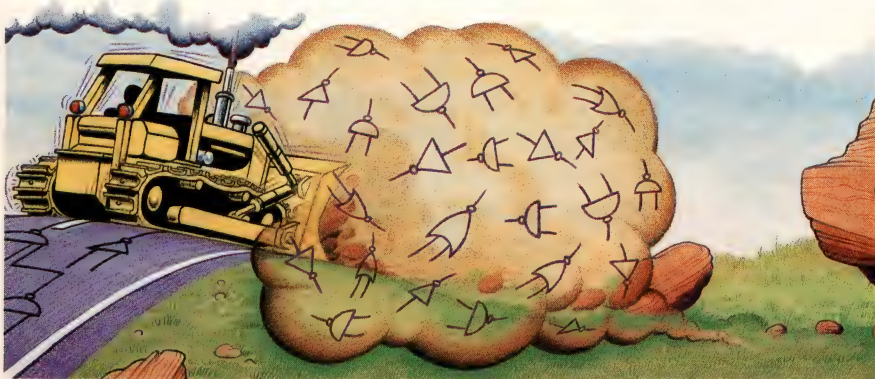
analyzers let you collect aggregate parametric information over device lots.

Fans of Burr-Brown's analog guru Jerald Graeme will find his latest article, on characterizing op-amp distortion, in this issue. Graeme points out that distortion performance in op amps has become increasingly important because of the recent upswing in DSP applications.

Time is another tough parameter to characterize. If you can't master your design's timing, you're really in trouble. In her Technical Update on high-speed digital circuits, Technical Editor Anne Watson Swager focuses on timing techniques, such as timing skew and clock generation and distribution, that help you take up the temporal slack.

One reason for characterizing devices is to ensure manufacturability no matter where the product is built. If your company expects to sell products based on your designs in Europe, you might want to study Technical Editor Brian Kerridge's report on contract manufacturing within the European community.

Steven H Leibson,
Executive Editor



This issue's Special Report covers CAE tools that construct tests or test logic.

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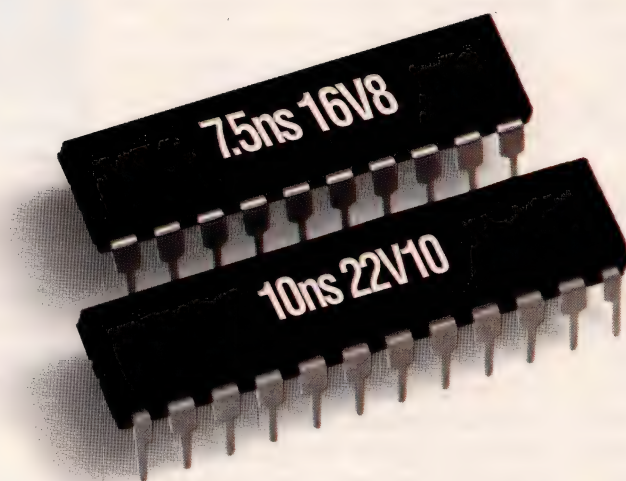
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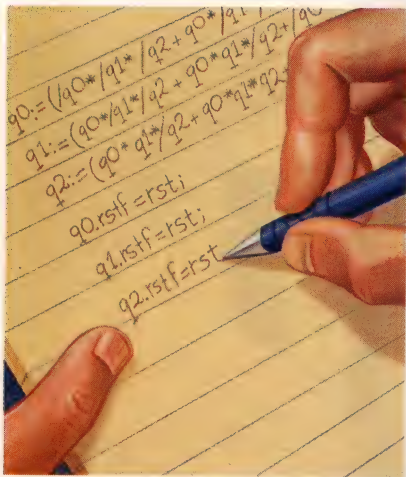


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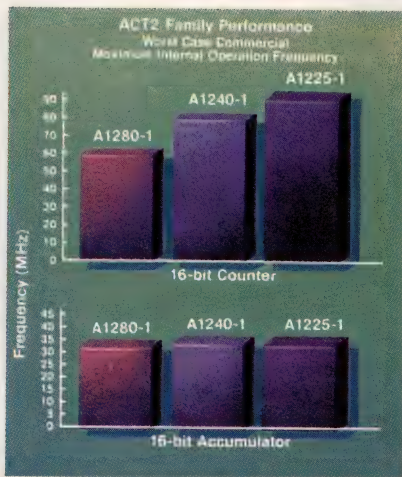
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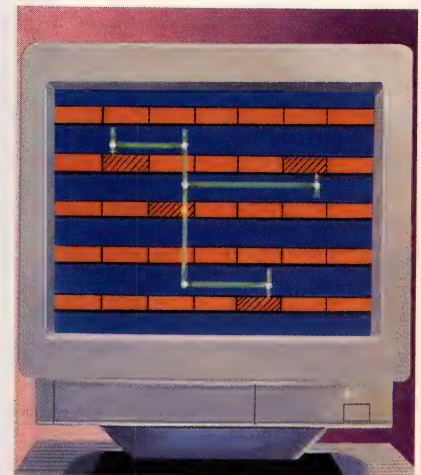
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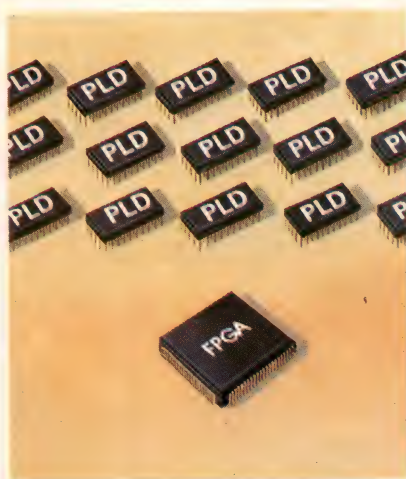
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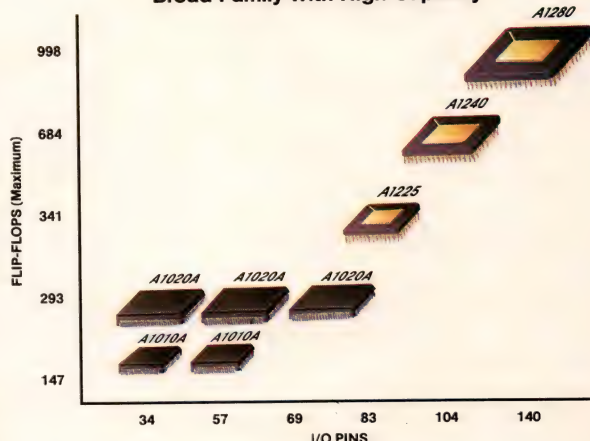


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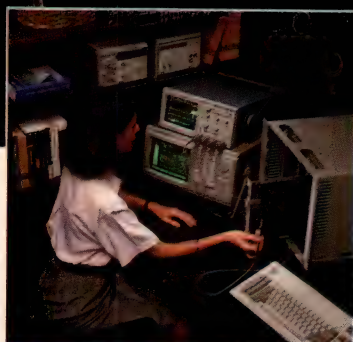
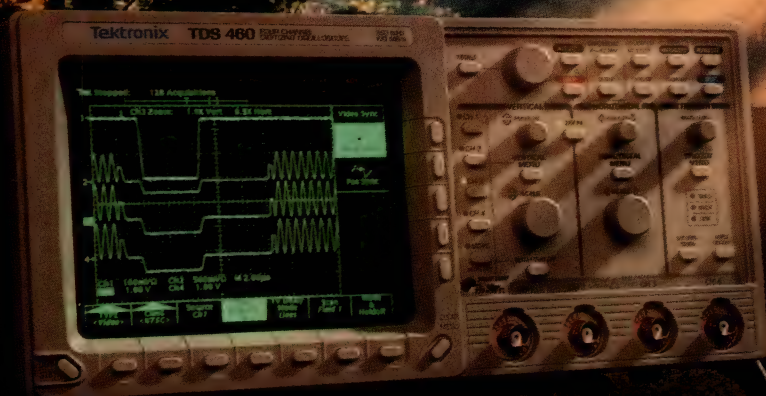


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CIRCLE NO. 17

EDN February 17, 1992 • 17

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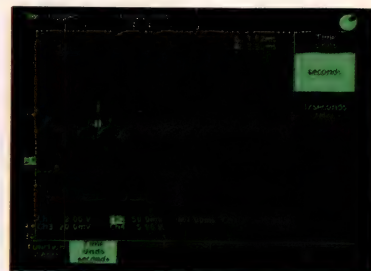
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New CPU boards shown at Buscon

A number of companies showed their new CPU boards for open buses at Buscon '92 West in Long Beach, CA, a few weeks ago. The emphasis of most of the products, naturally, is on faster CPU performance and highly integrated boards. For example, Omnibyte Corp's VMEbus Taurus board employs a dual-bus architecture that links onboard 25-MHz 68040 and 68030 μ Ps. The design dedicates the 68030 to I/O tasks, thereby freeing the 68040 to execute application code with little interruption. The board includes a memory architecture that lets the 68040 address as much as 256 Mbytes of memory, and the 68030 has access to as much as 64 Mbytes of memory. You can order configurations of the board with an Ethernet port, a SCSI host adapter, six serial ports, a parallel-printer interface, and 32 programmable digital I/O lines. A configuration featuring 4 Mbytes of dynamic RAM, 128 kbytes of static RAM, six serial ports, and the parallel interface costs \$3495.

Motorola, meanwhile, announced its plans for board-level support of the new 88110 RISC μ P. The company plans a single-slot VMEbus board that will include SCSI-2, Ethernet, and VSB interfaces as well as the μ P and a 64-bit-wide memory array. Final specs and pricing of the board have been delayed because the company's IC division has yet to ship production versions of the 88110 IC. The new μ P, however, will have a 3-D graphics-execution unit and a floating-point unit on chip. Omnibyte Corp, West Chicago, IL, (708) 231-6880, FAX (708) 231-7042. Motorola Inc, Tempe, AZ, (602) 438-3000.—Maury Wright

Embed a workstation in your next test system

You can use a 33-MHz 80486-based workstation with as many as four Expansion Module bus (EXMbus) expansion slots for your next embedded VXI controller. The EPC-7 from Radisys is a C-size plug-in board that you can use in place of an external workstation connected to your test rack. To provide

flexible I/O expansion, the board's EXMbus architecture accepts modules for IEEE-488, Ethernet, RS-232C, RS-422, RS-485, a modem, solid-state disks, an interval timer, and an assortment of video controllers. An adapter module lets you plug in a full-length ISA expansion board for specialized I/O interfaces that aren't available as EXM modules. Standard hardware includes a serial port, a printer port, a reset button, and a keyboard interface. Three connec-

tors let you externally route VXIbus trigger and clock signals. A SCSI connector lets you add external equipment such as tape-backup units or optical-disk drives.

For \$6995, this 2-slot-wide controller includes a 33-MHz 80486 CPU, 2 Mbytes of dynamic RAM, a 52-Mbyte hard-disk drive, a 3½-in. floppy-disk drive, and the EP-Connect runtime package for DOS. A VGA graphics controller sells for \$450. All software and application programs that run on the firm's EPC-2 systems will also run on the board without modification. Radisys Corp, Beaverton, OR, (800) 950-0044; (503) 690-1229, FAX (503) 690-1228.—J D Mosley

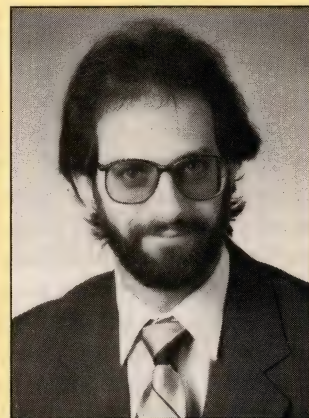
Gate array has 60-psec gate delay and 350,000 gates

Vitesse Semiconductor Corp continues to push GaAs semiconductors into mainstream semiconductor applications. The new VGFX350K member of the FX family of gate arrays includes 1.2 million active transistors—approximately the same number as the Intel 80486 μ P. The 0.6- μ m gate arrays feature a channel-less architecture with gate delays less than 60 psec. The first array Vitesse produced for a customer includes two 44-kbit blocks of static RAM and two 5-port reg-

ister files. The RAM array features a 3-nsec access time. Expect a non-recurring engineering cost of \$70,000 to \$120,000 to develop a VGFX350K array. The company also introduced 20,000- and 40,000-gate members of the FX family that previously included only 100,000- and 200,000-gate arrays. Vitesse Semiconductor Corp, Camarillo, CA, (805) 388-3700, (805) 987-5896.—Maury Wright

EDN Asia gets Chief Editor

Michael Markowitz is leaving his post as Technical Editor at EDN Magazine to become Chief Editor of EDN Asia. Michael will join Jack Kompan, Publisher of EDN Asia, in Canners Publishing's Hong Kong office.



Michael has been with EDN since 1988. Before coming to EDN, he was Senior IC Design and Applications Engineer at Marconi Electronic Devices and before that he designed

custom ICs for General Instruments' Microelectronics Division (now Microchip Technology). Michael has a BS in Liberal Arts from Haverford College, a BEEE from SUNY, Stony Brook, and an MBA from Adelphi University.

EDN Asia will begin monthly publication in May and will have a controlled circulation of 28,000. The magazine will carry the same types of technology features, reviews of technology trends, and surveys of state-of-the-art product areas as EDN does in the United States and Europe. It will also carry original, Asia-specific new-product stories, literature available

in Asia, and career-related articles. The magazine is based in Hong Kong and will circulate to readers in Korea, Taiwan, Hong Kong, and ASEAN (the Association of South East Asian Nations, which comprises Brunei, Indonesia, Malaysia, the Philippines, Singapore, and Thailand). It will be published in English, Chinese (Mandarin), and Korean.

Send EDN Asia-specific product announcements to Jack Kompan or Michael Markowitz. EDN Asia, 22/F Lo Yong Court, 212-220 Lockhart Rd, Wanchai, Hong Kong, (852) 572-2037, FAX (852) 838-5912.—Susan Rose

European Group aims to advance MCM technology

Eureka project EU462 brings together 13 European companies with the common objective of developing design tools and manufacturing techniques for multi-chip modules (MCMs). Funding provided by governments supporting the project amounts to 18.3 million ECUs (roughly \$23.4 million), which will be spent over the next three years. The project members will make a special study of the use of nonsilicon substrate material such as ceramic, laminate, aluminum nitride, and metal-based compounds. Project teams will focus on seven key areas covering substrates, thermal management, die attachment, interconnection, protection, thermal and electrical modeling, and CAD tools. Two specific aims of the project are to achieve high-frequency performance to 40 GHz for telecommunications work, and 40W/cm² for automobile applications.

Project member companies come from four countries: Nokia in Finland; SAT, SOREP, ES2, and Racal-Redac TAD in France; Saab-Sania Combitech in Sweden; and BNR, Newmarket Microsystems, Racal-Redac Systems, University of Warwick, Johnson Matthey, Gwent Electronic Materials, and TWI in the UK. TWI, an independent R&D contractor, is providing the project coordination and leadership. TWI, Abington, Cambridge, UK, 0223 891162, FAX 0223 892588, contact Norman Stockham.—Brian Kerridge

12-bit A/D converter won't sweat in 200°C

Guaranteed to perform in temperatures exceeding 200°C, the 12-bit I-6H005 is a pin-compatible replacement for Burr-Brown's ADC10HT A/D converter. Packaging techniques provide this chip with a 50% reduction in mass over the Burr-Brown part, which the company claims makes the chip less susceptible to shock in high g-force situations. Offering both serial and parallel data outputs, this IC also has a monolithic, internal 10V reference. Suitable for applications involving engine or power control, this device also has an internal clock and hermetic packaging. The chip costs \$650 (100); evaluation samples cost \$250. ITAC Hybrid Technology, Garland, TX, (214) 494-3073, FAX (214) 494-4159, contact Rick Carr.

—J D Mosley

Get fuzzy in Japan

Followers of fuzzy logic should check out the proceedings of the International Fuzzy Engineering Symposium '91 held last November in Yokohama, Japan. The symposium dealt with both the theoretical underpinnings of fuzzy systems and practical applica-

tions such as digital signal processing, robotics, and flight control. For more information about the symposium, which will be held every three years, contact the Laboratory for International Fuzzy Engineering Research, Yokohama, Japan, 81-45-212-8211, FAX 81-45-212-8255.

—Steven H Leibson

Coprocessor accelerates CAD/CAE applications

Users of PCs based on the 80386DX processor can now boost performance of their CAD/CAE applications packages with a coprocessor chip set designed specifically for engineering applications. The Intel RapidCAD engineering coprocessor chip set replaces the 80386DX CPU and 80387DX coprocessor in your system. The chip set will also work with all 386DX clock frequencies over a variety of bus architectures, including ISA, EISA, and MicroChannel. Performance improvements benchmarked by the company using Autodesk's AutoCAD Release 11 range from 8% for Redraw, 35% for Regen, and 46% for Hide.

Two chips comprise the set. The first chip fits in the CPU socket and is an 80386 processor with an integral 80387 coprocessor. The second chip fits in the coprocessor socket and provides glue logic for ex-

Text continued on pg 24

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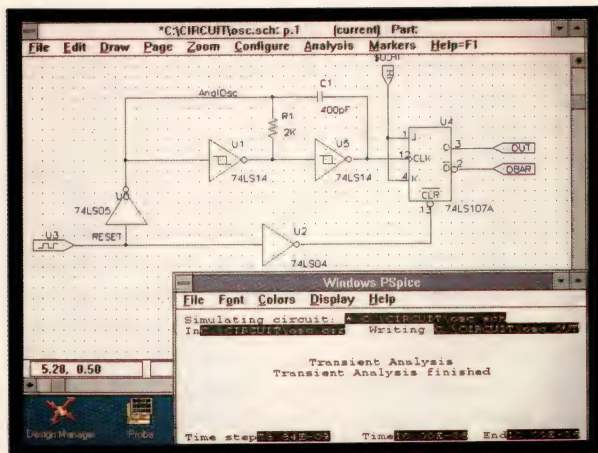
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—Richard Quinnell

Channel-less gate array awarded patent

Mehdy Khatakhota of SMOS Systems has received a patent on a novel interleaved, channel-less gate-array architecture. Typical cell architectures have two complementary transistors per cell aligned along the Y axis. In addition, the two source/drain interface regions and polysilicon gates for each transistor have a Y orientation, with the gates common to both transistors. Khatakhota's cell structure uses two transistors aligned along Y, but the interface regions have an X orientation. The two common gates have fingers along the interface regions and connect along the Y axis, one on the right-hand cell edge, the other on the left. Each gate has an additional finger between the two transistors, with the three fingers of each gate interleaved. This arrangement lets a router make all connections between transistors in a cell with straight lines in a single metal layer, preserving the other metal layer for cell-to-cell inter-

connect. The result is greater cell utilization.

SMOS Systems is planning an ASIC product, called the SLA1S gate-array family, based on this interleaved-gate architecture. The first devices will contain 7000 to 120,000 usable gates and should be available in the second quarter of 1992. SMOS Systems, San Jose, CA, (408) 954-0120, FAX (408) 922-0578.

—Richard Quinnell

IC ensures clock operation in absence of power

As an inexpensive way to ensure static-RAM (SRAM) data protection and reliable clock operation in the absence of power, the bq4285 real-time clock IC and bq4287 module also let PC designers easily upgrade nonvolatile memory capacity without extensive redesigning. Not only do these clocks eliminate any need for a second battery to protect your static RAM (SRAM) data, they also let you use lower-cost commodity SRAMs and improve reliability by protecting the battery from the environmental contaminants associated with board assembly. The lithium cells embedded in these clocks ensure data retention and clock operation for a minimum of 10 years in the absence of power. Including 114 bytes of user RAM for PC BIOS, prices range

Semicustom array combines analog and digital macrocells

The RLDA80 mixed-signal array from Raytheon Semiconductor combines 32V analog performance with some basic digital functions. A unique feature of the array is that it combines high-voltage operation with precision thin-film resistors. The array's major components include 8 analog gain blocks with matched thin-film resistor blocks, 8 large resistors, 4 medium-power npn transistors, 36 small npn transistors, 12 small pnp transistors, 10 digital input and output cells, 16 D flip-flops, and 18 logic function blocks.

The company provides kit parts and Spice models for prototyping and simulation. The analog macrocells have a frequency-response range of dc to 1 MHz. The digital macrocells have propagation delays typical of LS TTL logic. Thin-film resistors provide 200V isolation from the substrate and 100 ppm/°C typical temperature coefficients. The resistor tolerance is 10% with values as high as 200 kΩ. The array is available in a 44-pin leadless chip carrier in commercial, industrial, and military temperature ranges. Nonrecurring engineering charges start at \$30,000 and include layout, ten prototypes, and test development. Minimum order size is \$100,000. Delivery is 10 weeks after final design review. Raytheon Semiconductor, Mountain View, CA, (415) 968-9211, FAX (415) 966-7620.—Anne Watson Swager

from \$4.38 to \$8.40 (1000). Benchmark Microelectronics Inc, Carrollton, TX, (214) 407-0011, FAX (214) 407-9845, contact David Heacock.

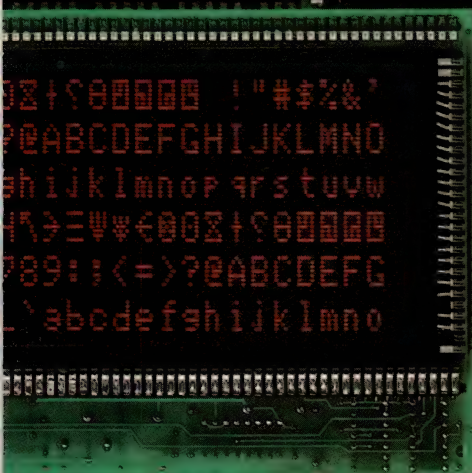
—J D Mosley

Logic-analyzer plug-in handles 102 channels

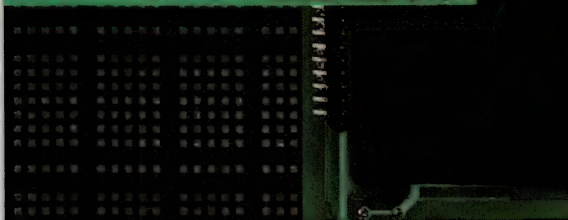
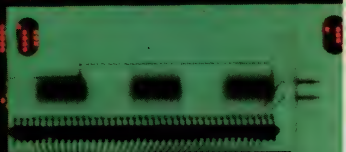
Hewlett-Packard has tripled the state-analysis speed and quintupled the timing-analysis speed of its 16500A. The 16550A plug-in holds 102 channels. Two plug-ins together make a 204-channel analyzer and you can install five card pairs in one unit. One card pair does 500-MHz

timing analysis on 102 channels with 8 kwords of memory or 250-MHz timing analysis on 204 channels with 4 kwords. If you use transitional timing, you cut the maximum timing-analysis speeds in half. Although there are faster timing analyzers, the company claims this unit provides the fastest timing analysis in a unit that also does state analysis. As with earlier units, you can use some channels for timing analysis and others for state analysis and obtain synchronized state and timing displays. The card costs \$8800; the mainframe, \$7700. Delivery is 4 to 8 weeks, ARO. Hewlett-Packard Co, Colorado Springs, CO, (800) 752-0900.—Dan Strassberg

APD-480M021 comes with frit

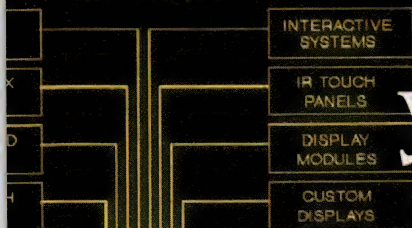


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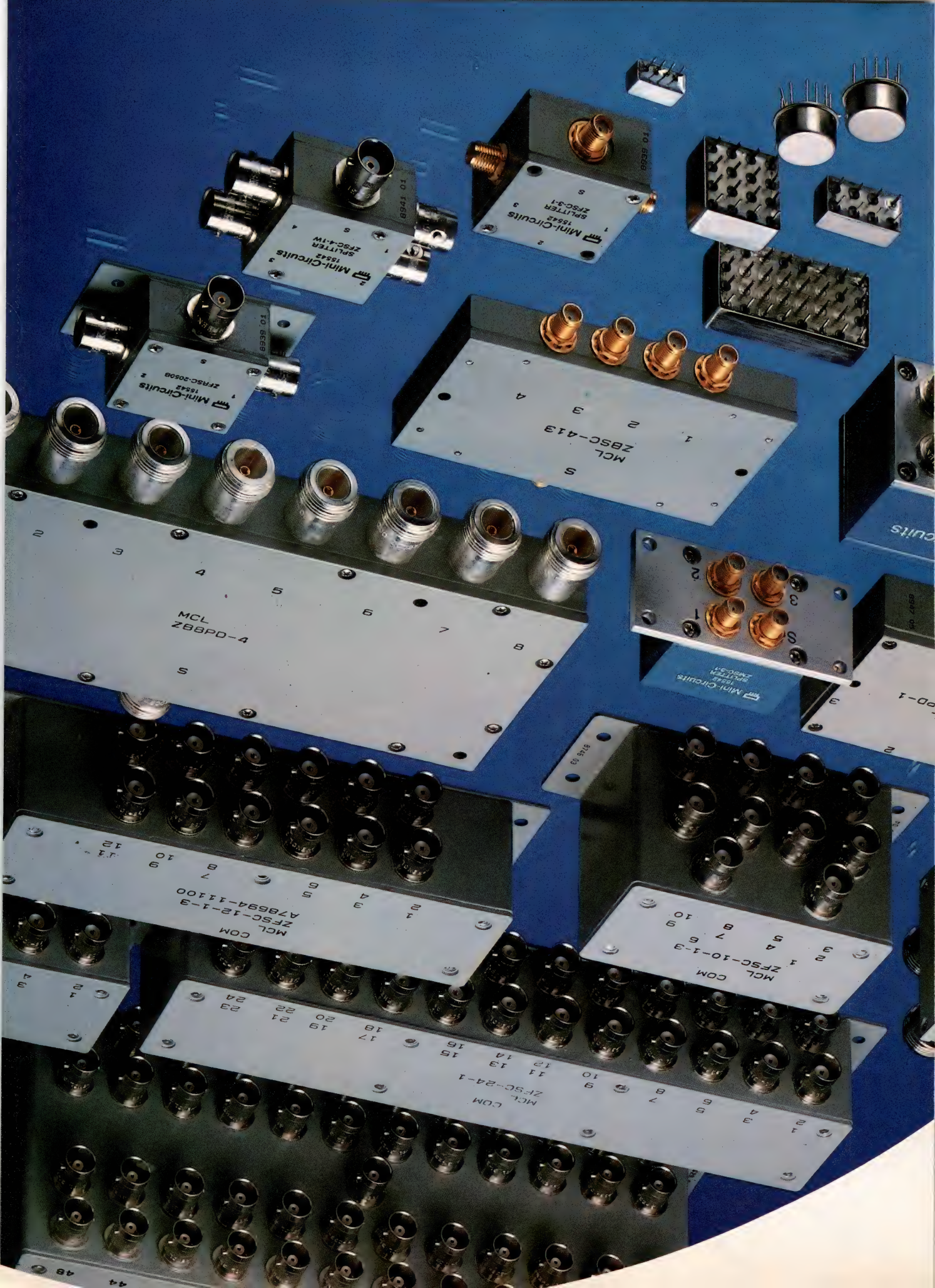
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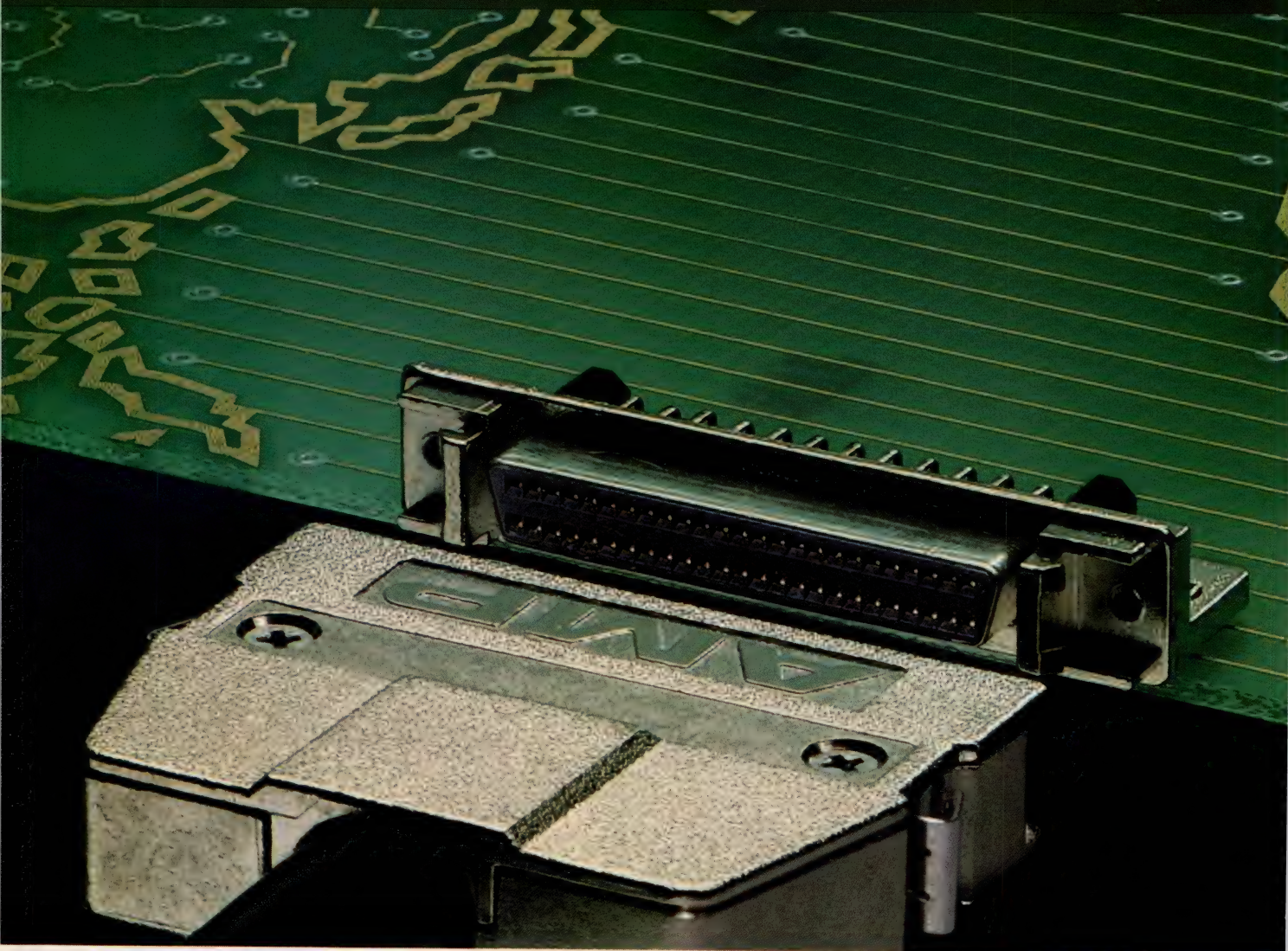
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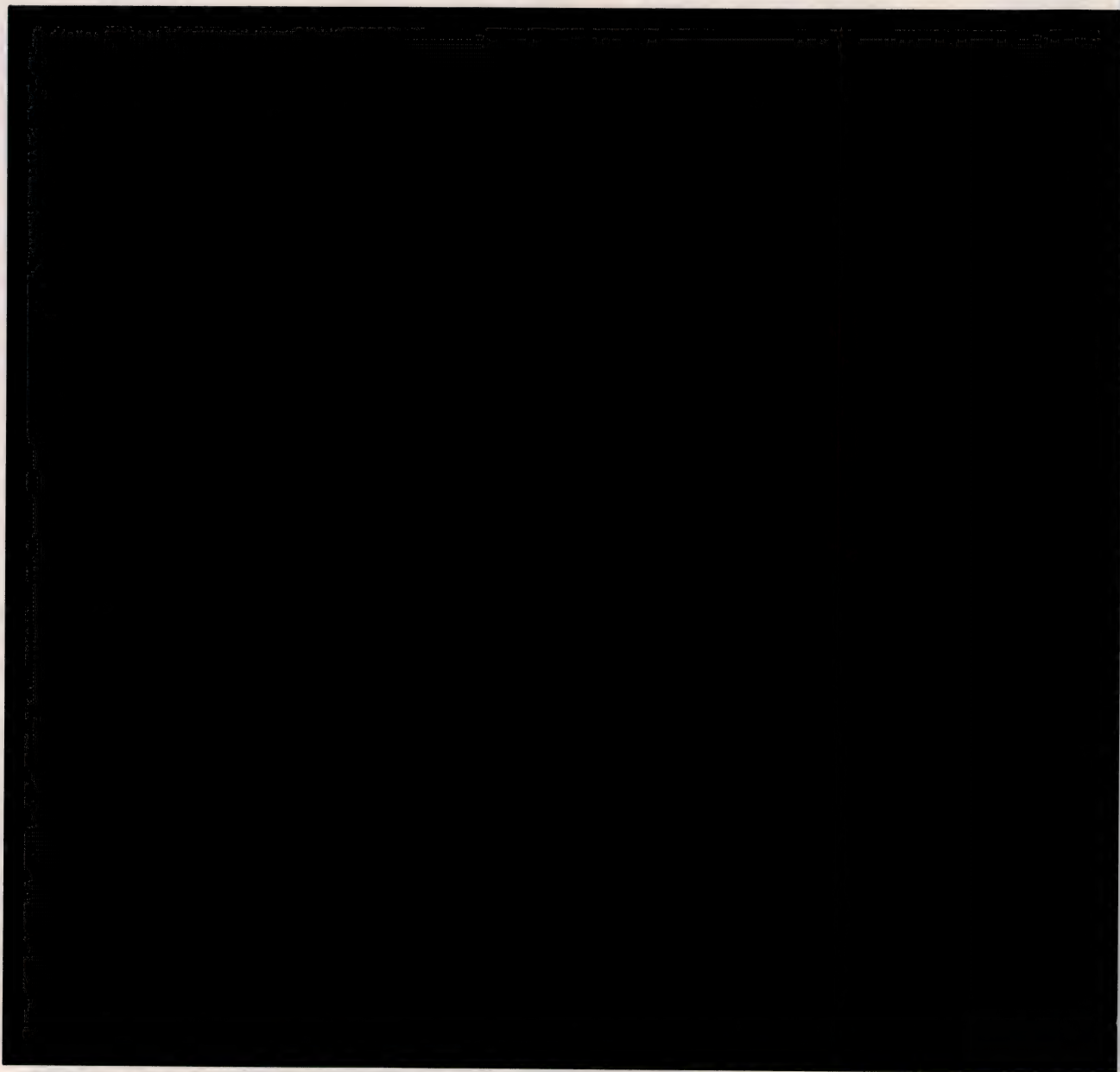
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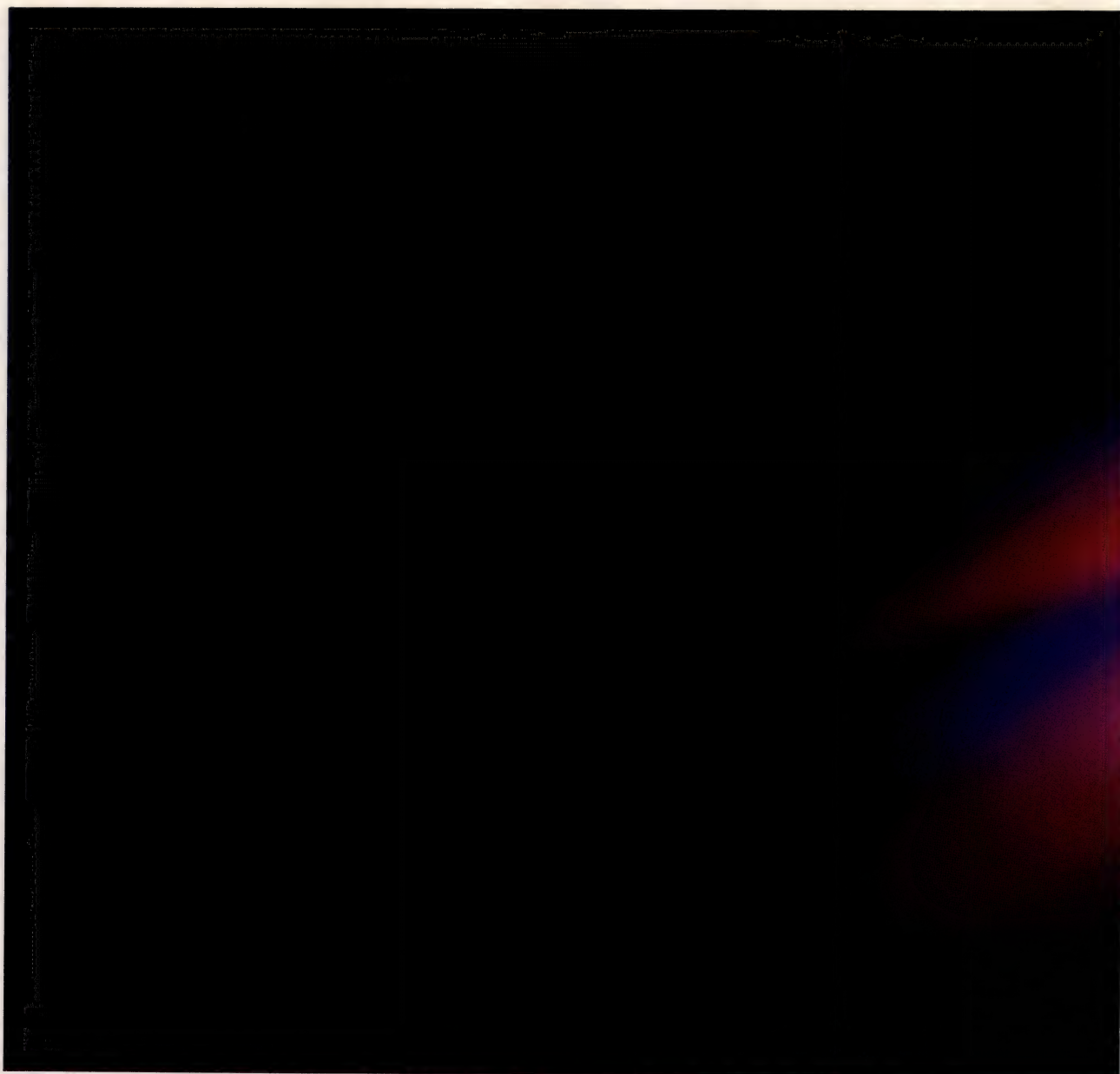
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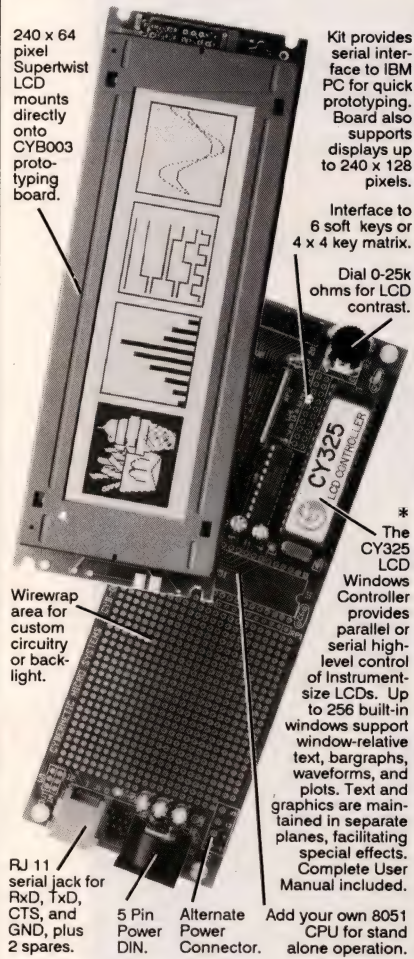
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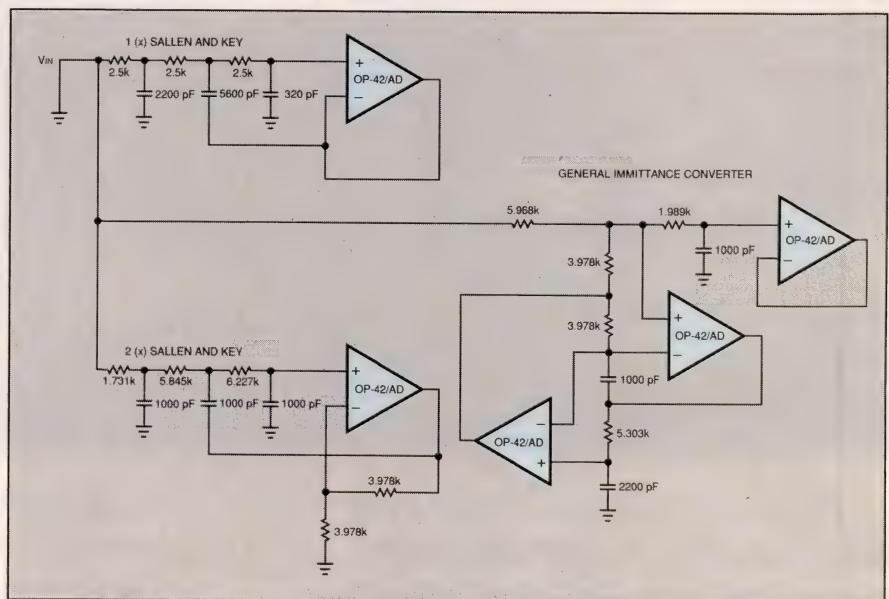
Pointing out a few differences

In the article "Vintage filter scheme yields low distortion in new audio designs" (EDN, November 7, 1991, pg 267), I'd like to point out some differences I've found.

In simulating Fig 5 (GIC and $2 \times$ Sallen and Key) circuits, the results indicate the $2 \times$ Sallen and Key filter misses the desired 40-kHz cutoff frequency by 11 kHz and has slight amplitude peaking. Although the GIC (general-immittance-converter) filter meets the desired 40-kHz cutoff without peaking, it achieves only 50-dB stopband attenuation. However, this discrepancy may be due to the OP-42 model limitations. In the simulation, I substituted OP-42 models for the OPA627 and OPA2604 because Spice models for the OPA types were not readily available.

I've found that by solving the transfer function of the third-order Sallen and Key lowpass filter with equal resistor values (the $2 \times$ Sallen and Key filter in the article has equal capacitor values), the "greater-than-unity gain to realize the component values" requirement can be eliminated. This solution realizes the unity gain $1 \times$ Sallen and Key filter illustrated in the figure below. PSpice simulations of the design indicate a cutoff frequency of 40 kHz and -80-dB stopband attenuation without any amplitude peaking. The unity gain $1 \times$ Sallen and Key filter also has lower output noise because of the lower gain.

Michael A Wyatt
Senior Engineering Fellow
Honeywell SSO
Clearwater, FL



(Author's reply: The first difference Michael Wyatt points out is in the cutoff frequency that Fig 5 [in the article] had for the Sallen and Key filter. He says that simulations of this circuit show it has a cutoff frequency of about 29 kHz, not 40 kHz as specified. Upon examining my data and doing my own Spice simulations, I find that Wyatt is correct. The reason for this and the associated peaking that the filter exhibits is that the 1.731- and 6.227-k Ω re-

sistors are reversed in position from what they should be.

I also discovered another error: the scaling factor used in the article text is incorrect. Instead of 7.23×10^4 , which is the scaling factor for a 22-kHz cutoff frequency, the correct factor should be 3.98×10^4 , which scales to a 40-kHz cutoff frequency. This error occurs only in the text; the component values in the circuit diagrams are correctly scaled.

Wyatt also points out that he has
If Goldstar insert is missing, Circle #50

overcome the "greater-than-unity gain to realize the component values" problem. He accomplishes this by solving for equal-valued resistors, rather than equal-valued capacitors. Although this approach is valid, it's much easier to find or fabricate equal-valued capacitors and 1% resistors than the other way around. Given the fact that the Sallen and Key realization suffers from much higher component value sensitivities than the GIC realization, the equal-valued-capacitor approach is the most likely one to be used in a manufacturing environment.

However, there may be realizations of a Sallen and Key filter that don't require an overall filter gain of greater than unity. Although I couldn't cover all the possibilities in my article, I picked an example which illustrated my point best: the gain-of-two Sallen and Key filter. Unity-gain active-filter realiza-

tions, whether Sallen and Key or some other topology, have always proven to have a higher THD+N than the GIC realization. One hypothesis may be that the noise gain of these circuits is higher than the GIC realization. This result may not be intuitive, because Sallen and Key filters generally have fewer op amps than GIC filters; I leave proving or disproving this hypothesis to someone who has the inclination and time. I used an example with higher gain simply to make this point clear. Wyatt's unity-gain Sallen and Key has "lower output noise because of the lower gain"; this statement is certainly true compared with the $2\times$ case, but is it lower than the GIC? I no longer have the lab or test equipment to make bench tests.

Spice models for the OPA2604 and OPA627 are available from Burr-Brown, either on disk or by

signing on to their BBS at (602) 741-3978, or from the EDN BBS (617) 558-4241 300/1200/2400/8,N,1. The 50-dB stopband attenuation that Wyatt mentions on the GIC filter is probably an artifact of his model; using the OPA2604, the same 80-dB attenuation is achievable as with the Sallen and Key topology.)

NEXT IN EDN

In EDN News Edition's February 20, 1991, issue, look for articles on the following topics:

- 3.3V ICs
- Hot products from ISSCC
- Job opportunities in Colorado, Utah, and Idaho.

Be on the lookout in April for special dual-EDN coverage of FPGAs. Technical Editor Doug Conner is in the middle of a hands-on FPGA project for the Magazine Edition; the News Edition will provide information on FPGA technologies, products, and career opportunities.

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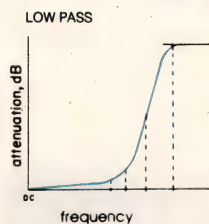


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low pass, Plug-in, dc to 1200MHz



Model No.	Passband MHz	loss < 1dB	Stopband, MHz	loss > 20dB	loss > 40dB	Model No.	Passband MHz	loss < 1dB	Stopband, MHz	loss > 20dB	loss > 40dB
PLP-5	DC-5		8-10	10-200		PLP-250	DC-225		320-400	400-1200	
PLP-10.7	DC-11		19-24	24-200		PLP-300	DC-270		410-550	550-1200	
PLP-21.4	DC-22		32-41	41-200		PLP-450	DC-400		580-750	750-1800	
PLP-30	DC-32		47-61	61-200		PLP-550	DC-520		750-920	920-2000	
PLP-50	DC-48		70-90	90-200		PLP-600	DC-680		840-1120	1120-2000	
PLP-70	DC-60		90-117	117-300		PLP-750	DC-700		1000-1300	1300-2000	
PLP-90	DC-81		121-137	167-400		PLP-800	DC-720		1080-1400	1400-2000	
PLP-100	DC-98		146-189	189-400		PLP-850	DC-760		1100-1400	1400-2000	
PLP-150	DC-140		210-300	300-600		PLP-1000	DC-900		1340-1750	1750-2000	
PLP-200	DC-190		290-390	390-800		PLP-1200	DC-1000		1620-2100	2100-2500	

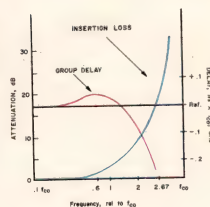
Price, (1-9 qty), all models: plug-in \$14.95, BNC \$32.95, SMA \$34.95, Type N \$35.95

Surface-mount, dc to 570MHz

SCLF-21.4	DC-22	32-41	41-200	SCLF-190	DC-190	290-390	390-800
SCLF-30	DC-30	47-61	61-200	SCLF-380	DC-380	580-750	750-1800
SCLF-45	DC-45	70-90	90-200	SCLF-420	DC-420	750-920	920-2000
SCLF-135	DC-135	210-300	300-600				

Price, (1-9 qty), all models: \$11.45

Flat Time Delay, dc to 1870MHz

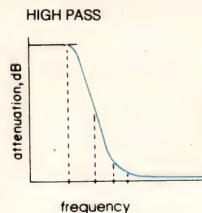


Model No.	Passband MHz	loss < 1.2dB	Stopband MHz	loss > 10dB	loss > 20dB	VSWR	Freq. Range, DC thru	0.6fco	0.6fco	Group Delay Variations, ns	Freq. Range, DC thru	2.67fco
PBLP-39	DC-23		78-117	117		1.3:1	2.3:1	0.7	4.0	5.0		
PBLP-117	DC-65		234-312	312		1.3:1	2.3:1	0.35	1.4	1.9		
PBLP-156	DC-94		312-416	416		0.3:1	1.1:1	0.3	1.1	1.5		
PBLP-200	DC-120		400-534	534		1.6:1	1.9:1	0.4	1.3	1.6		
PBLP-300	DC-180		600-801	801		1.25:1	2.2:1	0.2	0.6	0.8		
PBLP-467	DC-280		934-1246	1246		1.25:1	2.2:1	0.15	0.4	0.55		
▲BPL-933	DC-560		1866-2490	2490		1.3:1	2.2:1	0.09	0.2	0.28		
▲BPL-1870	DC-850		3740-6000	5000		1.45:1	2.9:1	0.05	0.1	0.15		

Price, (1-9 qty), all models: plug-in \$19.95, BNC \$36.95, SMA \$38.95, Type N \$39.95

NOTE: ▲ -933 and -1870 only with connectors, at additional \$2 above other connector models.

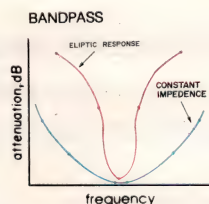
high pass, Plug-in, 27.5 to 2200MHz



Model No.	Stopband MHz	loss < 40dB	loss < 20dB	Passband MHz	loss < 1dB	VSWR	Pass-band Typ.	Model No.	Stopband MHz	loss < 40dB	loss < 20dB	Passband MHz	loss < 1dB	VSWR	Pass-band Typ.
PHP-25	DC-13	13-19	27.5-200	1.8:1		PHP-400	DC-210	210-290	395-1600	1.7:1					
PHP-50	DC-20	20-26	41-200	1.5:1		PHP-500	DC-280	280-365	500-1600	1.8:1					
PHP-100	DC-40	40-55	90-400	1.8:1		PHP-600	DC-350	350-440	600-1600	2.0:1					
PHP-150	DC-70	70-95	133-600	1.8:1		PHP-700	DC-400	400-520	700-1800	1.6:1					
PHP-175	DC-70	70-105	160-800	1.5:1		PHP-800	DC-445	445-570	780-2000	2.1:1					
PHP-200	DC-90	90-116	185-800	1.6:1		PHP-900	DC-520	520-660	910-2100	1.8:1					
PHP-250	DC-100	100-150	225-1200	1.3:1		PHP-1000	DC-550	550-720	1000-2200	1.9:1					
PHP-300	DC-145	145-170	290-1200	1.7:1											

Price, (1-9 qty), all models: plug-in \$14.95, BNC \$36.95, SMA \$38.95, Type N \$39.95

bandpass, Elliptic Response, 10.7 to 70MHz



Model No.	Center Freq. (MHz)	Passband I.L. 1.5 dB Max. (MHz)	3 dB Bandwidth Typ. (MHz)	Stopbands I.L. > 20dB at MHz	I.L. > 35dB at MHz	Model No.	Center Freq. MHz	Passband MHz loss < 1dB	Stopband loss > 20dB at MHz	VSWR 1.3:1 Total Band MHz
PBP-10.7	10.7	9.6-11.5	8.9-12.7	7.5 & 15	0.6 & 50-1000	PIF-21.4	21.4	18-25	1.3 & 150	DC-220
PBP-21.4	21.4	19.2-23.6	17.9-25.3	15.5 & 29	3.0 & 80-1000	PIF-30	30	25-35	1.9 & 210	DC-330
PBP-30	30.0	27.0-33.0	25-35	22 & 40	3.2 & 99-1000	PIF-40	42	35-49	2.6 & 300	DC-400
PBP-60	60.0	55.0-67.0	49.5-70.5	44 & 79	4.6 & 190-1000	PIF-50	50	41-58	3.1 & 350	DC-440
PBP-70	70.0	63.0-77.0	68.0-82.0	51 & 94	6.0 & 193-1000	PIF-60	60	50-70	3.8 & 400	DC-500
						PIF-70	70	58-82	4.4 & 490	DC-550

Price, (1-9 qty), all models: plug-in \$18.95, BNC \$40.95, SMA \$42.95, Type N \$43.95

Constant Impedance, 21.4 to 70MHz

Model No.	Center Freq. MHz	Passband MHz loss < 1dB	Stopband loss > 20dB at MHz	VSWR 1.3:1 Total Band MHz
PIF-21.4	21.4	18-25	1.3 & 150	DC-220
PIF-30	30	25-35	1.9 & 210	DC-330
PIF-40	42	35-49	2.6 & 300	DC-400
PIF-50	50	41-58	3.1 & 350	DC-440
PIF-60	60	50-70	3.8 & 400	DC-500
PIF-70	70	58-82	4.4 & 490	DC-550

Price, (1-9 qty), all models: plug-in \$14.95, BNC \$36.95, SMA \$38.95, Type N \$39.95

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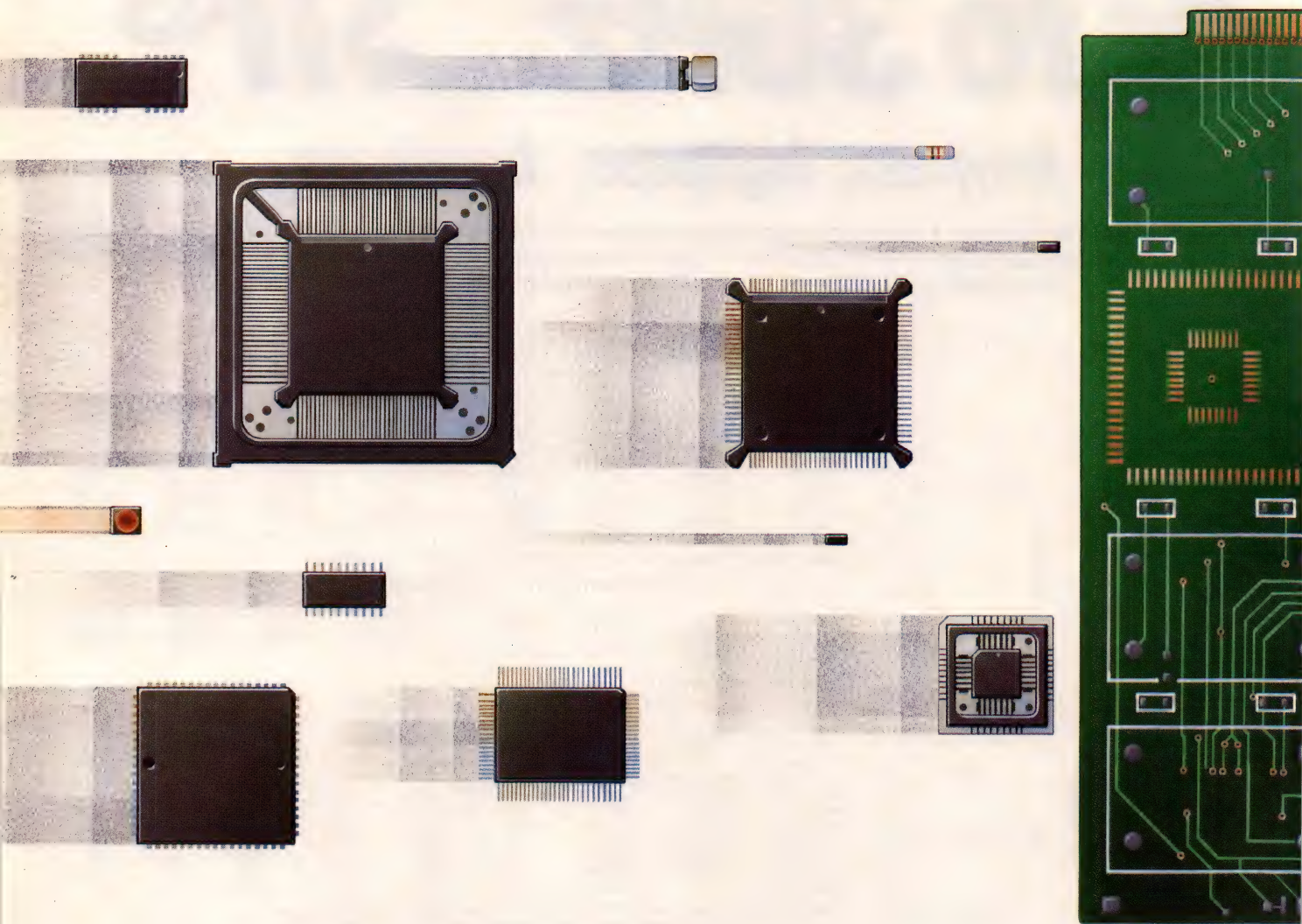
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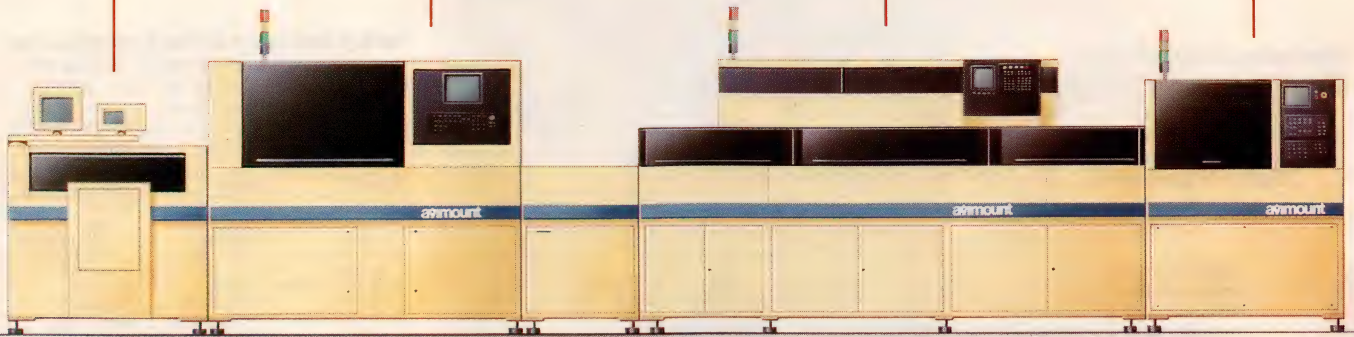
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Sparks fly as insulation fails

I have used the ICL7107 3½-digit integrating decimal-output ADC IC for voltage measurement in a circuit that measures insulating materials' dc leakage current, as **Fig 1** shows. The circuit works well as long as the insulator under test does not break down. But if a spark is generated across points A and B because the insulation fails when subjected to high voltage, the IC gets damaged, even though the current through the In High and In Low terminals remains well within the maximum permissible limit specified by the manufacturer.

Any capacitor or clamping diode I connect across points C and D does not help. However, if I use the **Fig 2** circuit, which has a 10-MΩ resistor (R_1) connected between In Low and the sparking points A and B, the IC is not damaged when the insulation fails. This result indicates that the damage in the earlier case may be due to static discharge, but exactly how it is causing damage is not very clear to me.

Could you comment on why the 7107 fails and suggest some solution to avoid this damage? In some other similar application, I may not be able to use a high-value resistor between one of the IC's input terminals and the sparking points.

Sanjay R Chendvankar
Tata Institute of Fundamental Research
Bombay, India

Peter Sharrock of Maxim Integrated products replies: Much of the circuitry is not shown in your figures, so there could be several failure modes that I haven't identified. However, the solution outlined below should give protection in all the configurations I can think of.

The circuit of **Fig 1** has parasitic capacitance between the 7107 circuitry and ground. When the insulation of the device under test breaks down, the voltage applied to In Low falls very rapidly. The parasitic capacitance prevents all of the ADC circuitry from instantly falling in voltage, so the In Low pin sees a momentary multikilovolt insult. This is the most likely cause of failure.

The circuit of **Fig 2** has a 10-MΩ resistor between the device under test and the 7107. When the insulation fails, any sudden change in the voltage across the device under test is transmitted to the ADC through the RC network comprising R_1 and the circuit parasitics. The In Low pin of the 7107 does not get exposed to such high voltages, so the part does not fail.

Another equally valid way of protecting the 7107 is to add an extra protection resistor between node D and the In Low pin. This resistor gives good protection in the circuits of both **Fig 1** and **Fig 2**. You could use a value of 10 MΩ to match the 10-MΩ resistor in series with the In High pin. Alternatively, you could try two 4.7-MΩ resistors.

Finding yourself with satellites

Do you know where I can find information regarding the Global Positioning System (GPS)? I've heard a lot about it, and I would like to know what is needed to build a GPS receiver that would tell me exactly where on Earth I am. Up to now, I haven't had any luck finding information or specs on the system.

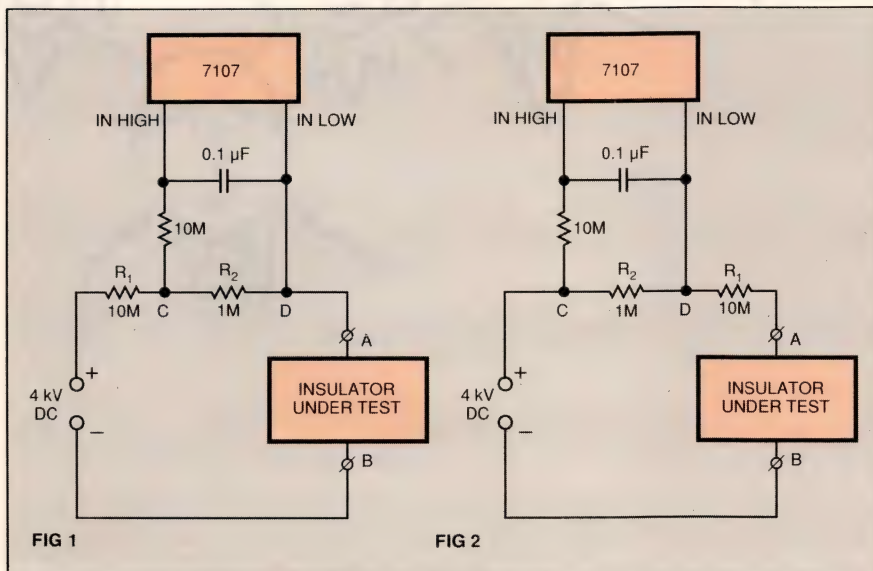
Javier Perez
Boston, MA

Try the Electronic Proving Ground GPS Range Instrumentation System (EGRIS) BBS at (602) 538-3818, N,8,1 for 300- to 2400-bps modems, or (602) 533-8087 for 9600-bps modems. Two other GPS bulletin-board systems are the US Coast Guard's GPS Information Center at (703) 866-3890, N,8,1 for 300- to 2400-bps modems, (703) 866-3894 for 9600-bps modems; and the US Air Force's Holloman GPS BBS at (505) 349-1525 for all modems. These BBSs provide information about constellation status, almanac data, electronic mail, downloadable files, and user advisories.

Also try *GPS World* magazine published by Astor Publishing Co, Box 10460, Eugene, OR 97440 USA.

Yet more information about the GPS is available from the Institute of Navigation, 815 15th St, Suite 832, Washington, DC 20005, USA. Phone (202) 783-4121. You can also purchase a 3-volume set of books, *Global Positioning System*, Volumes 1, 2, and 3, all for \$50, from Navtech Books, 2775 S Quincy St, Suite 610, Arlington, VA 22206, USA. Phone (800) 628-0885; (703) 931-0500. FAX (703) 931-0503. The books, which you can also buy separately, provide all of the signal protocols and frequencies that you would need to pick up and decipher GPS information. The books are called "The three little red books" by some GPS users. Navtech Seminars Inc offers courses, seminars, and tutorials about the GPS. Its address and phone are the same as Navtech Books. Have fun.

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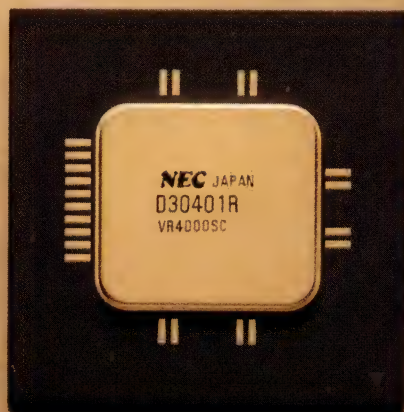




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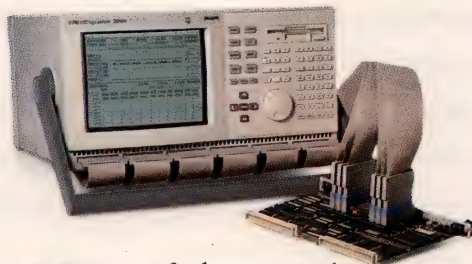
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Where have all the investments gone?



Like most engineers, I took a course in economics when I was an undergraduate. And like most engineers, I'm no expert on economics. But like most people who work in the private sector—and in the US, that's most people—economics has a profound influence on my life.

Most of the time, I don't think about economics a whole lot. But at times like this, with the US economy—and probably the world economy—in dire straits, I think about economics more than usual. Sure, a lot of people have their favorite scapegoats for the current economic malaise: Democrats like to blame George Bush and Ronald Reagan. Republicans like to blame the Democrat-controlled Congress. People who don't identify strongly with either party like to blame the bureaucrats in Washington, the directors of failed S&Ls, the Tax Reform Act of 1986, the budget deficits, the national debt, leveraged buyouts, corporate and private debt, widespread greed, the low savings rate, the reluctance of consumers to spend, bank regulators, bank loan officers, and any number of other vaguely defined entities.

At the moment, I'm not blaming anybody or anything. I do think, though, that it's time we get answers to some vexing questions—not for the purpose of assessing blame, but in the hope of learning from our mistakes so we can avoid repeating them.

I want to know why, with all the profitable opportunities for investment in this country during the decade just ended, so much investment money went into commercial real estate—for exam-

ple, to build office buildings that are now sitting empty. In fact, some of these buildings cost so much to leave unoccupied that their owners are razing them.

America's productive capacity is aging and outmoded. Investment in plants and equipment could have greatly improved our competitive position in the world. Investments in R&D could have produced new products and fueled demand. Increased demand would have created jobs and generated profits, which would have provided more investment money and tax revenues. The tax revenues, coupled with even a modest "peace dividend" could have made it possible to rebuild our crumbling infrastructure—things like bridges and roads. Improvements here would have helped to slow or halt the erosion of our competitive position.

So what went wrong? Why are we left with millions and millions of square feet of commercial real estate that, with some luck, we might actually occupy by the turn of the century? And why are our plants and production equipment still outmoded, our infrastructure still crumbling, and the money to be spent on developing new products still inadequate? As an engineer, you're probably just as curious as I am. As an American, you should be curious. And as an engineer with only minimal training in economics, you probably don't have all the answers or even most of them. But if you have some ideas, we'd like to hear them. Please write to us. Use the mail or the /soapbox Special Interest Group on the EDN BBS. We'll publish your responses.

Dan Strassberg
Technical Editor



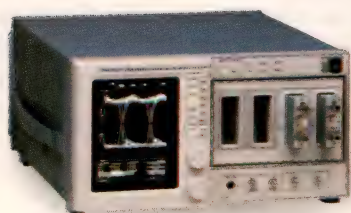
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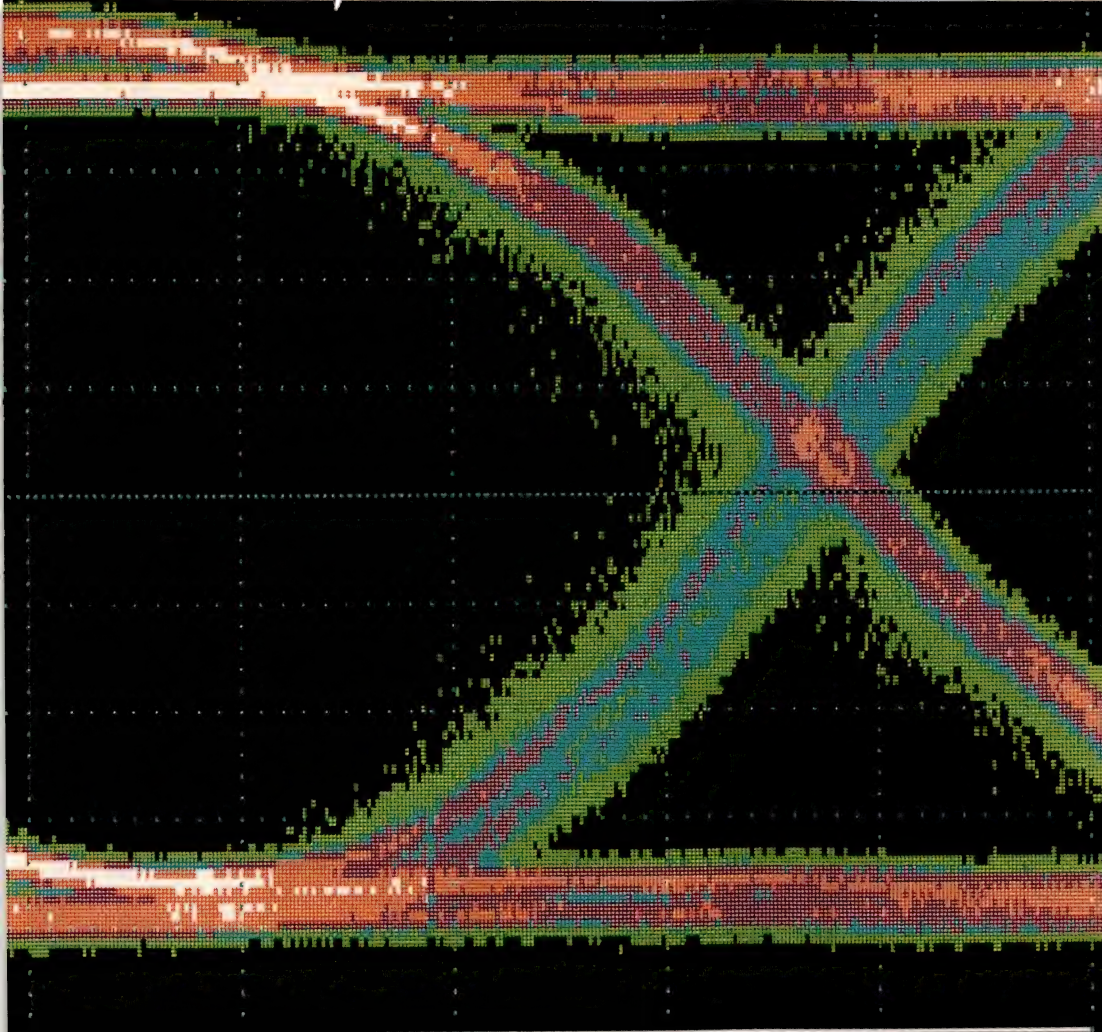


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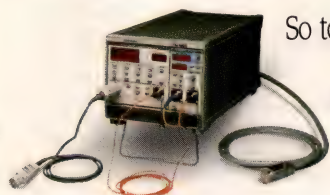
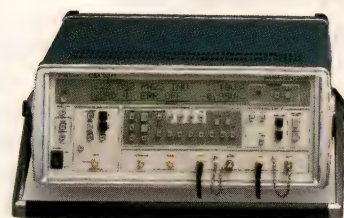


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European manufacturing contractors encourage close relationships

BRIAN KERRIDGE, Technical Editor



Interests of European contract manufacturers extend beyond pc-board assembly to include component procurement, test, final assembly, and even customer service. Overall, they want to contribute to the success of your product by becoming part of the business.

Manufacturing products in Europe is one way for companies to avoid import tariffs, and is thus a motivating factor for using a European contract manufacturer. For non-EC (European Community) countries, Europe's harmonization program offers further inducement, as since 1988, there has been no trade barriers among member states to products manufactured within the community.

More than avoiding tariffs, contract manufacturers say the main demand for their services follows when a company realizes it has to design in surface-mount-technology (SMT) components. The learning curve and capital cost of SMT is enough for many companies to halt in-house manufacture and look for an outside facility.

But using a contract manufacturer does not mean simply unshouldering all responsibility for getting your design produced. You should not expect to avoid being drawn into production issues as your product passes through the contractor's process.

To obtain the best service from a contractor, you need to re-create with that contractor the relationship you presently have with an in-house production facility. It's well understood that production inputs to the early phases of a design ensure a smooth passage for the product in the production phase. Equally beneficial is a designer's involvement with early production runs.

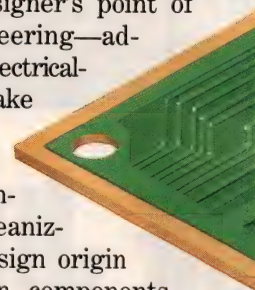
Contractors are keen to work with you in this way and are at pains to express the virtue of this approach. Without this product engineering, you'll be missing out on a wealth of experience that can make your design cheaper,

more producible, and therefore more competitive. Take your contractor's advice on board, and the likelihood is that your customer will end up with an all-around better product.

Contract manufacturers are scattered throughout Europe, but the major concentration is in France and the United Kingdom. In these two countries, professional associations represent the interests of about 50 member companies. Turnovers of the companies range from 1 to over 100 million dollars. Not every company belongs to an association either—in France alone, estimates suggest approximately 1000 companies exist.

The range of services available from contractors doesn't stop at manufacturing. Procurement of parts and test facilities are also standard offerings. But the key service from a designer's point of view is product engineering—adjusting the design both electrically and mechanically to make it more producible.

An additional and valuable service that contractors offer is "Europeanizing" a product if its design origin is outside the EC. Often, components specified in a parts list are not available locally, and equivalent types need to be found. As a bonus, if a contractor can build-in enough local cost content to your product, it may qualify as originating in the EC. In this case, your product would be exempt from import tariffs if you export it to countries that have a preference agreement with the EC, such as EFTA (European Free Trade Association) countries and Israel. Rules for determining local content vary, but



generally for electronic products there needs to be a local cost content of greater than 60% of the product's ex-works price. The EC member country's customs offices publish details (Refs 1 and 2).

CEL-CEP (Jouy en Josas, France) is typical of many European contractors in its ability to offer a turn-key manufacturing service. This company can design your pc-boards, subassemblies, and product enclosure. It will product-engineer your circuit design, and purchase all components and parts. Following manufacture, the company can perform in-circuit and functional test of the individual boards. It can assemble to final product level, carry out a burn-in operation, and ship direct to your customer or distributor if need be. Even maintenance and customer-service facilities are available.

Dr Daniel Thauvin, CEL-CEP's sales manager and vice president of a French contractors' professional association, says that although contractors are flexible enough to work on one or all phases of a manufacturing process, they have a preferred way of going about things.

In order for a contractor to do an effective job, the designer needs to provide more than just schematics and parts lists. CEL-CEP likes to have a functional description of the product, with quality and price objectives firmly stated at the outset. Naturally, the designer needs to specify clearly restrictions on choice of components, assembly parameters, and test methods. If a prototype sample is available, that's also useful.

One thing Thauvin emphasizes is the importance of setting up efficient communication between

customer and contractor. He suggests both companies nominate one person to transfer information back and forth. Or, on larger projects, for companies to provide a list of specialist staff to answer the range of questions that crop up.

Communication is also an issue to consider when you have no base in the country where you propose to have your product produced. Thauvin explains that when a contractor simply wants large volume production of an existing fully designed product, or there is limited product Europeanizing involved, then a local presence is not essential. But where you intend to use the full range of design and development services, a local customer base is a prerequisite. CEL-CEP does not accept contracts without that arrangement.

Thauvin adds that while open relationships with customers are beneficial, it should be clear what each partner expects of the other.

He cautions that at all times, the technical and functional responsibility for the product remains

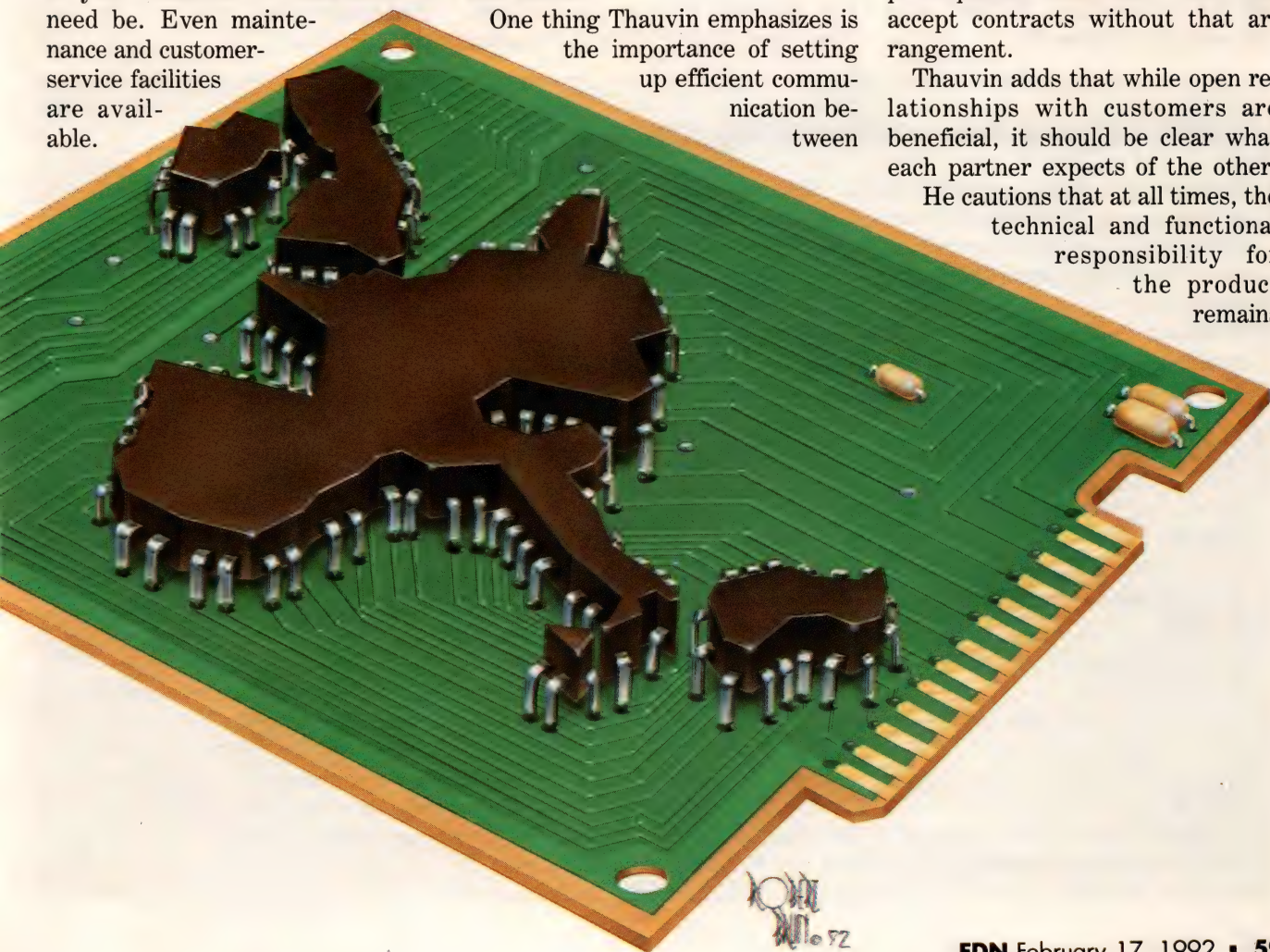


Illustration by Robert Brun

EUROPEAN CONTRACT MANUFACTURING

with the designer. In fact, the designer should retain essential product knowledge in order to avoid the possibility of the contractor's suddenly appearing with a competitive product.

Manufacturers need flexibility

It's not only large contractors that stress the importance of working in concert with clients. Gerald Willard, technical director of Xpert Systems (Mitcham, UK), and one of many smaller contractors, emphasizes the same point. Xpert prefers you to provide a circuit diagram and a generic components list as a starting point for its service. The company likes to do the pc-board layout and select individual component types for your design. Willard argues this procedure allows flexibility to optimize a product for manufacture. Willard cites the example where for an optimal

Getting the best from contract manufacturers

Establish liaisons with your contract manufacturer as you would with your own production facility:

- ideally involve contractor with your design from the outset
- involve contractor in all mechanical issues
- encourage contractor's advice on changes to type and value of components
- let your contractor lay out the pc board
- use your contractor to "Europeanize" your design
- use your contractor's test facilities.

pc-board layout, a capacitor may need to bridge five pc-board tracks. If you've already precisely specified the component as a chip capacitor, that freedom is lost.

In the same way, Willard says adjusting component type or voltage rating to match what Xpert currently uses takes advantage of better quantity pricing on the part. Also, this adjustment may avoid an

extra reel on the automatic insertion handler, or avoid changing reels more often.

Willard makes the point that except for eurocards, there are few standards for pc-board size. He says if you know in advance the fixing requirements of insertion, soldering, and test jigs that the contractor uses, you can lay out the pc board accordingly and

Finding a European manufacturing contractor

You can easily locate potential contract manufacturers in France and the UK through trade associations. Both associations publish brochures that list and profile members. The UK association brochure generously lists many nonmembers.

In France, contact Jaques Bayle-Ottenheim
**Syndicat National des Entreprises de
 Sous-Traitance Electronique (SNESE)**

11 Rue Hamelin
 75783 Paris, Cedex 16, France
 (1) 45057053
 FAX (1) 45530393

Circle No. 711

In UK, contact Derek Duffert

**Association of Contract Electronic Manufacturers
 (ACEM)**

Ramano House
 399-401 Strand
 London WC2R 0LT, UK
 (71) 497-2311
 FAX (71) 497-2335

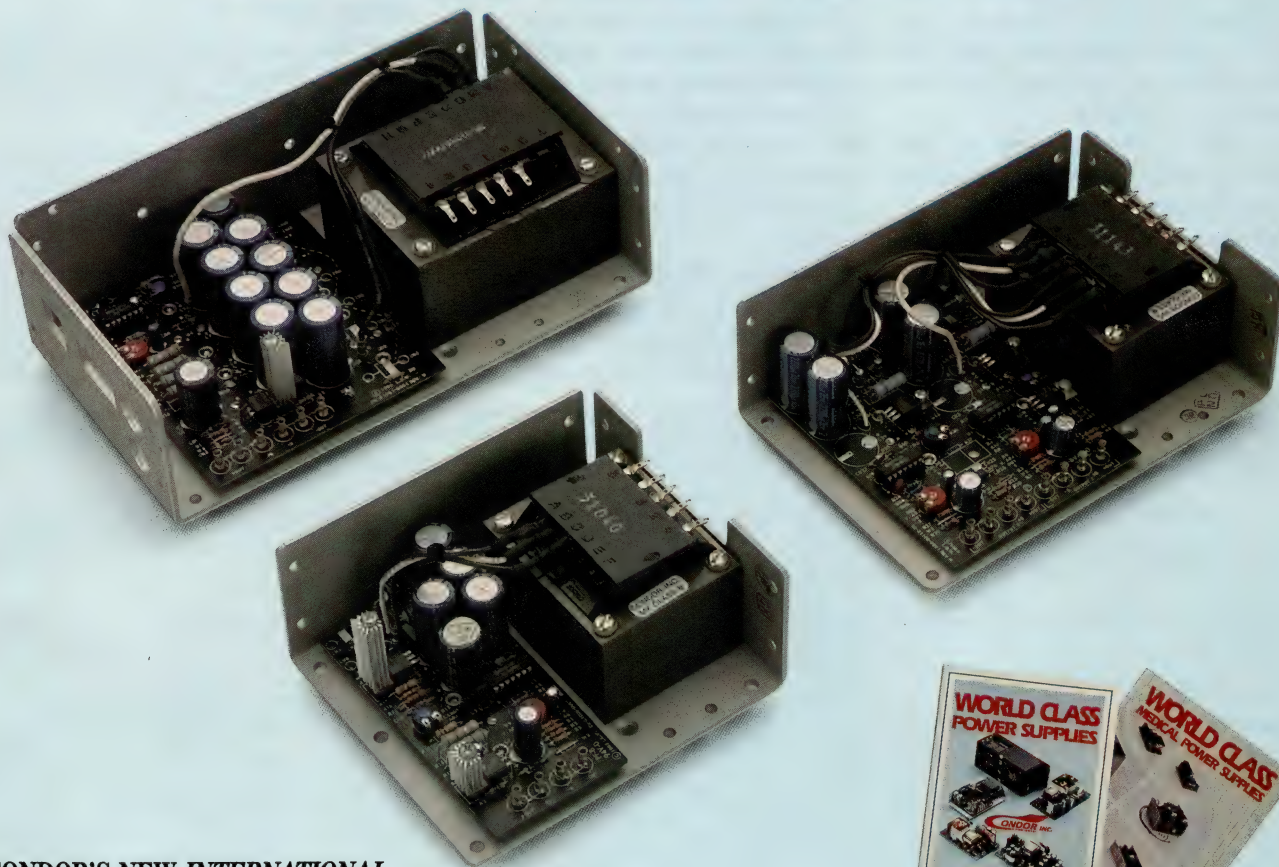
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ACEM plans a major presence at the Nepcon Electronics show set for March 24 to 26 at the National

Exhibition Centre, Birmingham, UK. A contract manufacturing center at the show will provide a dedicated forum for companies to promote their services. For more details, contact Peter Telford in the UK, phone (799) 26699, FAX (799) 26088.

It's quite likely that special components in your design will not be readily available for your contractor to procure locally. In this case, if you are outside the EC, import tariffs apply when you free issue such parts to your contractor. There are as many different tariff values as there are component types, but generally the figure for electronic parts falls in the range of 5 to 14%. Needless to say, parts such as ASICs are at the high end of that range. On top of this figure, you need to add carriage, insurance, and freight charges, and the cumulative figure for these items is further subject to value added tax (17.5% in the UK). The basis for import-tariff figures is a mystery. For example, on finished products such as spectrum analyzers and oscilloscopes the figure is 11%, but for DMMs it's 10.6%. Whatever figure applies, the information is readily available from customs offices in all European cities and ports. (In the UK, at Her Majesty's Customs and Excise offices).

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EUROPEAN CONTRACT MANUFACTURING

avoid tooling costs for special jigs.

In addition, where you use SMT components, Willard says it's important to consider component placement in relation to the direction of flow during wave soldering. Running IC pins in line with the wave direction, and avoiding component shadowing (placing low-profile parts behind high parts), are typical small details that can have a big effect on how easy your assembly is to produce.

At ACW Technology in Petersfield UK, Operations Director Chris Knowles says with disappointment that only one in ten first-time customers shows an interest in forming a long-term working relationship. He says the situation is improving, but the majority still

turn up with a finished pc-board assembly and simply request the best price and delivery. Although ACW, like most contractors, is flexible enough to work this way, Knowles feels that the product suffers by this nonpreferred approach.

Knowles says engineers, in general, do not appreciate the benefits of designing for manufacture. He says any design can benefit from a manufacturer's inputs, and manufacturers are often in the best position to decide such aspects as component types, pc-board construction (single, double, or multilayer), and layout.

Knowles advises that when you search for a contract manufacturer to work with, look for a contractor with ideally 10, and no more than

20, main customers. When a contractor tries to support more customers than this level, Knowles believes it's not possible to give adequate attention to the range and extent of design and manufacturing problems that inevitably arise. **EDN**

References

1. Her Majesty's Customs and Excise Offices. European Community Preferences: Export Procedures, Notice 827. August, 1990, UK.

2. Her Majesty's Customs and Excise Offices. EC Export Preferences: Rules of Origin, Notice 828. March, 1991, UK.

Article Interest Quotient (Circle One)

High 482 Medium 483 Low 484

For more information . . .

For more information on contract manufacturing in Europe, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you saw their services mentioned in EDN.

AB Electronic Products

Rogerstone
Newport NP1 9VA, UK
(633) 892345
FAX (633) 895755

Circle No. 713

ACW Technology

Hylton Rd
Petersfield GU32 2JY, UK
(730) 66311
FAX (730) 66045
Chris Knowles

Circle No. 714

ARS Industries

Z I Arc-Isère
73220 Aiguebelle, France
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FAX (7936) 4184
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FAX (1) 3465-9060
Anne Le Sayec

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FAX (6151) 141929
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GSPK (Electronics)

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Keith Warner

Circle No. 720

Hughes Microelectronics

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Glenrothes KY7 5PY, UK
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Morari

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94702 Maisons-Alfort, France
(1) 4368-5025
FAX (1) 4375-0775

Circle No. 723

MP Diffusion

Avenue de l'Europe, BP38
71202 Le Creusot, France
8556-2005
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9971-1867
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System Contact

13 Rue des Frères Lumière, BP24
67038 Strasbourg, France
8878-2089

FAX 8877-0411

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Xpert Circuit Assemblies

c/o Philips Components Mitcham
New Rd, Mitcham CR4 4XY, UK
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FAX (81) 687-1927
Gerald Willard

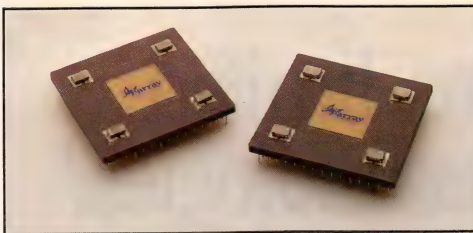
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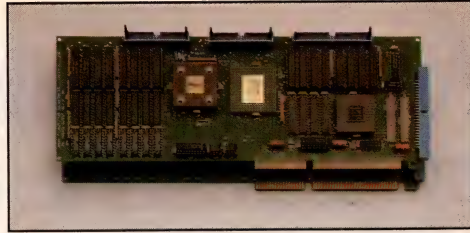


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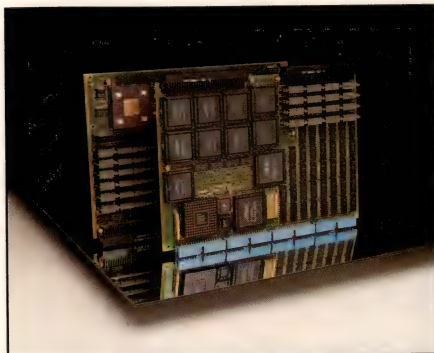
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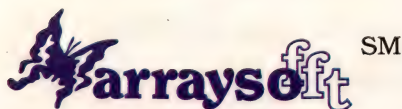
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CIRCLE NO. 137



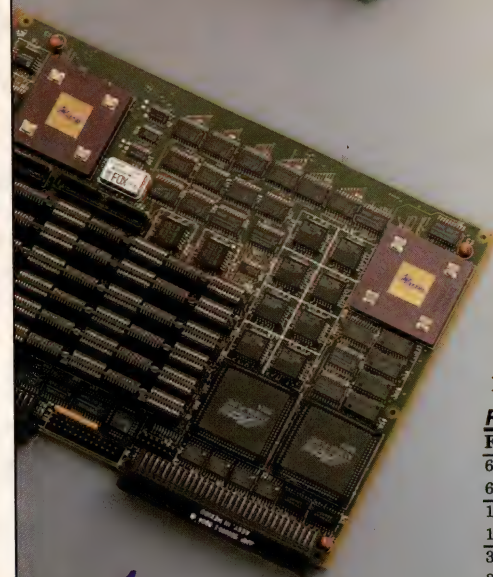
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PC-AT DSP 1K FFT/126 μ s

DSP engine for the 16-bit PC-AT Industry Standard Architecture (ISA) bus

Performance Benchmarks

FFT size	a66550/32K @25MHz
64 Real	7.2 μ s
64 Complex	10.9 μ s
1024 Real	125.9 μ s
1024 Complex	209.9 μ s
32K Real	5.90 ms
32K Complex	10.49 ms
64K Real	15.73 ms
64K Complex	N/A



VME DSP 1K FFT/79.6 μ s

DSP engine for industry-standard VMEbus

Performance Benchmarks

FFT size	a66540A @40MHz	a66540A Cascade Sys.
64 Real	5.1 μ s	2.9 μ s
64 Complex	5.0 μ s	3.7 μ s
1024 Real	79.6 μ s	29.6 μ s
1024 Complex	132.7 μ s	59.1 μ s
32K Real	3.69 ms	0.91 ms
32K Complex	6.56 ms	1.82 ms
64K Real	7.37 ms	1.82 ms
64K Complex	13.11 ms	3.64 ms

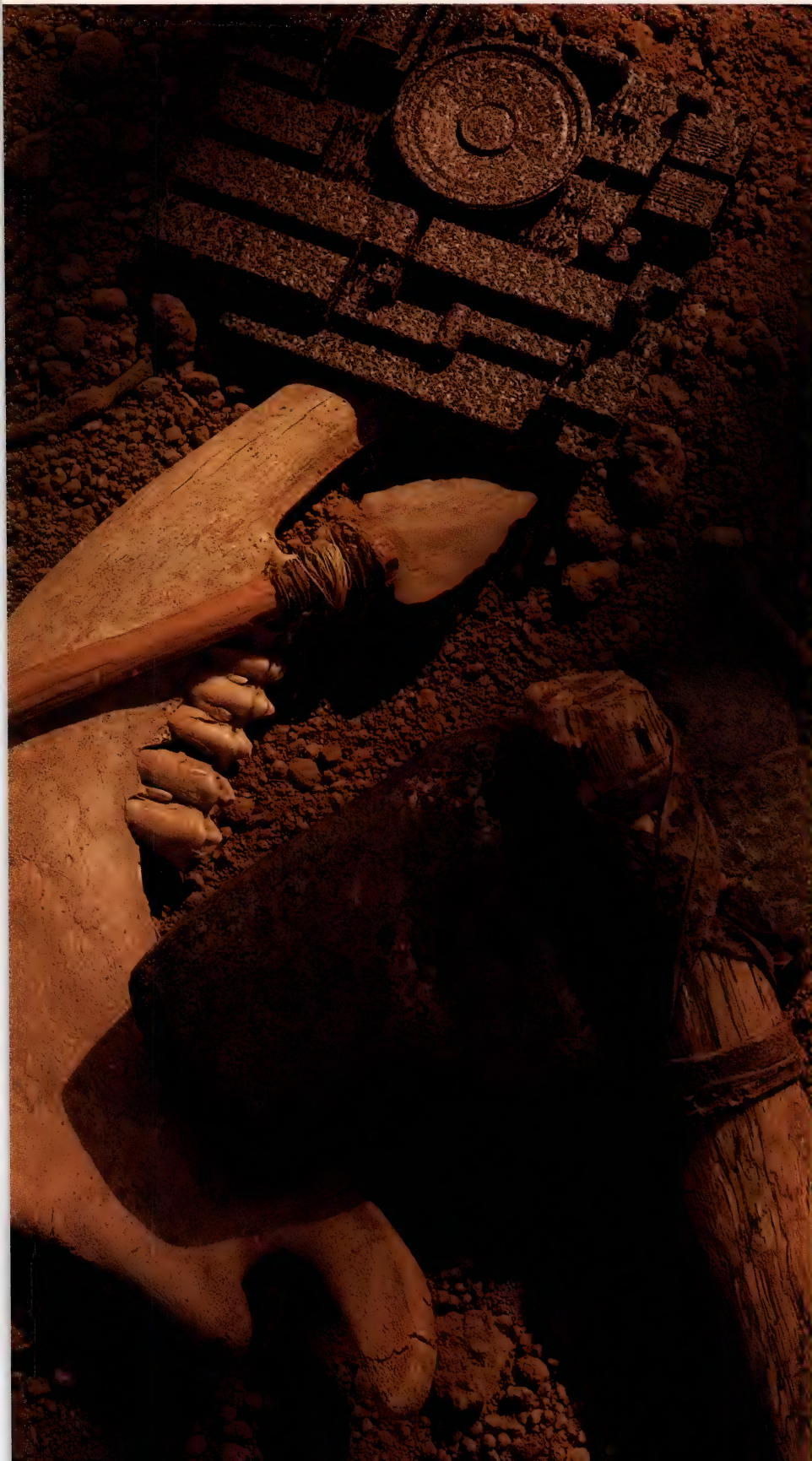


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Parameter analyzers give you a closer look at dc-circuit performance

DOUG CONNER, Technical Editor



Parameter analyzers based on source-measure units provide flexible and sensitive instruments for characterizing dc circuits.

When your circuit designs run up against data-book specification limits, it may be time to take a close look at the actual device performance. For digital devices, you often are interested in AC parameters, so you reach for pulse generators, time-interval analyzers, and oscilloscopes to get your answers. For analog components, and even occasionally for digital, you need dc parameter analyzers that can test the performance limits of the components.

Semiconductor device manufacturers perform extensive dc characterization of their devices, and some of that information ends up in the device data sheets. If you need more information, you can try to get it from the device manufacturer or you can make measurements yourself using a parameter analyzer.

Parameter analyzers are also useful for collecting data on real devices for use in creating accurate component simulations (Ref 1). In addition to generating data for simulation, you can test several devices to get a measure of the performance variation among components of the same type. Using the device-variation information, you can predict performance variations in your end product.

Any time you measure device characteristics

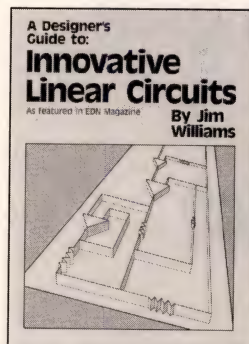
that are unspecified by the device manufacturer, you must be careful how you use the information. Unspecified characteristics can vary significantly among different lots of parts. If you need a continuing supply of devices with certain characteristics not specified on the device data sheet, you need to work out special arrangements with the device manufacturer.

Parameter analyzers used to measure dc characteristics are typically of two types. The first is the curve tracer, which can test specific characteristics of various semiconductor devices. The sec-



Source-measure units connected to a computer for control and display let you create a parameter analyzer or test system to suit varied requirements. The model 238 from Keithley Instruments offers current to 1A.

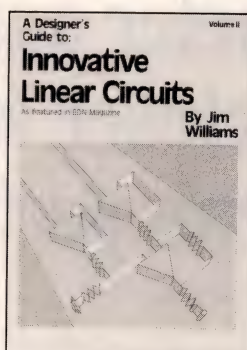
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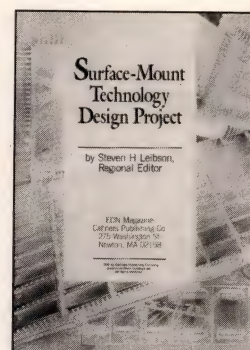


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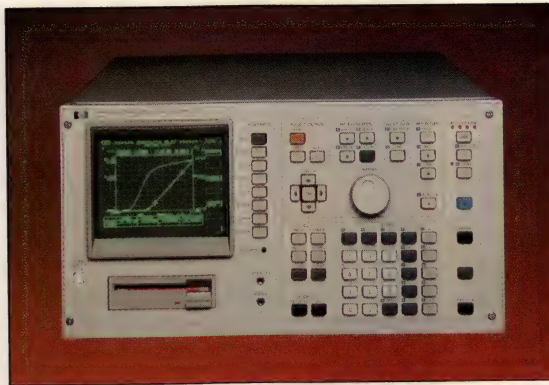
and is a more general-purpose instrument typically built around a source-measure unit (SMU). Four instruments go into an SMU: a voltage source, a voltmeter, a current source, and a current meter. An SMU either sources voltage and measures current or sources current and measures voltage.

For testing a component as simple as a diode, you need only one SMU. A transistor typically requires three SMUs, and an op amp might use four.

Although you could make the same measurements using separate voltage and current meters with voltage and current sources, using SMUs has some advantages. Because an SMU is capable of performing any source or measure function, you can have a general-purpose test setup that tests any type of device without your having to reconfigure the setup. Having all the instruments integrated into one means you only have to deal with one set of accuracy specifications. And a single instrument is often easier to program for automated testing.

Keeping safe compliance limits

Whenever you use a current or voltage source, it will have some compliance range over which it can source current or voltage. The compliance limits should be adjustable (they are on SMUs) to pre-



Comprising four SMUs integrated into a benchtop instrument, the HP4145B provides programmable data acquisition and display. You can store test setups and data, using the floppy-disk drive, or control the instrument through an IEEE-488 bus interface.

vent damaging the circuit you are testing.

For example, if you are using an SMU (or any current source) to source current to a circuit, the source will increase the voltage until either the programmed current flows into the device terminal or the current source reaches its compliance limit. While performing a test, you can typically set compliance limits to safe values for the device, then vary the force value.

Similarly, an SMU operating as a voltage source will increase current until it reaches its compliance limit or the programmed voltage level.

Only the instrument operator can set limits to protect a device under test from voltages or currents that will damage it. An SMU, though, at least has some built-in protection from self-damaging situations.

For example, if you are measuring the high-voltage breakdown of

a device, you force an increasing voltage until the current flow indicates breakdown. If you've neglected to set a safe compliance level on the current, then when breakdown occurs, the current may destroy the device under test. If you are using a separate voltage source and current meter, it's also possible you'll overload the current meter, damaging it or blowing a fuse. SMUs have a higher degree of built-in self protection because the integrated instrument always knows what levels it is sourcing and measuring and what its compliance limits are.

SMUs are able to make extremely sensitive voltage and current measurements (see Table 1). Voltage resolution to microvolts and current resolution to fA (that's femto-amps, 10^{-15}) requires using Kelvin connections and guard lines (Fig 1).

Kelvin connections, sometimes referred to as 4-wire measure-

Table 1—Representative parameter analyzers

Manufacturer	Model	Number of SMUs	Voltage range	Resolution ²	Current range	Resolution ²	Display	Price	Comments
Hewlett-Packard	4142B	0 to 8 (modular)	±1000V	40 μ V	±10A	20 fA	None	\$12,000 base	\$28,000 to \$35,000 for typical configurations.
	4145B	4	±100V	100 μ V	±100 mA	50 fA	CRT	\$27,500	
Keithley	236	1	±110V	10 μ V	±110 mA	10 fA	Digital readout	\$4990	
	237	1	±1100V	10 μ V	±110 mA	10 fA	Digital readout	\$6490	
	238	1	±110V	10 μ V	±1A	10 fA	Digital readout	\$6290	
Tektronix	370A	NS ¹	2000V	50 μ V	20A	1 nA	CRT	\$20,900	
	371A	NS	3000V	100 mV/div	400A	1 μ A/div	CRT	\$25,900	
	571	NS	100V	50 mV/div	2A	5 μ A/div	CRT	\$3190	
	577D2-177	NS	1600V	5 mV/div	10A	0.2 nA/div	CRT	\$10,395	

Note: ¹NS = Not specified.

²Finest resolution is not available over full voltage or current range.

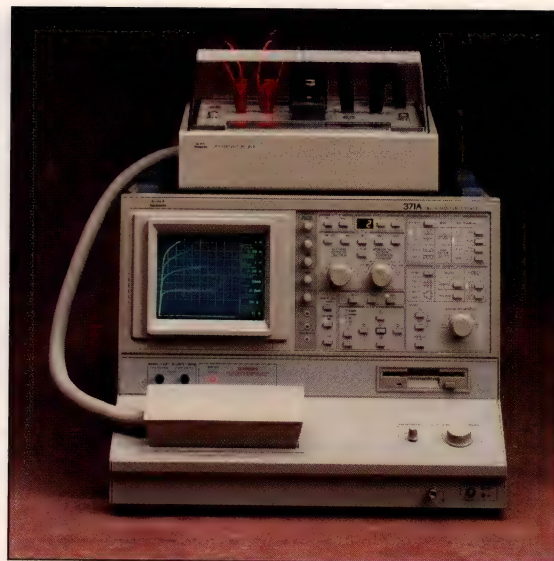
PARAMETER ANALYZERS

ments, use separate wires for current flow and sensing voltage. The sense wires connect at precisely the point where you want to force or measure a voltage. Some SMUs can have current levels of several amps, which can easily cause drops of tens of millivolts in the current-carrying wires. The Kelvin connection prevents the voltage drop in the current-carrying wires from affecting the accuracy of the measurement.

Guard lines minimize current leakage from interfering with measurements. The SMU drives the guard line to the same voltage as the sense lines, so little or no current flows between the force, sense, and the guard lines. Because the guard lines surround the force and sense lines, current leakage from the outside is to the guard line and, thus, does not affect the measurements.

Some of the important variations in parameter analyzers are in the voltage and current ranges shown in **Table 1**. Obviously, you'll need appropriate ranges to cover the circuits you'll be testing. Another significant difference in parameter analyzers is whether you can use the instruments in a stand-alone mode or if you'll need a computer for control and display.

The curve tracers from Tektronix



Testing components at power levels as high as 3000W is possible using the 371A Programmable Curve Tracer from Tektronix.

are stand-alone instruments. Although curve tracers do not offer the general-purpose capabilities of parameter analyzers made with SMUs, they do perform important functions in semiconductor parameter analysis.

A key feature favoring curve tracers is their ease of use. You can learn to operate a curve tracer quickly. The ease of operation is partly due to curve tracers' limited flexibility. They almost always offer only a voltage-vs-current display.

Compared with parameter analyzers using SMUs, curve tracers have

limited sensitivity. As **Table 1** shows, the curve tracers are all several orders of magnitude less sensitive in current measurements than the SMU-based instruments.

Yet curve tracers, especially Tektronix's 371A, have strong high-power testing capabilities. The combination of high current and high voltage allows testing to 3-kW power levels—far higher than any of the SMU-based instruments. The 3000V capability is also higher than for SMU-based parameter analyzers.

The curve tracers let you test devices at high power levels using pulsed-power testing. The periods of high-power pulses are separated by periods of zero power, keeping the average power low and avoiding the need for heat sinking. Some SMU-based parameter analyzers use the pulse-power technique even though power levels are considerably lower. The pulsed-power testing technique helps you avoid thermal effects that can cause device performance to change over the course of a test.

In addition to the curve tracers from Tektronix, the only other instrument in **Table 1** that operates stand-alone to produce device performance plots is the HP4145B. The instrument is a fixed configuration

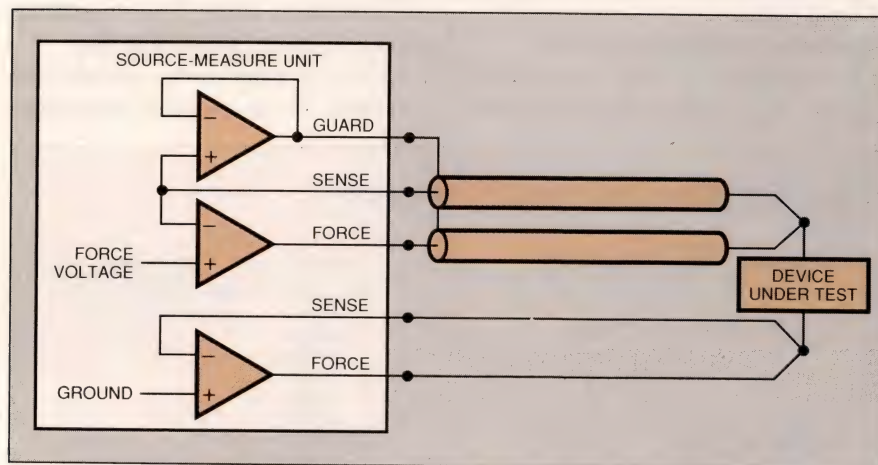


Fig 1—Kelvin connections avoid measurement inaccuracies caused by voltage drops in the current-carrying force line by sensing and correcting the voltage to the device under test. The guard line shields the force and sense lines from current leakage that would otherwise cause inaccurate current measurements.



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of four SMUs in a benchtop unit that handles all control and display functions. The instrument can perform mathematical functions on the acquired data rather than just plot voltage and current values on the screen. For example, you can program the instrument to plot gain vs current for a transistor.

The other parameter analyzer from HP, the 4142B, is a modular unit that requires a separate computer for control and display. Software for the instrument lets you operate it in a benchtop manner similar to the 4145B, although you'll still need a separate computer. With the HP4142B, you can select among four different SMU modules that cover the range of voltages and currents shown in **Table 1**. The high-voltage module 41422A and the high-current module 41423A are both 2-quadrant units, meaning they can source current only for positive voltages and sink current only for negative voltages.

Another module for the instrument is the analog feedback unit 41425A. The module lets you quickly find the input conditions required for a specific output condition. Typically, using a parameter analyzer, you would sweep through a set of input source levels and record the output measured. The analog feedback unit produces a plot of the input vs output that lets you zero in quickly on the input required for a specific output.

Although technically you'd have to say Keithley's family of SMUs operates stand alone, in practice you'd want to connect them to a computer, unless all you want to do is make single-point measurements. The 236, 237, and 238 are all single SMUs with different current and voltage limits as shown in **Table 1**.

The instruments work in an IEEE-488 setup with a minimum of bus traffic. Each SMU can take a 1000-point sweep of data that in-

cludes the sourced and measured values, the delay between each measurement, and elapsed time. When using a setup with more than one SMU, you can have each SMU trigger the next in a data sweep. Daisy chaining the triggers lets you limit the required IEEE-488 bus traffic to setting up measurement sweeps and downloading measurements from the SMU at the end of a data sweep. The reduced IEEE-488 bus traffic results in faster data acquisition.

The parameter analyzers using SMUs can record data vs elapsed time to examine characteristics that vary over time. For example, if you are characterizing a capacitor for precision sample-and-hold applications, you need a capacitor with low dielectric adsorption. You can test for dielectric adsorption by forcing a voltage, then forcing zero volts, and finally forcing zero current and measuring the voltage across the capacitor vs time. The capacitor's memory effect due to dielectric adsorption will cause the voltage to increase over time to some small fraction of the initially forced value.

A simple measurement such as dielectric adsorption shows the general-purpose nature of a parameter analyzer. You don't need to create any special instrument setup beyond programming the source and measure values. Creating your own test lets you test a capacitor with the voltage levels and time inter-

vals appropriate to your sample-and-hold application. You probably won't find information that's so tailored to your needs on a capacitor data sheet.

Curve tracers typically do not provide characteristics vs elapsed time. However, Tektronix's 370A offers limited characteristics-vs-time measuring capabilities. The 370A uses an envelope mode to show how a semiconductor's parameters change over time. Using the 370A's envelope mode is similar to using an envelope mode on a digital storage oscilloscope.

For some test applications, a parameter analyzer may be overkill. If you only need to perform a few parameter-analyzer functions occasionally, you may be able to connect existing instruments to make the measurements. If you find you need to characterize components often, you may want to use a general-purpose parameter analyzer. Don't overlook the flexibility of SMUs when setting up in-house ATE systems for dc testing. **EDN**

For more information . . .

For more information on the parameter-analyzer products discussed in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you saw their products in EDN.

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1. Oxner, Ed, "Parameter extraction and estimation produce accurate JFET models," *EDN*, August 19, 1991, pg 137.

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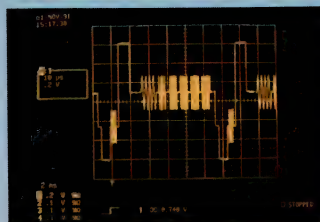
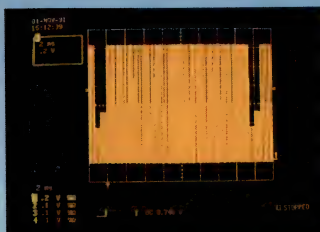
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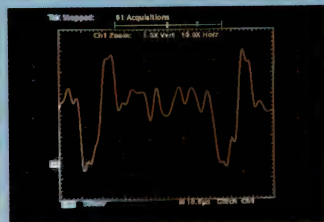
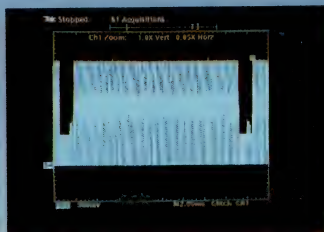


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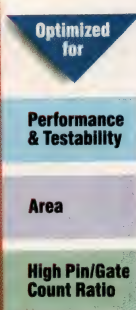
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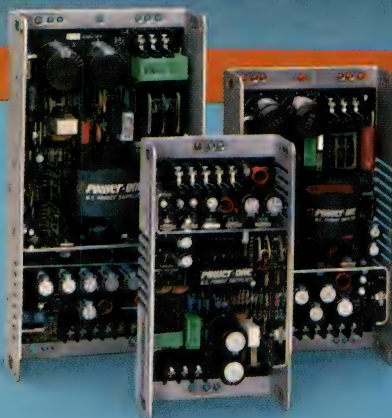
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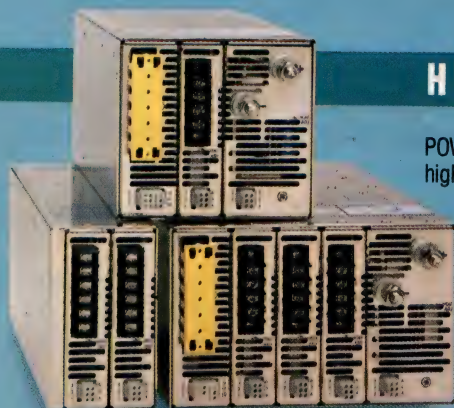
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Timing techniques help signals stay in sync

ANNE WATSON SWAGER, Technical Editor



You'll need a variety of practical skills and tools to tackle high-speed timing problems—even the best timing device presents no magical solution.

Without effective clock management, the benefits of a synchronous digital design break down at high speeds. Driving logic with synchronous clock edges will prevent any number of timing uncertainties, but only if those clocks are truly synchronous. As μ P speeds pass 33 MHz and head for 50 MHz and higher, generating and distributing those high-speed clocks becomes a specialty of its own.

This specialty requires diverse skills: knowledge and use of the appropriate

parts for clock generation; knowledge of high-speed layout techniques; and the ability to simulate, analyze, and test clock paths (see **box**, "Simulation spots timing uncertainties"). Acquiring these skills involves paying more attention to details, such as feedback techniques and transmission-line characteristics, once considered to be exclusively analog-circuit-design's domain.

These details relate respectively to the two problems of high-speed timing: generation and distribution. In the first

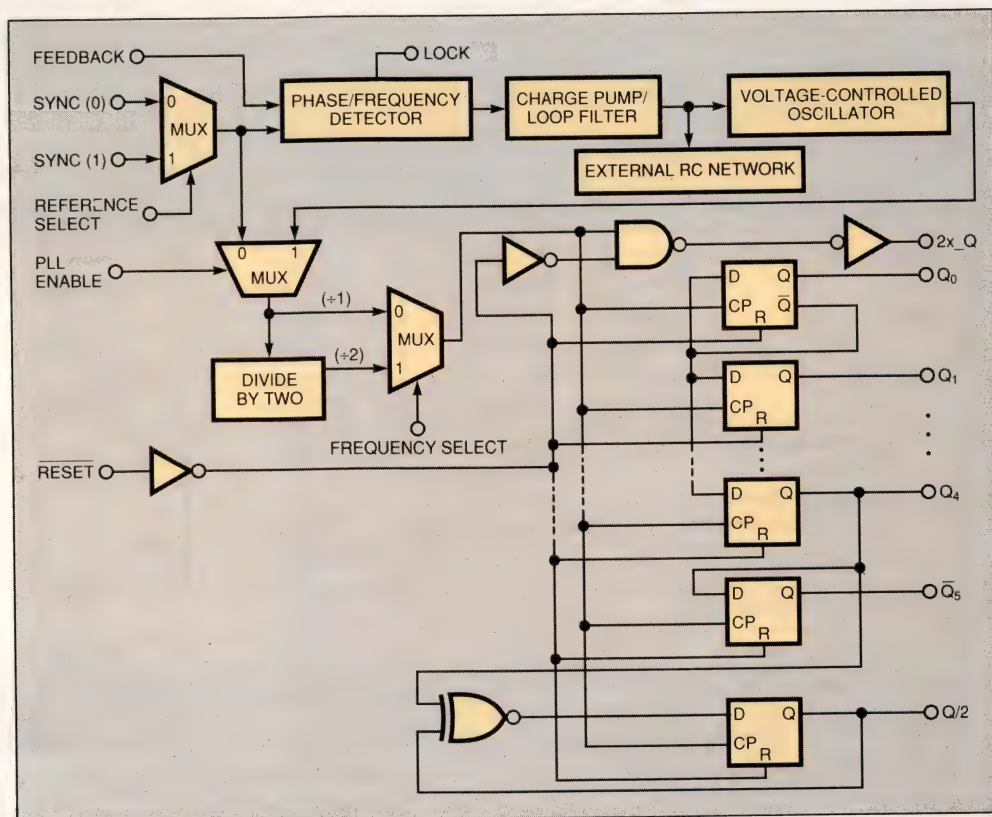


Fig 1—Phase-locked loops are popping up in purely digital designs for two reasons: They can produce multiples of an input clock reference, and they enable you to control the phase difference between that reference and the output. Motorola's MC88915 provides one output at $2\times$, six at $1\times$, and one at $\frac{1}{2}\times$ the input frequency.

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Sieve	speed code size	715 ms 169 bytes	960 ms 153 bytes	954 ms 164 bytes	67 ms 126 bytes
Optimize	speed code size	264 μ sec. 234 bytes	415 μ sec. 280 bytes	450 μ sec. 318 bytes	15 μ sec. 112 bytes
C Source Debugging: —Simulation —Evaluation Board —In-Circuit Emulator		CXDB C & ASM EVB/EVM/EVS Pentica, Orion, Nohau	IDB C No Pentica	No No No No	CXDB C & ASM EVB16 In Development
In-Line Assembler		Yes	Yes	No	Yes
Overlaid Local Data Storage		Yes	No	No	Yes
Compiler Price (PC)		\$1200	\$2000	\$1295	\$1600

Dhrystone v.1.1 CACM vol. 27; Sieve and Optimize Benchmarks from Byte Mag. 8/83; Whitesmiths v. 3.32.8; Introl v. 3.06 and Archimedes v. 3.20B. 68HC11 @ 2 MHz E-clock. 68HC16 @ 16.78 MHz clock.

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case, you want to generate multiple copies of a clock signal having fixed relationships to one another. Without interfering with those relationships, you want to distribute these clock copies to various points within a board or an entire system.

On the generator side, specialized clock drivers can produce copies of clock signals with a maximum skew of 0.5 to 1 nsec for TTL- and CMOS-compatible outputs. Also, some state-of-the-art clock drivers contain internal phase-locked loops (PLLs) that, when locked to a clock reference, can provide multiples and fractions of the reference with precise phase-delay characteristics (Fig 1.)

On the distribution side, the judicious use of delay lines can help you adjust a clock signal's characteristics as it travels through the system. However, there's no magic way to get around the fact that high-speed signals require layout techniques that minimize the length of traces and evenly load a clock driver's various outputs. You may also have to incorporate impedance matching and load termination into your layout techniques.

Generating and distributing high-

speed signals is tricky whether you're working at the chip, board, or system level. Clocking within an ASIC has its own unique challenge because of the clock tree, or lack thereof, designed in by the vendor. Though not discussed in detail in this article, many ASIC vendors are addressing the issue of timing by either implementing innovative clock trees or by designing on-chip PLLs.

Acknowledge potential problems

It's easy to discuss the problems you can have generating and distributing high-speed clock signals. But designing to prevent those problems, and detecting them if they do occur, is not so simple.

Accumulated skew—the difference between the expected and actual arrival time of a signal—eats into set-up-time and hold-time safety margins and can force the system to come dangerously and unreliably close to violating them. Imagine that two leaves on remote branches of your system's clock tree are exchanging data. The clock signal comes from two very different paths with relatively large differences in delay. In this case, skew

can amount to an entire clock-to-output delay. This amount of skew results in zero hold time.

Race conditions caused by inadequate set-up and hold times can also force the outputs of latches and registers into a metastable state. Even though semiconductor manufacturers have attempted to deal with the problem of metastability, no device is completely immune to it. The necessity of avoiding metastability compounds the importance of limiting skew.

Unfortunately, timing problems are some of the most elusive. A hold-time violation caused by communication between remote branches may not cause problems all the time or even some of the time. Your design may be working right at the edge of the safety margin without your knowing it. You, and your test equipment, may miss glitches entirely during prototype testing only to have them surface in volume production.

Not only are the problems hard to detect, but they're also sensitive to a number of system conditions: temperature variations, absolute power-supply level and power-

Simulation spots timing uncertainties

Despite your attention to the design details of clock generation and distribution, timing problems are hard to anticipate. Simulation is one tool that can help you pinpoint where and when those uncertain edges will occur in a final design. Most vendors of low-skew clock drivers and buffers now provide models of the input and output stages of their devices.

Semiconductor manufacturers aren't the only ones participating in the modeling efforts. Connector manufacturer AMP (Harrisburg, PA, (800) 522-6752) now offers connector models. If you have to run clock signals from board to board through a backplane, these models help you realistically include the effects of connectors.

Many CAE vendors offer timing verifiers to help you analyze clock paths. These may or may not be suitable for high-speed analysis. One software package that is tailored to high-speed designs is Motive (\$9000 for

PC version; \$13,000 for single-node Unix version) from Quad Design Technology Inc (Camarillo, CA, (805) 988-8250). This software identifies all set-up and hold violations in an ASIC or board-level design without test vectors by tracing every signal-delay path. The software accounts for worst-case interconnect and component delays. The software's clock-description language can describe multiphase and multifrequency clocks as well as the skew between any pair of clock signals. Before route, the software can calculate board delays by estimating wire length and by accounting for the electrical characteristics of all drivers and receivers. After route, the company's transmission-line-calculator package (\$7700 for PC version; \$12,000 for Unix) can send more accurate interconnect data back to Motive for further analysis.

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supply noise, and master clock noise and jitter.

All types of skew can accumulate to the point that your system literally operates on borrowed time. The most often quoted rule of thumb says that skew should be at most 10% of the system clock's period. For a 33-MHz clock, 10% of the period is 3 nsec. For 50 MHz, the number is 2 nsec. Thus, most of the 1-nsec parts in **Table 1** would be sufficient to meet the 10% skew specs for these systems.

However, rules of thumb aren't guarantees. For some systems, the percentage of tolerable skew may be much lower, in which case the available TTL and CMOS clock drivers don't give you much margin. ECL is about your only choice for skew requirements less than 0.5 nsec. If you have any prejudice against ECL, you may want to take a second look at its benefits for clock distribution (**Ref 2**).

Many forces, including changing system conditions, work against the

timeliness and integrity of high-speed signals. These forces all produce clock skew. Managing the production of that skew is the subject of Clock Management 101.

Various types of skew can affect high-speed timing. Intrinsic skew arises in the generator circuitry; extrinsic skew arises in the distribution circuitry, which includes the receivers and the traces that carry signals to them (**Fig 2**). Controlling clock skew at the generator is the first step.

Table 1—Representative clock drivers (buffer and PLL types)

Manufacturer	Part	Description	Input/output levels	Maximum skew (nsec)		
				Output-to-output	Part-to-part	Duty-cycle
Integrated Device Technology Inc	49FCT805/6	Dual, 1-to-5 buffers	TTL/TTL	0.7	1.5	1.0
Motorola Inc	MC10/100H640	÷2 and ÷4 buffers for 68030 and 040 μ Ps	PECL or TTL/TTL	0.5	NS	NS
	MC10/100H641	1-to-9 clock driver	PECL/TTL	0.5	1.0	NS
	MC74F1803	Quad, D-type inverting flip-flops	TTL/TTL	2.0	NS	NS
	MC10/100E111	1-to-9 differential clock driver	ECL/ECL	0.05	NS	NS
	MC88915FN55 /70	PLL type with 8 outputs	TTL/CMOS or TTL	0.5 (rising edge) 0.75 (falling edge)	NS	NS
National Semiconductor Corp	CGS74B2525/ 'C2525/ 'CT2525	1-to-8 clock buffers	TTL/TTL, CMOS/CMOS, TTL/CMOS	1.0	1.75 3.5 3.5	1.5 NS NS
	CGS74C2526/ 'CT2526	2-to-8 clock buffers	CMOS/CMOS, TTL/CMOS	1.0	3.5 5.0	NS NS
	F100115	1-to-4 clock buffer	ECL/ECL	0.075	NS	NS
Silicon Connections Corp	SC3501Q-1	1-to-20, ÷2, ÷4, and ÷8 clock buffers with symmetry adjust	TTL or PECL/TTL	0.5	1.0	±0.5
	SC3502Q-1	1-to-20 clock dividers	TTL or PECL/TTL	1.0	1.5	±0.25
	SC3505Q-1	1-to-20 clock buffer	TTL or PECL/TTL	0.5	1.0	NS
	SC3507Q-1	1-to-20 clock divider	TTL or PECL/TTL	0.5	1.0	±0.25
Texas Instruments Inc	SN74AS303/4/5	1-to-8 ÷2 clock dividers	TTL/TTL	1.0	NS	1.0
	SN74ABT328	1-to-6 buffer with selectable polarity	TTL/TTL	0.5	NS	0.8
	74AC11204	Hex inverting buffers	CMOS/CMOS	1.0	NS	NS
	54/74ACT11208	Dual, 1-to-4 buffers with 3-state outputs	TTL/CMOS	1.0	NS	NS
Triquint Semiconductor Inc	GA1110E-50	PLL-type 1-to-6 buffer	TTL/TTL	0.5	NS	1
	GA1210E-50	PLL-type clock doubler	TTL/TTL	0.5	NS	1

Notes: PECL=ECL referenced to 5V.
NS=not specified
NA=not applicable

Standard buffers, such as the '244, don't specify skew on their data sheets. You could arrive at a rough skew figure by taking the difference between the low-to-high and high-to-low propagation delay specifications. However, manufacturers claim this calculation produces vague and overly conservative numbers. Also, these calculations don't provide any information on how skew varies with system conditions.

Skew's importance has increased

as speed has increased. So the types of clock buffers in **Table 1**, which includes both buffer and PLL types, are much more than respecified '244 buffers. The chips listed were designed to minimize internally generated skew. Manufacturers of these clock drivers recognize five different types of intrinsic skew: output-to-output skew; part-to-part or process skew; duty-cycle, pulse, or pin skew; input skew; and limit skew.

Output-to-output skew is the dif-

ference between output edges of clock drivers that generate multiple copies from a single input clock. These devices have anywhere from 6 to 20 outputs (**Table 1**). Currently, the lowest output-to-output skew—the guaranteed maximum—for TTL or CMOS-compatible devices is 0.5 nsec. For ECL devices, the best is around 50 psec.

For those devices with mixtures of inverters and buffers, such as the Texas Instruments SN74A30X family, the skew is the same, 1 nsec,

Propagation delay	Output frequency (MHz)	Number of Q outputs	Number of Q outputs	Output drive (IOH, IOL)	Package(s)	Price (100)
6.5	NS	5/0	0/5	-24, 64 mA	20-pin DIP, SOIC, LCC	\$8
6	33 and 66	4 ÷ 2, 2 ÷ 4	2	-15, 24 mA	28-pin LCC	\$15.11
6.27	66	9	0	-15, 24 mA	28-pin LCC	\$15.11
7.5	35	0	4	-20, 24 mA	14-pin DIP, SOIC	\$3.25
0.73	600	9 pairs differential	0	NS	28-pin LCC	\$30.67
NS	55/70	5 × 1, 1 × 2, 1 ÷ 2	1 × 1	-36, 36 mA	28-pin LCC	\$15.11/ \$14.57
4.8 7.8 7.8	NS	8	0	-24, 24 mA	14-pin DIP, SOIC, 20-pin LCC	\$6.10 \$8.29 \$8.29
7.8 7.8	NS	8	0	-24, 24 mA	16-pin DIP, SOIC, 20-pin LCC	\$8.29 \$8.29
1.2	NS	4 pairs differential	NA	NS	16-pin SOIC	\$7.25
NS	80	10 ÷ 2, 5 ÷ 2 or ÷ 4, 5 ÷ 4 or ÷ 8	0	-24, 24 mA	52-pin QFP	\$25
NS	80	5 ÷ 2, 5 ÷ 2 or ÷ 4	5 ÷ 2, 5 ÷ 2 or ÷ 4	-24, 24 mA	52-pin QFP	\$25
NS	80	20	0	-24, 24 mA	52-pin QFP	\$24
NS	80	10 ÷ 2, 5 ÷ 2 or ÷ 4, 5 ÷ 2 or ÷ 4	0	-24, 24 mA	52-pin QFP	\$25
9	80	6/8/4	2/0/4	-24, 48 mA	16-pin DIP, SOIC	\$6.64
4.8	NS	user selectable	user selectable	-15, 64 mA	16-pin SOIC	\$9.13 \$11.62
5.7	NS	0	6 independent inverters	-24, 24 mA	20-pin DIP, SOIC	\$7.05
10.2	NS	2 groups of 4 of one selected polarity	see left	-24, 24 mA	20-pin DIP, SOIC, chip carrier	\$7.47
1.0	50	6 in user-selected 2-nsec phase-shift increments	see left	-24, 24 mA	16-pin DIP	\$33.20
1.0	100	6 in user-selected buffering, inverting, or doubling configurations	see left	-24, 24 mA	16-pin DIP	\$37.40

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within the groups of Q and \bar{Q} outputs. However, the skew across the Q and \bar{Q} outputs can be as high as 2 nsec.

Part-to-part or process skew is the difference in output skew across different packages of the same device. Tight part-to-part specs are difficult to achieve, and you can see from **Table 1** that they are always worse than the output-to-output specs. Also, many manufacturers don't test for or guarantee any part-to-part numbers. Thus, depending on how many copies of the clock you need, you should either attempt to choose one driver for them all, such as one of Silicon Connections' 20-output devices, or use individual drivers for various branches of a clock tree.

For those applications that require clock duty cycles very close to 50%, duty-cycle skew is an important parameter. Duty-cycle skew is the difference between low-to-high and high-to-low propagation-delay times when a single input causes one or more outputs to switch.

As **Table 1** reflects, most manufacturers don't routinely include duty-cycle skew specifications for all their devices. For its 1-input to 20-output drivers, Silicon Connections specifies that at a threshold voltage of 1.5V the maximum asymmetry between high-to-low and low-to-high transitions is ± 0.25 nsec. Just as with the output-to-output specs, these numbers apply only within certain output groupings. Some of the company's devices also feature a symmetry adjustment. Using three inputs, you can move the output edge of the SC3501 in 0.25-nsec increments from +0.75 to -0.75 nsec.

Two skews go unspecified

The final two types of skew are rarely specified and aren't as relevant as the previous types. Input skew pertains to multiple input de-

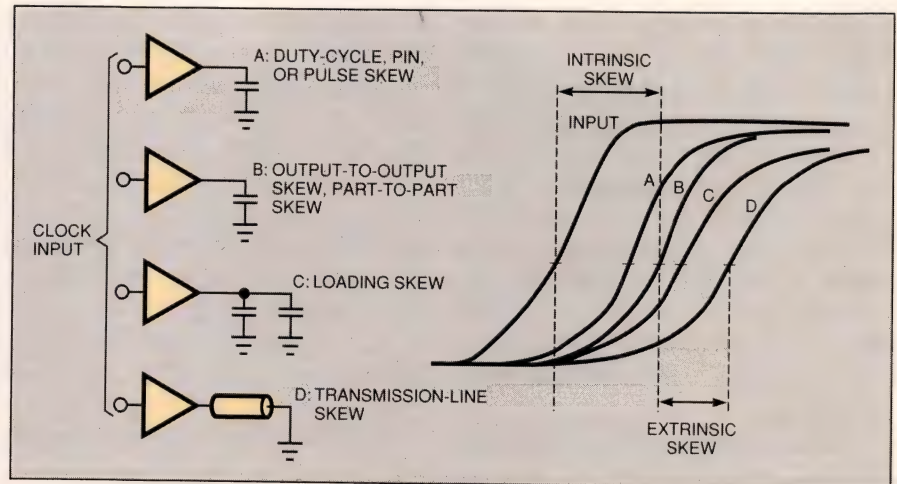


Fig 2—Clock management boils down to controlling the production and accumulation of skew, which can arise from many sources intrinsic and extrinsic to the clock drivers.

vices and is the difference between any two propagation-delay times that originate at different inputs and terminate at a single output. Limit skew is the calculated difference between the maximum specified values of either low-to-high or high-to-low propagation delay and the minimum values of the same. This calculated number can tell you how much the propagation delay varies due to change in supply voltage, temperature, output load, and other operating conditions.

Of all of these types of skew, the data sheets at best specify the first three. When specified, the skew numbers for different parts don't cover the same performance range, which varies from manufacturer to manufacturer. So even having the specifications available doesn't guarantee that you can compare parts easily.

Some of the specs cover the entire operating temperature range of the part. Others are only true at 25°C. Also, manufacturers derive certain specifications from tested results while deriving others from calculated or simulated results. National Semiconductor is one manufacturer that provides extensive test data, such as that in **Fig 3**, to show the performance of their devices as parameters such as output

frequency and capacitance change.

Just as the data sheets aren't standardized, neither are the parts themselves. These drivers don't come in any standard package or pinout. Some have center power and ground pins. The drivers' numbers of outputs and their configuration, whether buffered, inverted, or both, varies. Some of the devices can accept positive ECL (PECL) signals, (ECL signals referenced to 5V). Others have TTL-compatible inputs with CMOS-compatible outputs.

PLL types lock on

Most so-called clock drivers can produce copies or divided-down versions of an input clock. But they do not give you control over the delay through the device. On the other hand, those drivers with internal PLLs can produce multiples of the input clock and give you some control of the phase difference between input and output. Motorola and Triquint Semiconductor are currently the only manufacturers of PLL-type clock drivers. However, Texas Instruments is currently designing a PLL device that should be available in the first half of this year.

PLL-type clock drivers are useful for two primary reasons: to multiply the input clock and to phase-

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advance or retard the output in relation to the reference input. For example, using select pins and external feedback, you can phase-adjust the outputs of the GA1110E in ± 2 -nsec increments. The GA1210E produces multiple copies at $2 \times$ the input frequency. Because of feedback, PLL-based drivers can compensate for process, temperature, and voltage variations by always locking the output of each part to the common input reference clock.

The standard PLL contains a phase detector, voltage-controlled oscillator (VCO), and a loop filter, and can include a frequency detector (Fig 1). The free-running frequency of the VCO is usually much higher than the output frequency, which allows the parts to generate various multiples of the input frequency. The internal VCOs in Triquint Semiconductor's GA1110 and 1210 run at 500 MHz, but the device's outputs are set for output frequencies of 25, 33, 40, and 50 MHz.

The loop filters of these PLL-based drivers may require external

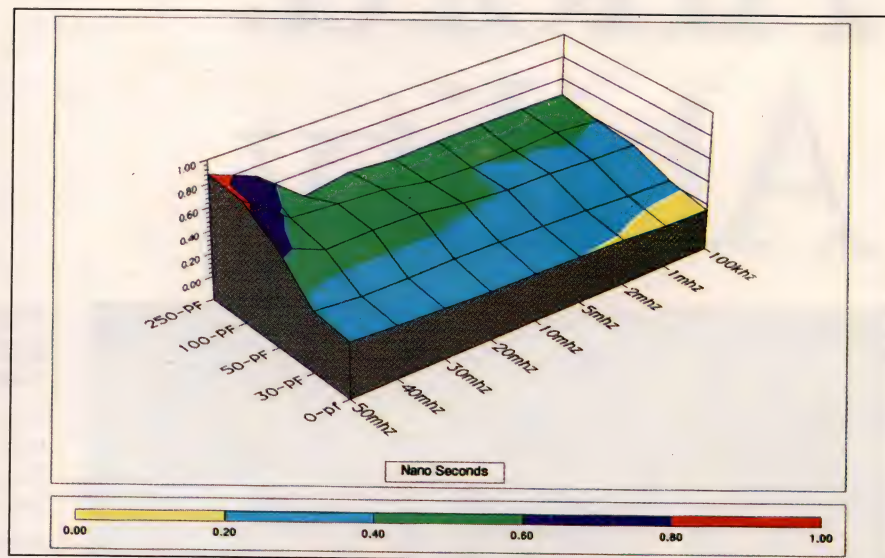


Fig 3—Guaranteed skew specs aren't necessarily the results of thorough testing. However, National Semiconductor does provide extensive test data such as this graph, which shows how output capacitance and clock frequency affect the output-to-output skew of the CGS74B2525.

components. The loop filters of the GA1110 and 1210 are on chip, whereas Motorola's MC88915 requires an external RLC network of six passive components. Requiring an external loop filter does have one advantage—it provides the PLL with a wide frequency range. While the free-running outputs of the Tri-

quint parts are set to specific output frequencies, the 70-MHz version of the MC88915 can lock onto an input that ranges anywhere from 10 to 35 MHz.

As versatile and useful as the PLL-based devices are, they have their own unique performance quirks. Any phase-locked system

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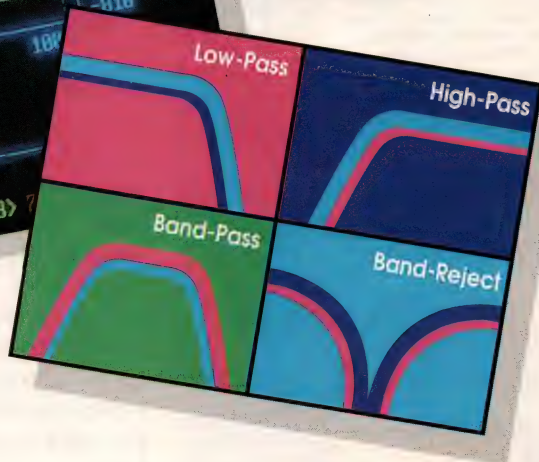
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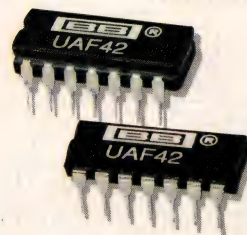
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requires a finite time to reach the locked condition. The time required for the GA1101 and GA1210 to acquire lock is typically 200 μ sec and maximally 500 μ sec. The typical wait for resynchronization in a 33-MHz system would then be 6600 cycles. Texas Instruments' SN74ABT338 requires a minimum of 50 μ sec. Motorola's MC88915 takes a minimum of 1 msec and a maximum of 10 msec.

These numbers are fractions of the normal start-up times required by the clock oscillator. Thus, from start up, the time required for lock doesn't require any waiting, since you're already waiting for the oscillator. However, if the path from the system clock and the device is interrupted for any reason—without the clock source itself losing power—once the clock signal returns, you can't expect any precise relationship between input and output until the chip itself reestablishes lock.

Distribute without adding skew

Generating multiple clock-signal copies with low skew solves just half of the timing problem. Extrinsic skew can accumulate during distribution because of trace-length differences, loading differences, or because the clock signal's waveform has been corrupted. Layout techniques that evenly load all of the outputs of one clock driver, by matching trace lengths for example, are another step toward minimizing extrinsic skew.

Some parts, such as delay lines, do exist that help correct for distribution effects by allowing you to de-skew multiple channels of a shared clock (Ref 3). Analog Devices and Brooktree both make delay lines primarily for the ATE industry that are applicable to many high-speed systems. For exacting timing requirements, Brooktree's Bt622 dual and BT624 quad delay lines (\$32 and

\$43, respectively, (100)) allow you to adjust both the delay and the width of high-speed ECL pulses. These devices let you compensate for differences in positive-vs-negative-going signal delays.

Adjustable delay lines are more useful than those with fixed delays at their tap points because you can use one device to cover a variety of delay times. The CMOS Bt630's (\$11.10 (100)) five tap points at 20, 40, 60, 80, and 100% of the full-scale delay are adjustable over a 25- to 400-nsec full-scale range. Analog Devices' ECL AD9500 (\$16 (100)) and TTL- and CMOS-compatible 9501 (\$8.60 (100)) are digitally programmable delay generators with resolutions as small as 10 psec and a delay range of 2.5 nsec to 10 μ sec full-scale range.

All specialized timing devices can help you generate and distribute high-speed clock signals more effectively. However, every high-speed design and every high-speed layout is unique: No one device works in every situation. High-speed timing problems can only be averted by the combination of part selection, layout, simulation, and thorough test.

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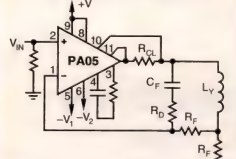
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High 476 Medium 477 Low 478

PA05

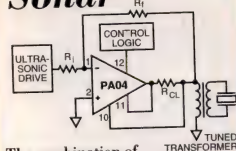
Deflection



High speed makes the PA05 operational amplifier the choice for deflection applications. Combining a 100V/ μ s slew rate with a 100V supply, ± 30 A output current, thermal protection, and a 360kHz power bandwidth, makes the PA05 a cost effective solution. 100+ pricing is \$189.00.

PA04

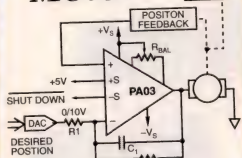
Sonar



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PA03

Motor



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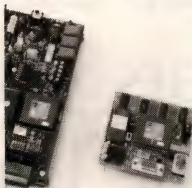
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This helpful, new 44-page application guide explains what an instrumentation amplifier (in-amp) is, how it operates, and how and where to use it. Written by Lew Counts and Chuck Kitchin, this free guide covers topics including *Basic In-Amp Theory*, *Design Considerations for Instrumentation Amplifiers*, and *In-Amp Applications*. It should be on every designer's desk!

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The industry's first octal 12-bit DAC, AD7568, costs less than \$3 per channel in 1,000s! Featuring eight independent 12-bit current output DACs, serial interface and four-quadrant multiplication, it's available in low-profile 44-pin PQFP. Requiring a single +5-V

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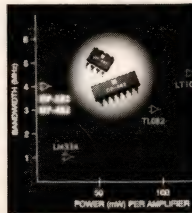


Accompanying the ADSP-21020 and its family of floating-point DSPs, the development software tools, ADDS-210XX-DSW, comprise an assembler, linker, assembly library, librarian, simulator and PROM splitter. Algebraic syntax of the assembler (and instruction

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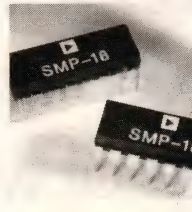


signals of 10 V rms can be driven into low-load impedances with no degradation of performance.

Our SSM-2017 replaces discrete solutions made from up to 20 passive components, four transistors and an op amp. This low-cost audio preamplifier features input noise voltage of 950 pV/√Hz (at 1 kHz, G=1,000), and THD is typically just 0.01% over the full audio range. And output

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include ATE, comparator and time delay generator circuits, process control system set points, and more.

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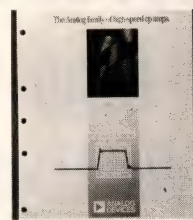


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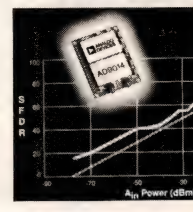


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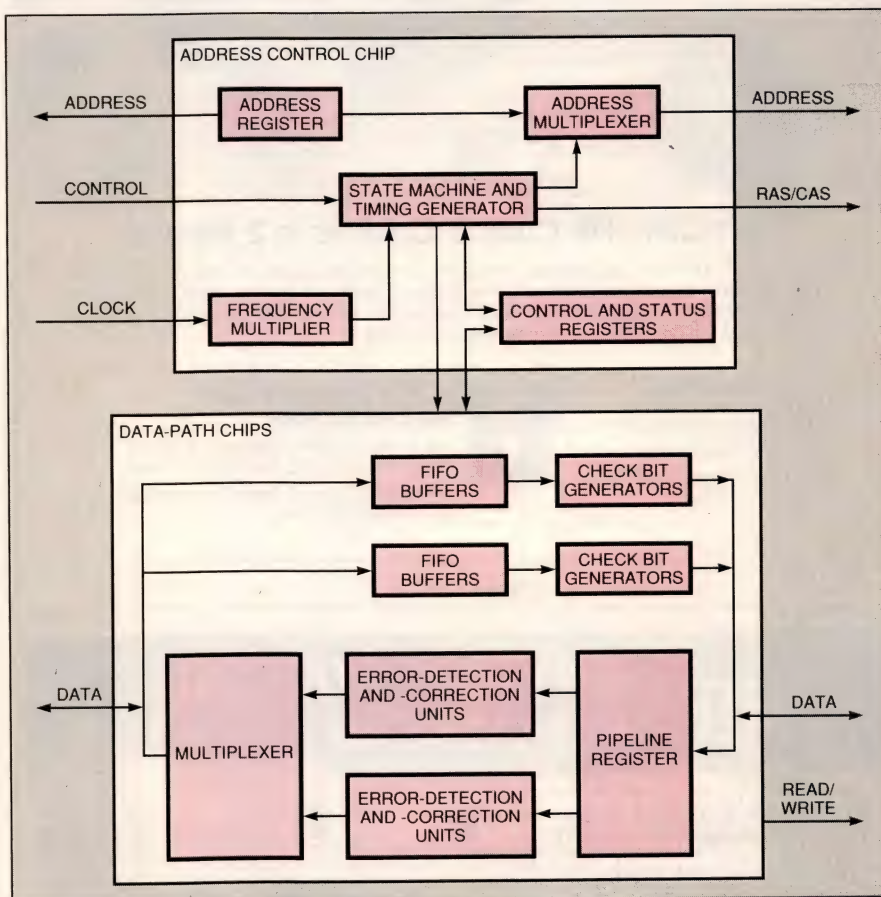
DRAM controller simplifies 32-bit-processor access to memory

The CYM7232 dynamic-RAM (DRAM) controller module simplifies and speeds your 32-bit processor's access to its banks of the main DRAM. It handles all of the DRAM interface as well as error detection and correction for memory banks as large as 1 Gbyte and systems as fast as 50 MHz.

The module speeds your processor's access to its DRAM in a variety of ways. For example, the module uses a first-in, first-out (FIFO) buffer to store as many as 16 words coming in from the processor. The buffer allows the module to accept burst writes at the processor's speed, independent of the DRAM's speed or refresh status. The buffer also allows the module to offer a posted write, temporarily holding the data until the processor has completed a read operation, then writing the data to DRAM. The posted write allows the processor to swap cache lines without waiting for the DRAM write cycles to complete.

The module speeds read access by using as many as four banks of memory and multiplexing the data to the processor. When the processor addresses one DRAM word, the module reads from all the banks simultaneously, pipelining the data so that subsequent sequential read operations are independent of the DRAM's timing.

The module handles all DRAM control while maintaining a straight-forward interface to your processor. This interface is programmable to adapt to a variety of 32-bit processors, including SPARC, i486, i860, 68040, and 88110. For example, the interface can handle either multiplexed or separate data and address buses. You can also set the module's bus acknowledge sig-



This DRAM controller module handles DRAM access for a variety of 32-bit microprocessors with system clocks as fast as 50 MHz.

nal timing, choose big- or little-endian byte ordering, set the length and sequencing of burst accesses, and choose bus parity.

The module's system interface also supports multiprocessor configurations. It allows processors with snooping cache controllers to inhibit read or write operations initiated by another processor. The inhibited operation can then be re-directed to account for differences between the DRAM's data and data stored in the various processor caches.

For example, the snooping processor would inhibit a read operation

if its cache contained the requested data and the DRAM data was not current. The snooping processor would then supply the requested data in place of the DRAM. A command line on the module also allows the inhibited read to become a reflective read. A reflective read requires the module to capture the processor-to-processor data transfer and update the DRAM when the transfer is complete.

The module's DRAM interface handles all DRAM addressing and refresh operations, supporting DRAM arrays as large as 1 Gbyte with speeds as fast as 80 nsec. The



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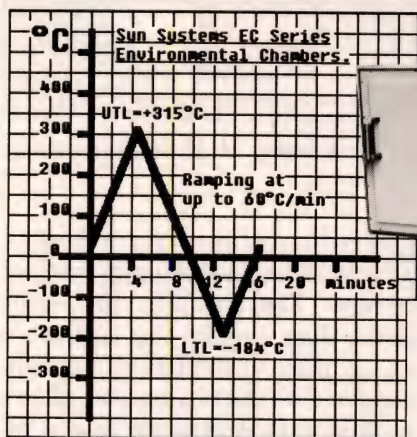
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CIRCLE NO. 95

DRAM array can have as many as four blocks of memory, each as deep as 16 Mbits. Each block has four banks of memory with 32 data bits and 7 check bits. The module's address timing is programmable, allowing you to use 256-kbit-, 1-Mbit-, 2-Mbit-, or 4-Mbit-deep devices. The DRAM interface timing is synchronous, deriving from a frequency-multiplied version of the system clock generated by the module's phase-locked loop.

Large banks of memory increase the opportunity for soft errors to creep into your data. To help maintain data integrity, the module offers two error-handling features.

It has built-in error-detection-and-correction (EDC) circuitry that operates on 32 bits at a time. The module has four EDC circuits, one for each bank. The circuits can detect a 2-bit error and correct a 1-bit error as the data is transferred from the DRAM to the processor. The module keeps an internal FIFO log of any errors detected and can generate a system interrupt when an error occurs.

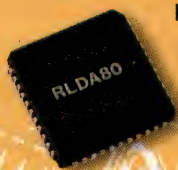
Automatic data scrubbing allows the module to check for errors on all four banks simultaneously, as it refreshes each block of memory. If it detects a correctable error, the module changes the DRAM refresh cycle to a read-modify-write cycle, then corrects the corrupted data. The module can scrub a 1-Gbyte array every 15 minutes.

The CYM7232 module comes in a 400-pin pin-grid array that measures 2.8 in. square. Samples will be available in March at a cost of \$327 (100).—**Richard A Quinnell**

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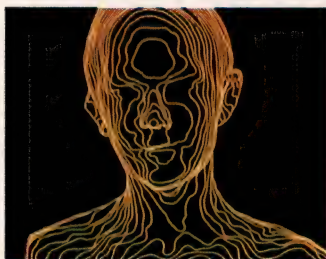
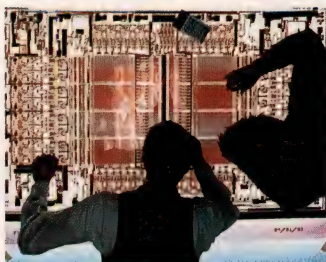
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μP/peripheral-function building blocks speed system-design tasks

Having a library of microprocessors and peripheral functions allows you to design complex ASICs quickly, much as you'd build a breadboard. The Coreware library contains three groups of building blocks: 16- and 32-bit microprocessors, floating-point processors, and peripheral functions.

Several ASIC-vendor libraries contain 4-, 8-, and 16-bit microprocessor cores. One ASIC vendor, VLSI Technology, offers a core of its Acorn 32-bit RISC (reduced-instruction-set-computer) processor. LSI Logic's Coreware library offers familiar 32-bit RISC cores that allow you to customize designs by tailoring the cache or peripherals to meet your application's special needs. These building blocks are high-speed, standard components with existing software bases and large installations of native hosts.

At introduction, the library contains embedded SPARC and Mips microprocessor cores and a 1750A 16-bit processor core. Among the range of pipelined and nonpipelined IEEE-754-compliant floating-point units are 32- and 64-bit ALUs and multipliers as well as a pipelined 32-bit divider. Initially, peripheral functions are limited to a SCSI-1 controller, a generic multiprocessor bus interface, an SBus DMA controller, and a Mips read-write buffer. JPEG (Joint Photographic Experts Group) Image Compression, a Reed-Solomon Codec, and the Mips integrated FPU/CPU functions are currently in the works.

Each function block, like ASIC primitives, consists of a schematic representation and a gate-level simulation model in LSI Logic's proprietary format. In addition, the function blocks also offer behavioral-level simulation models. These

C-code models are kept in an intermediate format that the vendor can translate to VHDL (VHSIC Hardware Description Language), Verilog, and its own behavioral-simulation language.

In addition, the function blocks feature existing test vectors. These vectors allow the vendor to perform comprehensive in-circuit manufacturing tests on each of the blocks. The test method that each pattern uses varies depending on the particular functional blocks; the embedded SPARC module uses an internal scan chain whereas the embedded Mips module uses parallel-input vectors that require you to provide pin access to the block's borders. These tests reduce your design responsibility to just providing observation and control of nodes within the random logic and non-Coreware library functional blocks.

The roughly 20,000-gate embedded SPARC core is a bare-bones processor. The core is based on the early SPARC instruction set; it doesn't perform direct multiplication or division. In addition, the core offers no floating-point coprocessor interface and requires two memory cycles for load instructions. The core, which runs at 20 MHz, does provide on-chip cache support or offers an interface to off-chip cache.

The Mips family is represented by two core processors, which can run at 25, 33, and 40 MHz. Both the roughly 35,000-gate embedded core and the 25,000-gate CPU are fully static designs that implement most of the Mips I instruction set. Using 1-μm fabrication, you can surround the core with approximately 65,000 gates of additional logic. The embedded core provides a 4- or 8-kbyte instruction cache, an optional data cache, a DRAM (dy-

namic RAM) controller, a bus-interface unit, and three counter/timers.

A direct data-bus interface bypasses the bus-interface unit and provides single-cycle data transfers between the embedded CPU and dedicated on-chip static RAM or ROM. The cores offer provisions for DMA, although they sacrifice coprocessor support, a memory-management unit, and translation look-aside buffers (TLBs). Without the TLB registers, the CPUs don't offer instructions to manipulate them; if your code contains them, these instructions will cause exceptions.

Pricing depends on several factors, including the core, volume, and design requirements. The access fee, which includes function-block royalties, starts at \$30,000. This fee supplements the nonrecurring engineering cost, which starts at \$30,000. If your needs require it, the vendor will actively participate in the design.—**Michael C Markowitz**

LSI Logic Corp, M/S D102, 1551 McCarthy Blvd, Milpitas, CA 95035. Phone (408) 954-4875.

Circle No. 731

Low-cost package links 68HC16 to PC

Debugging critical code for an embedded μC is a bit easier with Motorola's ICD16 debugging tool for the 16-bit 68HC16 microcontroller (μC). This tool links a PC host computer to a 68HC16 target system. The ICD16 module plugs into a PC parallel port. Using the module, users can directly control μC target code's execution.

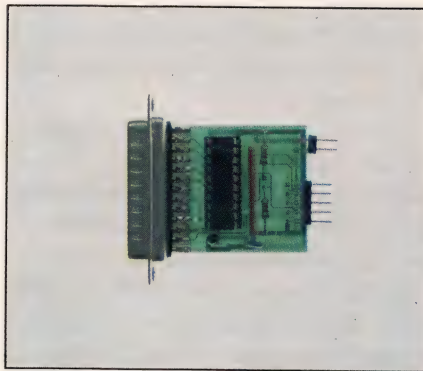
The ICD16 takes advantage of the background mode, which Motorola added for on-target debug-

ging, of the 68HC16. In background mode, normal processor execution is halted and an external host can control the processor via eight control pins. In background mode, a remote user can interrogate or set register or memory values as well as set breakpoints. When execution hits a breakpoint, processor execution halts and control passes to background mode.

Unlike an ICE (in-circuit emulator), the debug tool requires some board space for wiring and a 10-pin header. In addition, the ICD16 operation is intrusive: Debugging affects code execution. The ICD16 uses processor resources, mainly execution time, to execute breakpoints, retrieve and set memory or register values, and communicate with the host PC. However, once you set a breakpoint, you can monitor execution in real time until the code hits it and breaks.

In contrast, ICEs are mainly non-intrusive. They collect trace data in separate buffers, not affecting performance until the trace buffer is full. A breakpoint will, of course, stop execution. The ICD16 approach is less intrusive than that of using a monitor—a small debug

kernel, which takes up memory and processor resources. In addition, the ICD16 does not need to use the μ C's serial port to link to a host; it uses special pins. You could actually run a monitor—linked via a serial port—and the ICD16 simultaneously, because they don't share link resources.



You can debug 68HC16 target code without an ICE. To monitor and control execution, the ICD16 links to the target μ C via background mode.

The ICD16 package consists of the module, a target cable, and debugging software. The software is a more advanced version of the integrated assembler furnished with Motorola's 68HC16 evaluation board. This version provides a win-

dowed development environment, which integrates a macroassembler, an editor, and a source-code debugger with a host-to-target communications link.

The source-code debugger enables you to debug target code at the source level (C or assembly). It adds performance monitoring (address reference counts), macroscripts, a dumb terminal window, file verification, and interrogation of the 68HC16 multiply-and-accumulate unit. P&E Microsystems Inc (Woburn, MA) developed the core software for Motorola.

The ICD16 supplements Motorola's 68HC16 evaluation board; initially, you can work the 68HC16 with the evaluation board, and then use the ICD16 to debug target boards. You could also bypass the evaluation board and use the ICD16 with a simple target configuration.

The ICD16 costs \$99. The 68HC16 evaluation board costs \$168 during the first quarter of 1992; the standard evaluation-board price will be \$320 thereafter.—**Ray Weiss**

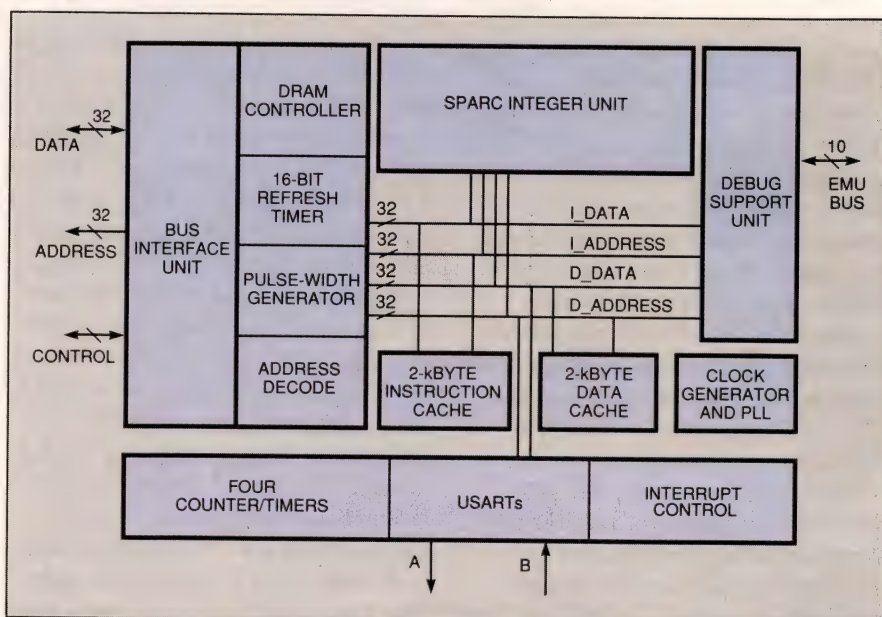
Motorola Microprocessor Products Group, 6501 William Cannon Dr W, Austin, TX 78735. Phone (512) 440-2000.

Circle No. 732

32-bit μ C integrates SPARC with embedded peripherals

Fujitsu's 32-bit SPARClite MB86931 integrates the SPARC RISC (reduced-instruction-set-computer) architecture with a set of μ C peripherals tailored for embedded processing. The SPARClite "event processor" handles real-time events. The chip integrates the SPARC integer processor with 2 kbytes each of on-chip instruction and data cache, an interrupt controller, counter/timers for monitoring external events, and a dynamic-RAM controller.

To increase execution speed,

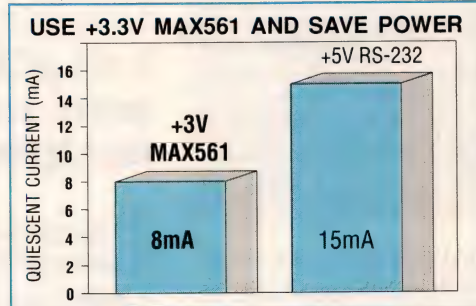


SPARC RISC fits embedded systems. The SPARClite μ C combines a SPARC CPU with on-chip cache, timers, and an interrupt controller.

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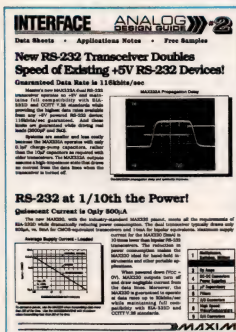


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* As stated in the EIA/TIA-562 specification.

SPARClite MB86931

Clock	20, 49 MHz
Instruction cache	2 kbytes
Data cache	2 kbytes
Memory	Dynamic-RAM support: Wait-state generator, Refresh controller
Timers	4 counter timers, Refresh timer
Miscellaneous	Interrupt controller, 15 interrupts, 2 USARTs
Package type	256-pin quad flatpack
Sample price	\$49 (10,000)

Fujitsu added instructions to the original SPARC instruction set: an integer multiply instruction and a divide step instruction, as well as a bit-scan instruction that looks for the first nonsign bit. This bit-scan instruction helps in processing bit maps.

In addition, the chip is a fully static design. SPARClite cleans up a number of problems of earlier SPARC implementations. For example, loads and store are typically one instruction cycle, compared with two and three cycles for earlier SPARC CPUs. Some of these speed-ups are a result of a Harvard architecture with divided dual instruction and data caches, unlike Sun SPARC's single unified cache.

Also, this family has on-chip hooks for embedded system test and built-in, in-circuit-emulator/monitor support. The processor has six breakpoint registers. To monitor code execution, users can set two instruction, two data-value, and two data-address breakpoints.

The chip has small on-chip caches. These 2-kbyte caches are generally effective if inner loops fit into the caches. Cache entries can be locked in, enabling critical code to be kept in the 2-way set associative caches for continuous processing. The CPU doesn't wait for the 2-word cache line to be filled from external mem-

ory: The first word is used without waiting for the second.—**Ray Weiss**

*Fujitsu Microelectronics Inc,
Advanced Products Div, 77 Rio
Robles, San Jose, CA 95134. Phone
(408) 922-9000. FAX (408) 943-
9293.*

Circle No. 733

8-bit μ C handles power and keyboard management

Laptop power-management and control functions are becoming a major application area. Signetics 80C550 microcontroller (μ C) is an 8051 derivative that combines key laptop functions: power management and keyboard control. The 8-bit μ C crams the 8051 architecture (with 30 I/O pins and A/D converter) into a 40-pin DIP or 44-lead PLCC (plastic leaded chip carrier).

This chip fills a gap in the 8051 world: It supplies enough peripherals to handle power management and provides the I/Os and program-

ROM space to support standard control functions such as keyboard management. In addition, the μ C's 40- or 44-pin packaging lets you minimize board space but still get the job done.

The controller's 8-channel, 8-bit A/D converter samples and converts in 40.5 μ sec. The converter can sample power levels, signaling brownout, and power failures, in power-critical applications. The μ C

80/83/87C550

Clock	3.5 to 16 MHz
Program	4 kbytes ROM/EPROM
Data	128-byte RAM
I/Os	30/32 pins
Interrupts	2 external
Special	8 channel, 8-bit ADC (6 channel on DIP) 2 16-bit counters, watchdog timer, UART
Package types	40-pin DIP, 44-lead plastic leaded chip carrier or quad flatpack
Price	\$4.60 DIP ROM (10,000) \$17.83 one-time-programmable DIP (1000)

Power-management design kit

Today, laptops are hot and laptops require power management. The Signetic's design kit lets engineers design in 80C752/550 μ Cs for laptop power management.

The kit consists of an application note, which defines the design; a schematic of the complete design; and the application source code.

Using this kit, you can modify the design for your own needs or use it to understand a power-management application. This baseline design saves time by providing an easy-to-understand base to start from. The kit defines a Signetics optimizer board that monitors power. It controls the system frequency generator for clocks and the system-memory, dynamic-RAM-refresh cycles. Keyboard and peripheral activity drives the state machine that controls power management.

An on-chip A/D converter monitors the system battery level and V_{CC} . The optimizer drives the clock-frequency generator and controls the system-refresh generator. Six operational modes include full power; doze, when the clock rate is halved; shutdown, when power to specific peripherals is turned off; shutdown-doze; sleep, when power is removed from display backlight and LCD regulator; suspend, when the μ C takes over memory refresh task and removes power from the rest of the system; and off, when all power is turned off.

The design kit is free of charge.

STEP-UP DC-DC REGULATORS DELIVER 90% EFFICIENCY!

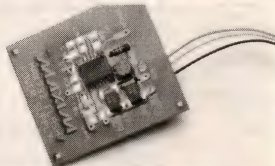
Compact Solutions for +5V, +12V, +15V or Adjustable Outputs

Use the new MAX731, MAX732, MAX733, and MAX752 step-up regulators to build complete 85% to 95% efficient power supplies that fit into less than 0.65in^2 of board space. Low input voltages (2.5V) and miniature external components make these compact regulators ideal for portable and board-level DC-DC conversion in 3V, 5V, or battery-powered systems. High-frequency 170kHz pulse-width modulation (PWM) current-mode control provides excellent transient response and minimum ripple.

- ◆ **Evaluation Kits – SOIC and DIP**
- ◆ **Guaranteed Output Current:**
200mA @ 5V (MAX731, $V_{\text{IN}} > 2.7\text{V}$)
150mA @ 12V (MAX732, $V_{\text{IN}} > 4.5\text{V}$)
100mA @ 15V (MAX733, $V_{\text{IN}} > 4.5\text{V}$)
- ◆ **Regulates From Low Input Voltage:**
2.5V & Up (MAX731/MAX752)
4.0V & Up (MAX732/MAX733)
- ◆ **Logic-Controlled $6\mu\text{A}$ Shutdown**
- ◆ **8-Pin DIP & 16-Pin SOIC**

Part	Input Voltage Range	Output Voltage	Output Current	Power Eff. Range	Price† (1000-up)
MAX731	2.5V to 4.65V	+5V	200mA	85%-90%	\$3.20
MAX732	4V to 9.3V	+12V	200mA	85%-95%	\$2.60
MAX733	4V to 11V	+15V	125mA	85%-95%	\$2.60
MAX752	2.5V to 15V	Adjustable 2.7V to 15.75V	200mA	85%-95%	\$3.20

EVALUATION KITS GIVE IMMEDIATE RESULTS

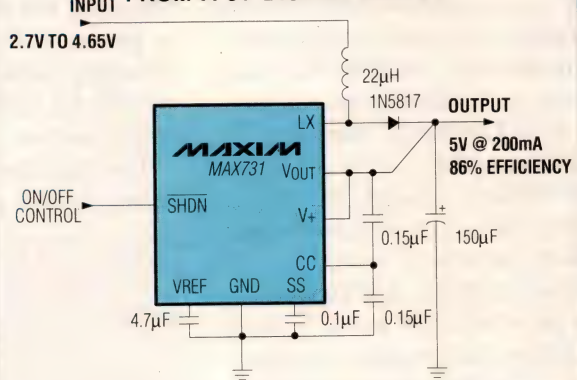


MAX732 Surface-Mounted EV Kit

Each complete surface-mount or through-hole kit contains a PC board and all external components, including inductor. \$20.00 each.†

MAX731EVKIT – DIP MAX733EVKIT – DIP
MAX732EVKIT – DIP MAX752EVKIT – DIP
MAX732EVKIT – SO*

POWER 1 WATT OF 5V-LOGIC FROM A 3V DIGITAL SUPPLY



The MAX731 surface-mount circuit fits in 0.65in^2 (4.2cm^2) and has 86% efficiency while delivering 200mA at 5V from a 3V source.

POWER SUPPLIES ANALOG

Data Sheets • Application Notes • Free Samples

+5V To ±15V DC-DC Converter Delivers 30W

No Design Required—Just Drop It In

MAXIM's MAX731, MAX732, MAX733, and MAX752 step-up regulators are ideal for portable and board-level DC-DC conversion in 3V, 5V, or battery-powered systems. High-frequency 170kHz pulse-width modulation (PWM) current-mode control provides excellent transient response and minimum ripple.

Evaluation Kits Simplify Prototyping

Maxim offers design aids, evaluation kits, and application notes to help you get the most out of your MAX731, MAX732, MAX733, and MAX752 step-up regulators. These kits are available for purchase or as a free sample.

Production Kit Saves Procurement and Increases Reliability

Maxim's production kit is a complete, turn-key solution for your MAX731, MAX732, MAX733, and MAX752 step-up regulators. It includes all the components you need to get your design up and running quickly and reliably.

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FREE Power Supply Design Guide

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*Flash Memory Programming Supply. †FOB USA recommended resale.

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has standard 8051 idle and power-down modes for power saving. In idle mode the CPU shuts down, but selected peripherals continue to operate. In power-down mode, the entire μC shuts down. An interrupt or reset will resume μC operations.

The chip runs at 16 MHz. Its power-supply current is 35 mA for active mode, which drops to 6 mA in idle mode and falls to 50 μA in power-down mode.—**Ray Weiss**

Signetics Corp, 811 E Arques Ave, Sunnyvale, CA 94088. Phone (408) 991-2000. FAX (408) 991-2311.

Circle No. 734

μC combines small pin-out, power management, application protection

Designing controllers for low-cost appliances and industrial controllers is a tough compromise among low cost, multiple functions, and safety. National Semiconductor's 8-bit COP820CJ microcontroller (μC) can take a little of the pain out of appliance design. It combines a 1- μsec CPU core with power management, brownout detection, direct display drive, A/D conversion, pulse generation for motor or sound generation, and multiple timers.

The μC is built around the National COP800 CPU core. This core is an accumulator-based implementation (six registers), with 1-kbyte program ROM and 64 bytes of data RAM. This μC is designed for low-end appliance applications such as toasters, coffee makers, vacuum cleaners, and food processors. These applications require fail-proof safety, moderate program capability, multiple hardware interfaces, and power management.

Safety features are built in to the μC . Brownout, power failure, infinite software loops, and other error conditions will automatically force a CPU reset. To save power, a hold mode drops power consumption in the static device from 8 mA

at a 10-MHz clock to 10 μA .

A brownout-protection circuit monitors V_{CC} and automatically resets the μC when the power level falls below 3V. It also detects transients with pulse widths of 70 nsec or greater. On a transient fault, the μC will stop CPU execution, returning to normal-mode operation when the transient ends. Detection circuitry saves designers from building external, discrete protection circuitry.

The μC responds to multiple external events. Eight of the I/O lines can be edge programmed to wake the processor from halt mode. Like other interrupts, the wake-up forces the CPU into a power-up or reset condition to start processing.

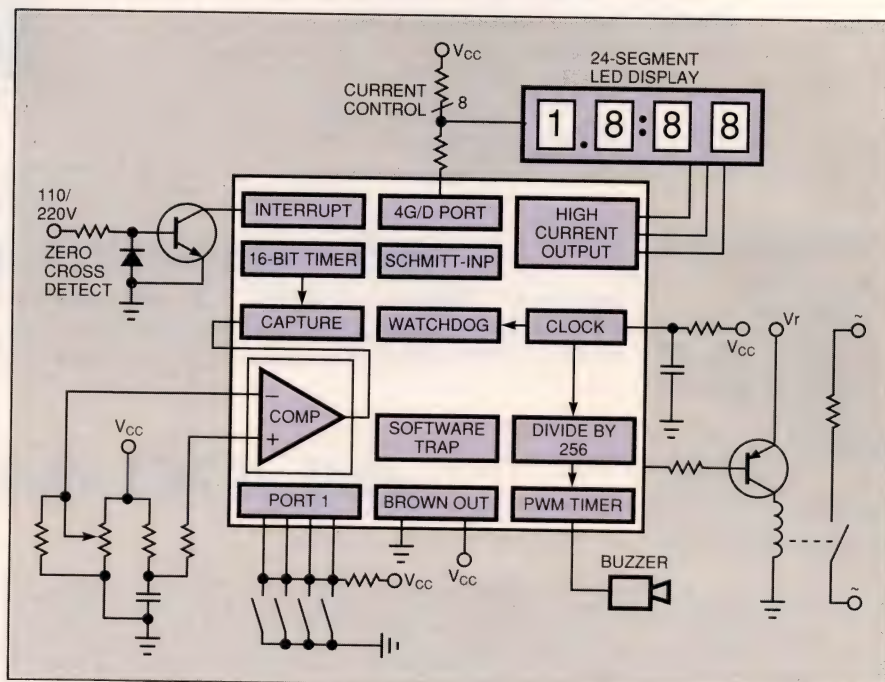
This controller has three timers. The 8-bit programmable watchdog timer has a divide-by-256 prescaler and can detect runaway software. The 8-bit PWM timer enables code to generate high-frequency pulses, including variable duty-cycle pulses (PWM) for motors or other electronic control.

The third timer is a 16-bit general timer/counter with a load/compare

register. This counter counts down, once per instruction cycle. On underflow, it generates a pulse for output or for interrupting the CPU. At the same time, it loads from the load/capture register. The counter can be programmed as an event counter, counting down for external signal pulse (500 kHz max). It can also serve as an input timer, counting down until an external signal triggers, whereupon the current count is saved to the load/compare register.

COP820CJ

Clock 1, 4, 10 MHz
Program 1-kbyte ROM
Data 64-byte RAM
I/Os 12 to 24 lines
	16 Schmitt triggers
Interrupts 3 external, timer, Software
Power 2.5 to 6V, HALT mode
Serial Serial bus
Timers Watchdog, 16-bit timer
Special Analog comparator
	Brownout detector
Package types 20- or 28-pin DIP, 16-pin SOIC
Price \$1.25 (10,000) \$1.15 (100,000)



Smart appliances can be controlled with a single low-end, 8-bit μC , the COP820CJ. In a 20-pin DIP, the chip supports small displays, motor control, power management, and user appliance control.

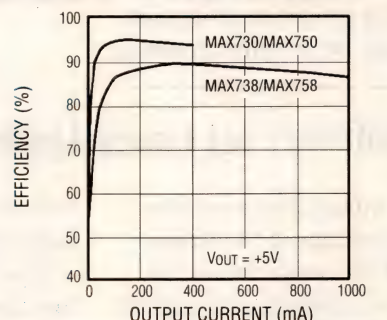
SMALL +5V & ADJUSTABLE DC-DCs HAVE 94% EFFICIENCY!

No Design Required for Guaranteed 300mA (1.5W) or 750mA (3.75W) Outputs

The new MAX730/MAX738 and MAX750/MAX758 step-down switching regulators are compact and simple solutions for battery-powered portable applications. They extend battery life by providing 85% to 95% efficient step-down regulation. Pre-selected components simplify design work and the standard application circuit delivers the guaranteed power over all specified line, load, and temperature conditions. High-frequency 160kHz pulse-width modulation (PWM) current-mode control provides low-noise operation and reduces output ripple to less than 50mVp-p.

- ◆ **Evaluation Kits – SOIC and DIP***
- ◆ **Guaranteed Output Current:**
750mA for $V_{IN} > 10.2V$ (MAX738/MAX758)
300mA for $V_{IN} > 6.0V$ (MAX730/MAX750)
- ◆ **Regulates From Low Input Voltage:**
+5.2V to +11.0V (MAX730/MAX750)
+6.0V to +16.0V (MAX738/MAX758)
- ◆ **Logic-Controlled 6 μ A Shutdown**
- ◆ **Adj. Output:** 1.25V to V_{IN} (MAX750/MAX758)
Fixed Output: +5V \pm 5% (MAX730/MAX738)
- ◆ **Space-Saving Footprint:**
8-Pin SOIC and 8-Pin DIP (MAX730/MAX750)
16-Pin SOIC and 8-Pin DIP (MAX738/MAX758)

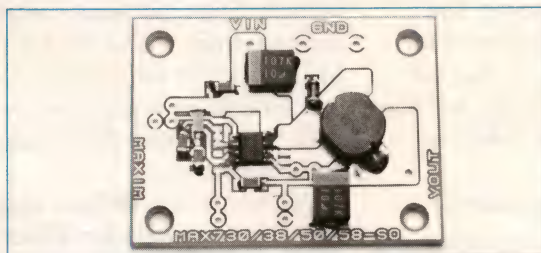
EFFICIENCY vs. OUTPUT CURRENT



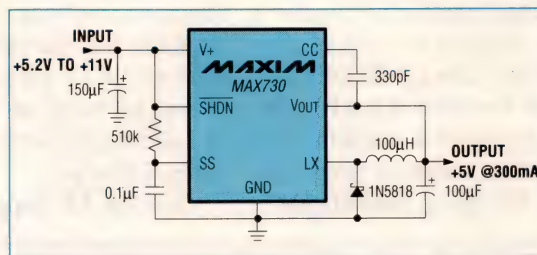
The MAX730/MAX750 and MAX738/MAX758 deliver high efficiency over a wide load range.

Evaluation Kits* Reduce Design Cycle & Provide Immediate Results

Surface-mount and through-hole kits are available for all four products, and contain a PC board and all external components, including inductor.*



The MAX730 application circuit components fit into $\frac{1}{2}$ in² (3.2cm²) of board space.



The MAX730/MAX738 evaluation kit has all the components needed to build a complete +5V step-down circuit.

POWER SUPPLIES ANALOG

Data Sheets • Application Notes • Free Samples

+5V To ±15V DC-DC Converter Delivers 30W

Free Design Required—Just Drop It In

The MAX730/MAX738 and MAX750/MAX758 step-down switching regulators are compact and simple solutions for battery-powered portable applications. They extend battery life by providing 85% to 95% efficient step-down regulation. Pre-selected components simplify design work and the standard application circuit delivers the guaranteed power over all specified line, load, and temperature conditions. High-frequency 160kHz pulse-width modulation (PWM) current-mode control provides low-noise operation and reduces output ripple to less than 50mVp-p.

The MAX730/MAX738 and MAX750/MAX758 are available in two versions: a surface-mount version and a through-hole version. The surface-mount version is available in 8-pin SOIC and 8-pin DIP packages. The through-hole version is available in 16-pin SOIC and 8-pin DIP packages.

Evaluation Kit Highlights:

- Contains a PC board and all external components, including inductor.
- Delivers 30W of power.
- Regulates from low input voltage.
- Provides 94% efficiency.
- Logic-controlled shutdown.
- Adjustable output.
- Space-saving footprint.

Production Kit Benefits:

- Reduces design cycle.
- Provides immediate results.
- Contains a PC board and all external components, including inductor.
- Delivers 30W of power.
- Regulates from low input voltage.
- Provides 94% efficiency.
- Logic-controlled shutdown.
- Adjustable output.
- Space-saving footprint.

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*Four Kits Available — MAX730/MAX738EVKIT-DIP; MAX730/MAX738EVKIT-SO; \$20 each.
MAX750/MAX758EVKIT-DIP; MAX750/MAX758EVKIT-SO.

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The COP820CJ doesn't have a full A/D converter. Instead, it has an analog comparator to test external voltages. With the proper program, you can use the comparator to build a single- or dual-slope A/D converter.

In addition, the μ C supports as many as 24 I/Os. These I/Os comprise a 4-bit output port, a 4-bit input port, and two 8-bit programmable ports. The programmable-port pins can be set at a high-impedance

input (weak pull-up) or a push-pull output. Four of the programmable pins can directly drive LEDs with as much as 15 mA. The 16-pin DIPs or SOICs have only 12 I/Os.

—Ray Weiss

*National Semiconductor Corp,
2900 Semiconductor Dr, Santa
Clara, CA 95051. Phone (408) 721-
5000. FAX (408) 730-0764.*

Circle No. 735

μ C and software kit tames Appletalk

PCs and workstations can now take advantage of the Appletalk network for desktops and offices. Zilog is releasing a design kit for the two lower layers of the 6-layer Appletalk protocol. With this kit, developers can link peripherals and systems using the Appletalk network. The Appletalk protocol transfers data at 230.4-kbits/sec.

The kit implements the toughest part of the Appletalk protocol, the data-link level—the Local Talk Link Access Protocol (LLAP). The Local Talk protocol is implemented as an assembly-language program running on the Zilog Z80181, an

8-bit microcontroller (μ C) for communications processing.

The remaining higher levels of the Appletalk protocol are less timing and processor dependent. They can be implemented on a back-end or host CPU: The Z80181 serves as a front-end communications processor, buffering packets for transmission or for passing back to the host. However, the Z80181 has enough headroom for the complete protocol. It can address as much as 1 Mbyte, and the LLAP implementation takes up only 5 kbytes.

The LLAP supports node-to-

node transmission and receipt of data and control packets. Because of tight signal-timing and synchronization constraints, this transmission is the most difficult part of Appletalk to implement. LLAP is a CSMA/CA (carrier-sense multiple-access and collision-avoidance) protocol with synchronous pulse generation and frame transmission and reception for each node.

The software kit includes assembly source code for the first two layers of the Appletalk protocol, a hardware evaluation board with a 10-MHz Z80181 μ C, the LLAP driver in an 8-kbyte EPROM, 8 kbytes of static RAM (SRAM) for additional user programs, RS-422 drivers, and a DIN-8 LLAP connection module. For PC-host-based debugging, the kit provides a debug monitor and a terminal emulator.

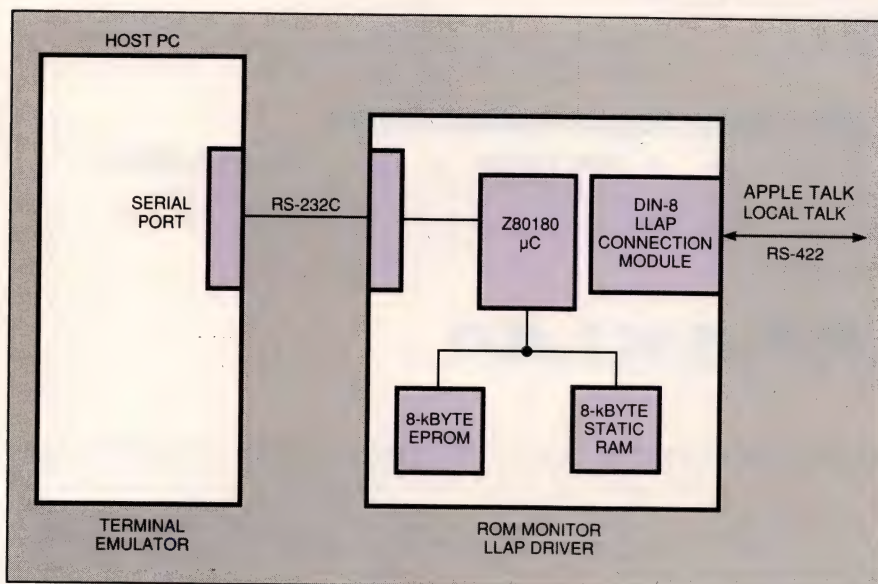
The Local Talk implementation of the physical layer uses an SDLC (synchronous data-link control) frame format with FM0 bit encoding (checks for bit transition on line) and RS-422 as a physical medium with a differential driver and 3-state signals.

Appletalk also defines data-link and physical levels for Ethernet (Ether Talk) and Token Ring (Token Talk). The data-link levels, including Local Talk, encapsulate or strip packets for a network level, which defines a Datagram Delivery Protocol (DDP). The data-link level supports node-to-node packet transmission and receipt. (It does not guarantee packet delivery but does deliver error-free packets.)

The Appletalk LLAP driver kit costs \$5,000, including source code. There is no run-time licensing fee.—Ray Weiss

*Zilog Inc, 210 E Hacienda Ave,
Campbell, CA 95008. Phone (408)
370-8000. FAX (408) 370-8056.*

Circle No. 736

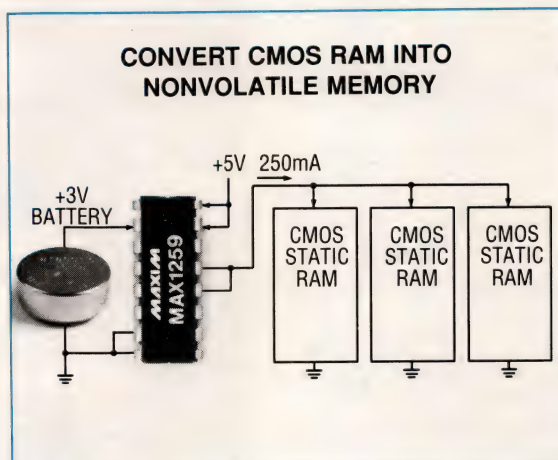


Help for the toughest part of the Appletalk communications protocol is available in a kit that includes source code and a Z80181 μ C-based board.

SWITCHOVER TO MAX1259 BATTERY MANAGER AND REDUCE POWER 67%

Maxim's new MAX1259 battery manager consumes only 100nA supply current in backup mode, 3.3mA in operating mode, and costs less than the industry standard DS1259. When power fails, the MAX1259 switches CMOS RAM, real time clocks, or other continuously powered circuits to the backup battery.

- ◆ **Uses 1/3 the Supply Current of DS1259 in Operating Mode – Only 3.3mA**
- ◆ **250mA Output Current at 0.2V Switch Drop**
- ◆ **Under 100nA Supply Current in Backup Mode**
- ◆ **Industrial/Military Temperature Ranges**
- ◆ **Plug-in DS1259 Upgrade**



The MAX1259 output makes it possible to backup several CMOS RAM chips.

Ideal for Monitoring +5V Supplies

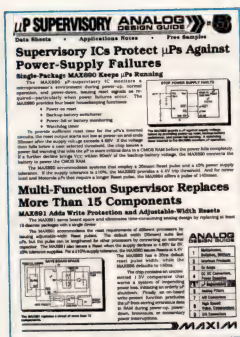
The MAX1259 is the perfect low-cost battery management system for portable and nonvolatile electronic equipment. Handheld instruments, controllers, computers and uninterruptable power supplies will benefit from extended battery life and guaranteed performance over temperature.

FREE μ P Supervisory Design Guide

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CIRCLE NO. 91

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Linear Technology Corporation and EDN are proud to sponsor a seminar for designers focusing on high speed amplifier techniques. This seminar is primarily devoted to familiarizing designers with the realities and difficulties of high speed circuit design.

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Jim Williams, the industry expert on both high speed amplifier and switching regulator techniques will discuss the complex world of circuit design. A staff scientist at Linear Technology, Williams has written over 100 application articles for numerous industry trade magazines including EDN. In addition to being one of EDN's



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SEMINAR LOCATIONS

Date	Location
March 30	Orlando
March 31	Boston
April 1	Northern New Jersey
April 2	Chicago
April 3	Dallas
April 7	Santa Clara
April 8	Orange County

Note: Seminar Schedule:
8:30 am - 12:00 pm
Lunch 12:00 pm - 1:00 pm.



Tickets for this half-day seminar are \$30.00 (price includes lunch). Reserve your place by calling 1-800-637-5545.

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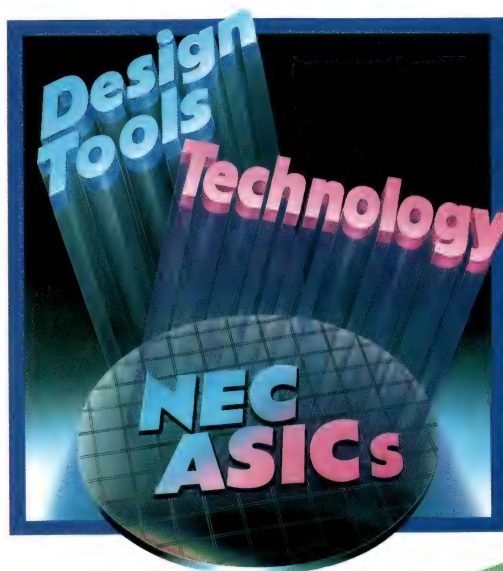
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NEC CB-C7 Cell-Based ASICs - Single-Chip Solutions to System Problems

Putting intelligent systems on silicon has never been so easy. Using NEC's CB-C7 advanced CMOS ASIC technology you can integrate all your system elements – such as micro-processor or microcontroller cores, RAM, ROM, intelligent peripherals and analog I/O – into a single-chip solution. And it won't cost you a fortune in new design tools, because NEC CB-C7 ASICs can be designed using industry standard hardware platforms and EDA software you probably already have.

NEC's CB-C7 cell-based ASIC technology gives you other advantages as well. The sub-micron CMOS process used to implement it not only allows CB-C7 to achieve the high level of integration required for systems-on-silicon, it also provides you with 0.44 nsec gate delays and ultra-low power consumption.

To make things even better, NEC offers you two routes to finished silicon. If you require a fast turnaround, we can implement user-defined logic in your design as a sea-of-gates gate array. Alternatively, if you are aiming for minimum chip cost, we can produce the entire ASIC as a standard-cell solution.

Functional Cells

CB-C7HD	CB-C7FT
Standard Logic Functions	Standard Logic Functions
74LS logic function	74LS logic function

Soft Macros

Peripheral Devices
System Support Functions
Compiled RAM/ROM

Hard Macros

CPUs:
V20H, V30H, μ COM 87

Peripherals
72-series 82-series

CB-C7 ASIC DESIGNS

Industry standard workstations and EDA software

For example, the library of mega-function blocks contains cores of our μ COM87, V20H and V30H microprocessors, plus intelligent peripheral functions such as those provided by NEC's 72-series and 82-series standard peripheral devices. And because most of these megafunction blocks are hard macros, derived directly from the chip layouts of our standard parts, they have fully characterized timing parameters and can be tested with the standard part test vectors.

Our hard macros are complemented by an extensive range of soft macros to provide additional peripheral device and system support functions, and by a library of over 300 standard logic functions available for both silicon realization approaches, the 'High-density' (CB-C7HD) and the 'Fast TAT'-option (CB-C7FT). And of course, all our RAM and ROM blocks can be compiled to exactly match your system requirements.

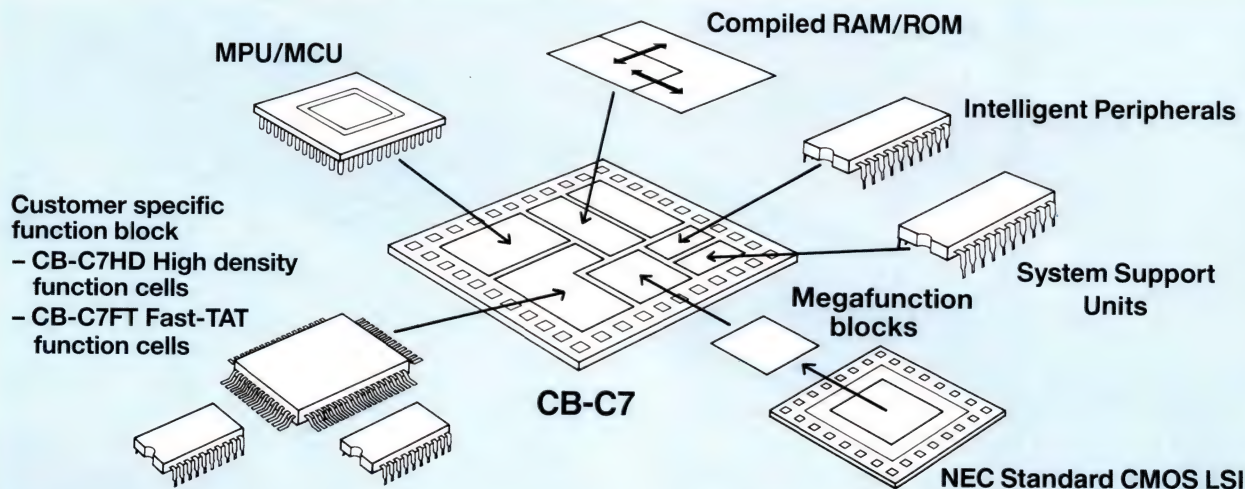
Sub-micron CMOS - high speed, low power

CB-C7 ASICs utilize an advanced CMOS process technology which features 0.8 μ m gate lengths. This technology achieves internal gate delays of only 0.44 nsec and power gate delays of 0.34 nsec (fan-out = 2, wire length = 2mm).

The high silicon utilization of the process allows us to achieve integration levels of over 180,000 usable 2-input NAND-gate equivalents per chip – more than sufficient to put high-performance systems into single-chip solutions. And although CB-C7 ASICs consume very little power – only 6.5 μ W/gate/MHz – their 48-mA drive capability allows them to deliver power when it's needed.

Mega function block Libraries – key to system integration

NEC's CB-C7 megafunction block-libraries cover all your likely integration requirements – from the simple logic elements which glue your system together, right up to the high-level functions which provide your designs with on-chip intelligence.



Solving Cost/Turnaround Trade-offs

Fast turnaround and low unit price are often conflicting requirements when it comes to implementing your ASIC designs – the first suggesting the use of a gate array solution, and the second dictating a standard cell approach. NEC's CB-C7 ASIC technology solves these cost/turnaround trade-offs – with combined gate-array/standard-cell solutions for fast turnaround, and full standard-cell implementations for low unit cost.

Whichever option you choose, the hard-macro, megafunction block and RAM/ROM blocks in your design will be floor-planned onto the chip in much the same way. If you need finished silicon in less than a month, we will then implement your customer specific logic in a 'sea of gates' gate array, laid down around these cells. Alternatively, if you are aiming for minimum piece price, we will implement the entire ASIC as a standard cell design – using sophisticated cell optimization algorithms to ensure we achieve minimum chip area.

High Performance ASICs and Packages

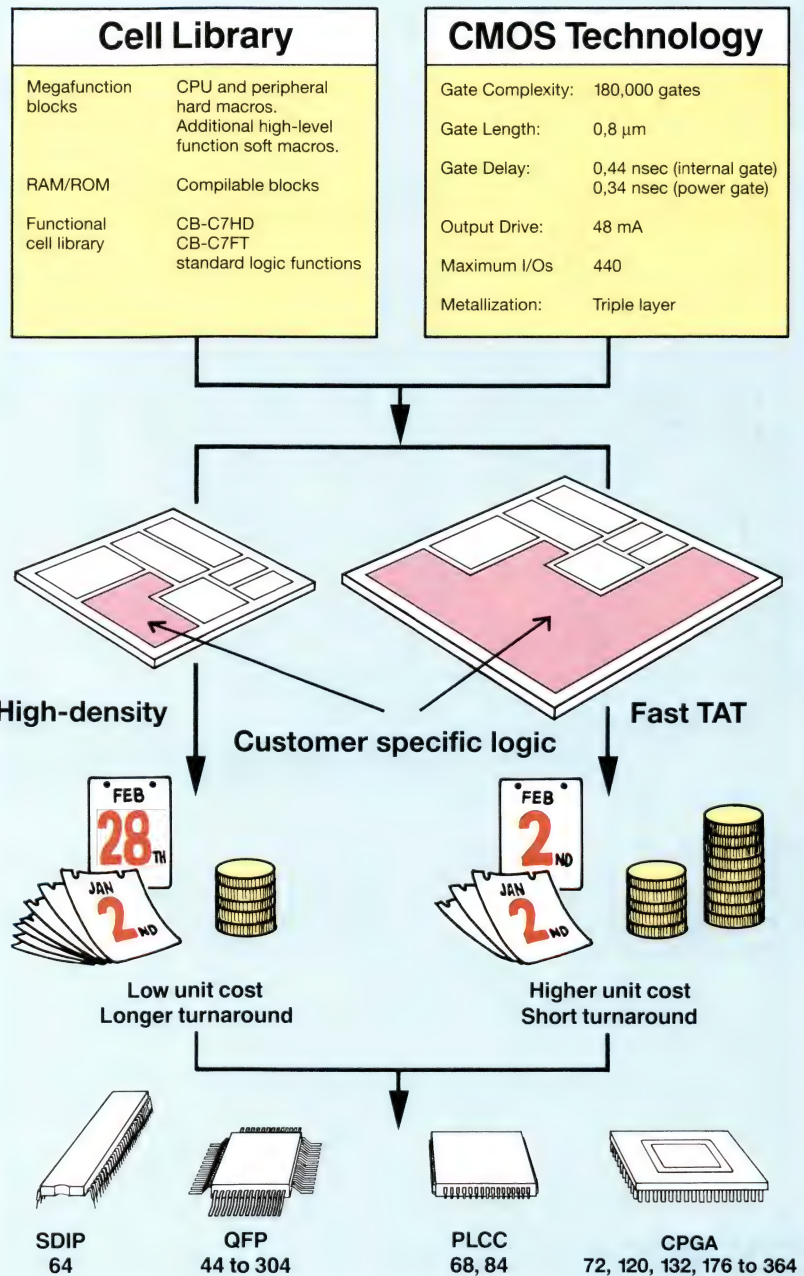
Both the fast turnaround and low unit cost versions of CB-C7 ASICs feature the same high performance – so there are no compromises with either solution.

To match this performance, we have an equally impressive range of packages in which to house them. You can choose between conventional plastic DIPs, quad flat-packs, PLCCs and high pin-count plastic or ceramic pin-grid arrays. NEC's state-of-the-art packaging technology provides CB-C7 ASICs with maximum protection from their environment, ensuring their long-term reliability.

OpenCAD – flexibility in design

NEC OpenCAD gives you maximum freedom in the CB-C7 design process. Freedom to perform schematic capture using popular EDA software such as DAZIX, Mentor, Valid and VIEWlogic, on industry standard workstations from DEC, HP-Apollo, IBM and SUN.

After schematic capture, your design is completed by compiling RAM/ROM



blocks and optimizing user-defined logic. It is then floor-planned using ChipPlan, simulated with System Hilo or Verilog, and placed and routed using Cell-3 Ensemble. After post-layout simulation and design-rule checks, we pass pattern generation data to one of our wafer fabrication facilities in Japan, the USA or Europe.

To simplify your design task, logic optimization, simulation, and chip layout are normally carried out by a NEC ASIC design center on their SUN or DEC workstations. Providing access to NEC's Unified Design Environment – a suite of ASIC design tools which operate

under DEC PowerFrame system management software – these workstations ensure a simple user interface and smooth data flow from one design process to the next.

However, OpenCAD also gives you the flexibility to install part or all of the NEC Unified Design Environment on your own system, so that you can perform as much, or as little, of the CB-C7 design process as you choose.

NEC Unified Design Environment - A Framework for Right-First-Time Designs

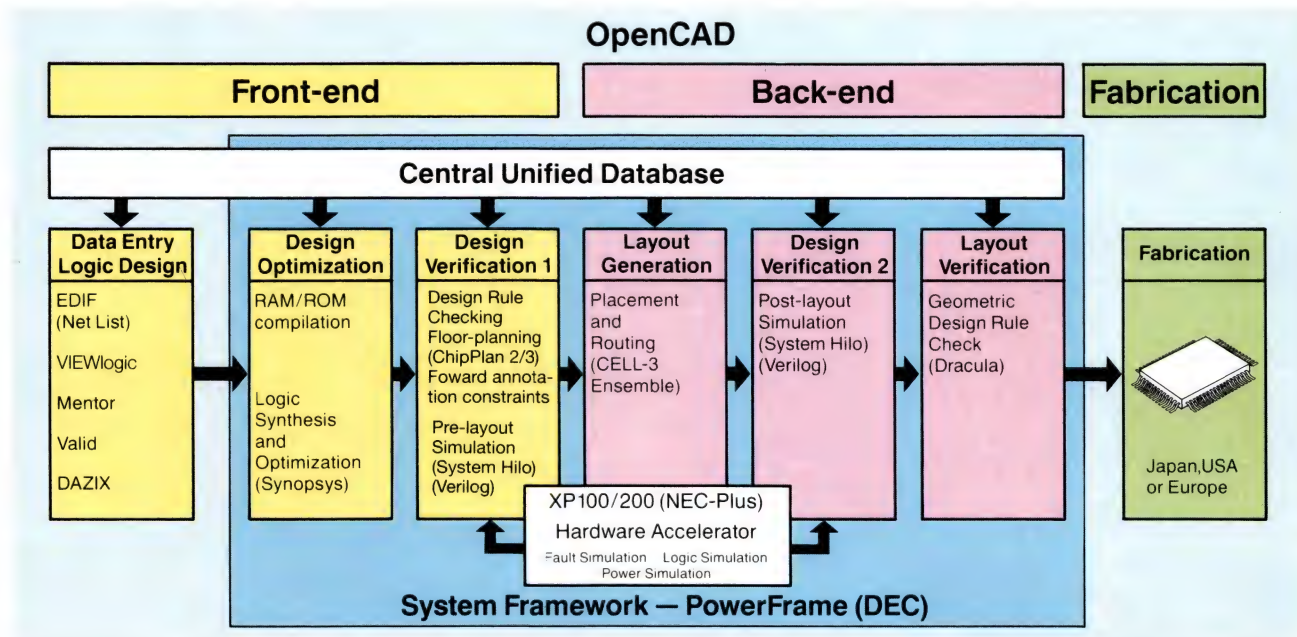
To handle the complexity of CB-C7 ASICs, and that of our next generation of ASIC technologies, we have taken some of the best ASIC design packages in the industry – such as VIEWlogic schematic capture software, Synopsys HDL compilers and logic synthesizers, Genrad System Hilo, and Cadence simulation,

layout and routing software – and integrated them into the NEC Unified Design Environment.

At the heart of this design system lies the NEC Central Unified ASIC Database – a technology independent database which allows us to automatically generate new simulation models as new

process technologies are introduced.

So with NEC, you not only get ahead, you stay ahead.



Wherever you are in the world, there is a NEC design center close enough to support you in CB-C7 ASIC design. If you are already using industry standard workstations and EDA software to

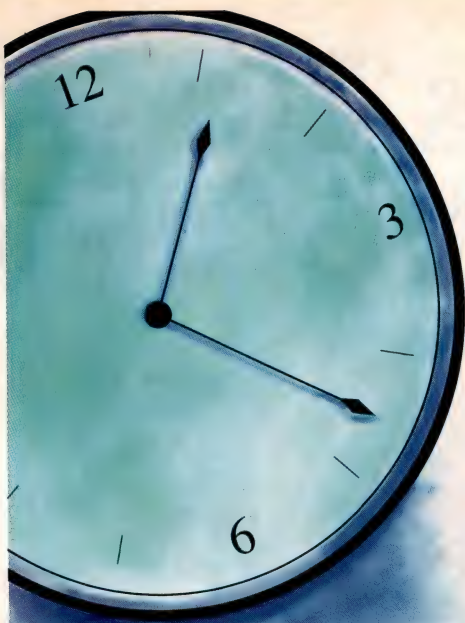
design ASICs, you probably have all the hardware and software design tools you will need. Simply install the CB-C7 ASIC libraries, and you can start on a CB-C7 design tomorrow.

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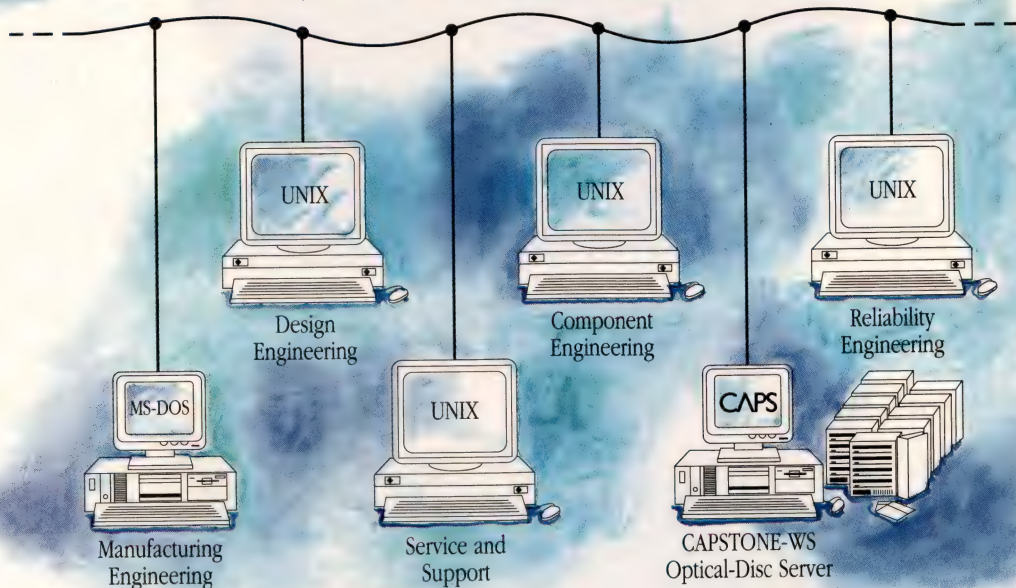
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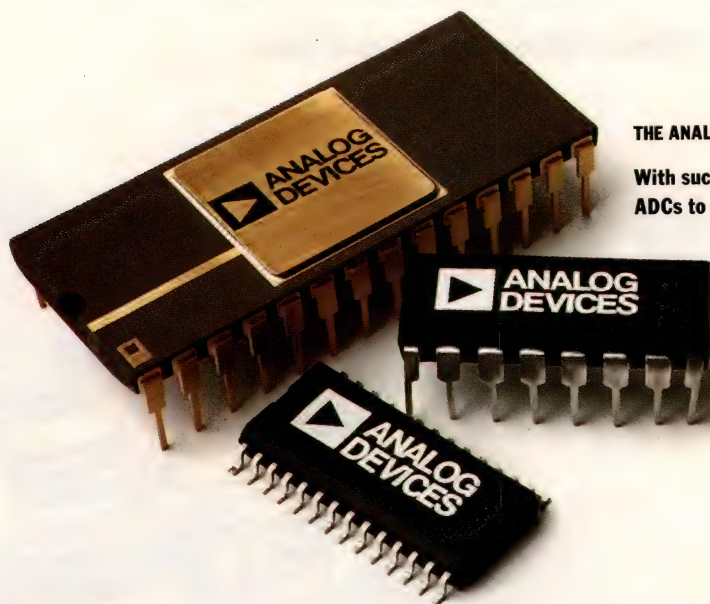
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Design for test

(without really trying)

Michael C Markowitz, Technical Editor





You have every reason to ignore test in your projects. Schedules make little or no allowance for the extra time design for test requires; in fact, shrinking product-development cycles give you less time to finish more complex projects. In addition, although design specifications occasionally include test metrics, management judges you by your ability to meet your specifications' demands on function and cost. The bottom line is that schedule, function, and cost are the standards management use to grade your performance. Test? "Oh yeah, make sure the manufacturing guys can test your designs."

Designers often cite performance and area penalties as the most vexing problem of design-for-test strategies. Unfortunately, as with most generalizations, these may be

Despite the dangers of ignoring testability, subtle costs can make designing an ASIC for test prohibitively expensive.

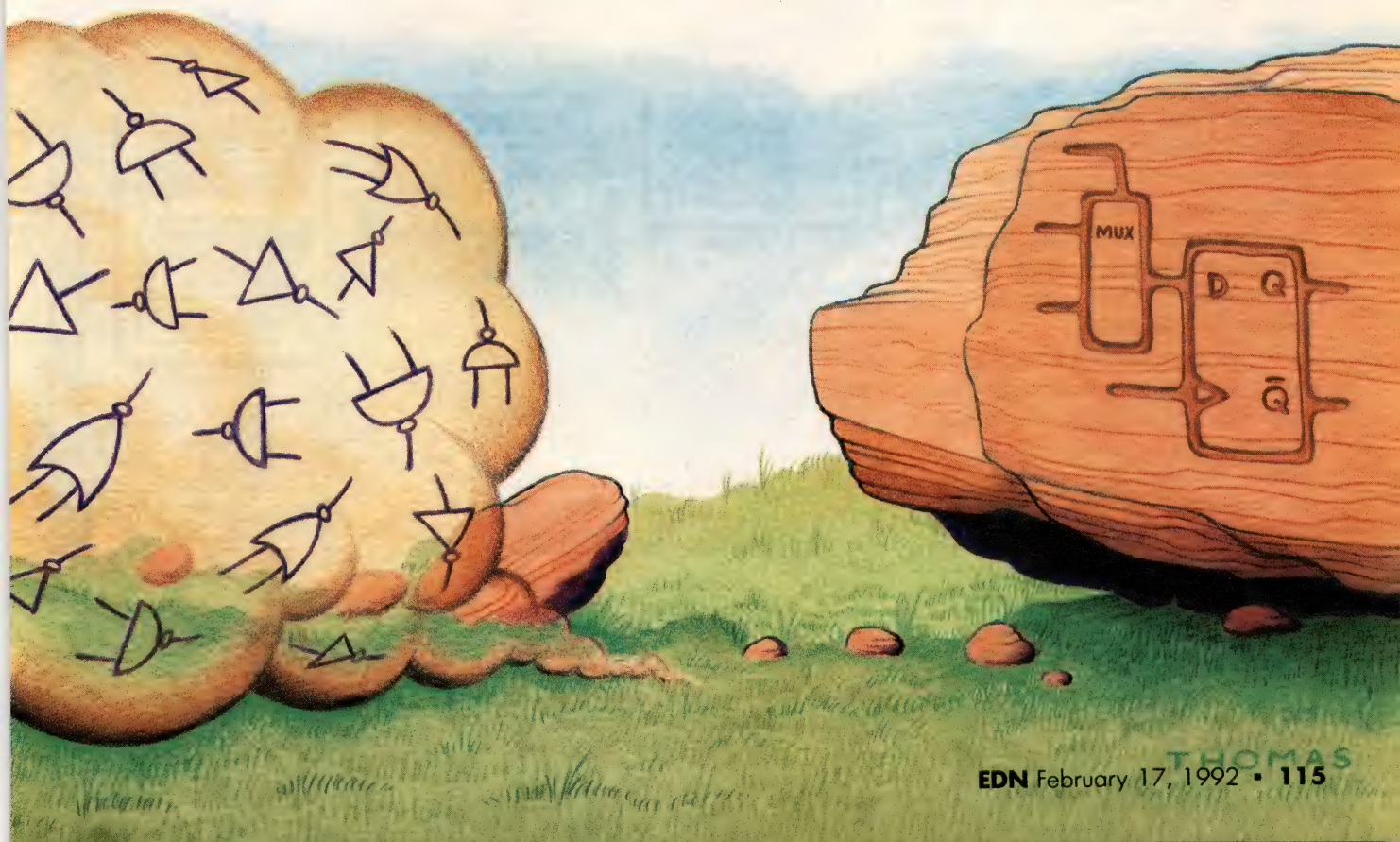
Testability tools provide construction techniques that lower the cost of designing for test.

untrue in specific cases. If you underutilize a gate array or design a pin-limited standard-cell circuit, then area shouldn't be an issue. And, although I/O requirements may prevent you from dedicating pins to testing, you may be able to multiplex test pins with functional ones. In fact, although the IEEE-1149.1 test port requires four dedicated pins, Toshiba, through its Vertex subsidiary, multiplexes signals to offer a test interface option

where you dedicate only one pin to test. The test pin internally selects between functional I/O and a pseudo-IEEE-1149.1-compatible test port. (IEEE-1149 was formerly known as the JTAG—Joint Test Action Group—specification.) Toshiba can't call its port IEEE-1149.1-compatible because a true IEEE-1149.1 *must* have four dedicated test pins.

Performance-impact fears can be an even bigger paper tiger. Many designers claim that their design is too close to the edge of the ASIC vendor's process capabilities. However, these designers forget that not every path is critical. Adding testability to less worrisome paths may not make your design fully testable, but the design will be more testable than it might otherwise be. In addition, several ASIC vendors, Toshiba among them, of-

Illustration by Rod Thomas





fer zero-delay scan latches, which don't rob time from your functional circuits.

Aside from designing smart, there are several ways your company can build testable circuits without specifically designing them that way. Over time, these testability enhancers will take as much control for design testability as you are willing to give them.

In addition to letting your company test your designs, many design-for-test (DFT) strategies offer a side benefit. If the test strategy lets you control internal voltage levels, then you can also use the test circuits to set internal states and conditions. By defining a particular initial condition, you can analyze behavior and facilitate prototype or device debug. Strategies that provide internal observation points simplify evaluating the capability.

Perhaps the simplest approach to designing for test is to pass the responsibility off to your ASIC vendor. Many vendors, among them Gould AMI and Fujitsu, provide transparent test as an internal service. You'll pay for the privilege, however; the vendors will add the cost of making your designs testable to your NRE. And the service isn't entirely transparent; you must recheck the vendor's simulation results to ensure the inserted testability doesn't impact your design's timing specifications.

In general, commercial testability tools fall into two broad categories. One group physically changes your design by adding logic, scan chains, or testability enhancers such as built-in logic-block observers (BILBOs) or test matrices. In contrast, the other type of tool accepts your design and creates test patterns to evaluate it.

Of those test schemes that modify your design, the Crosscheck approach is the most innovative and

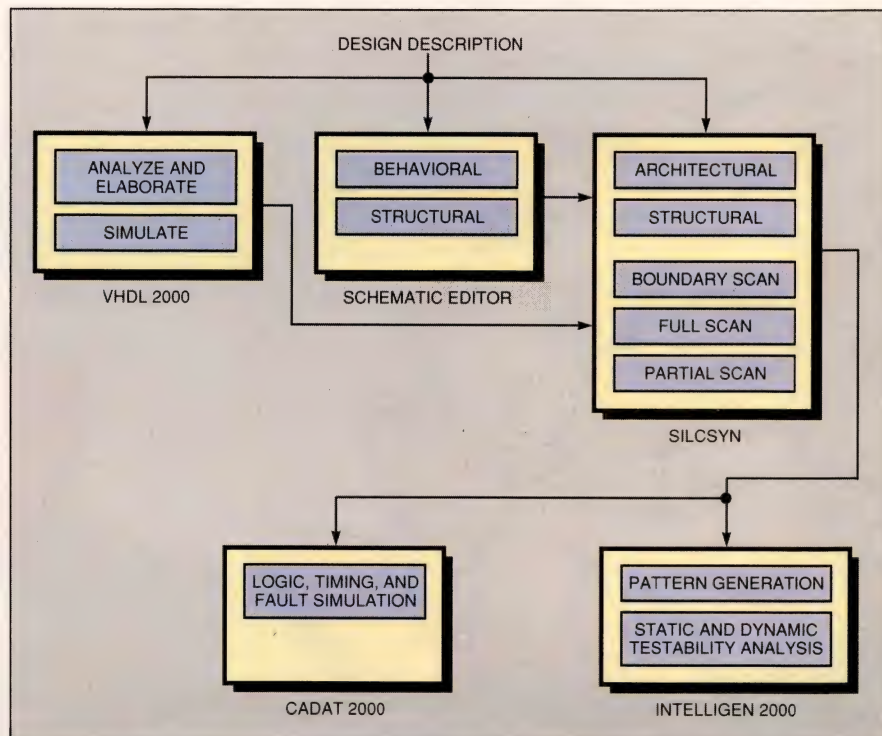
seems to least affect performance. The approach, available to ASIC designers only through Crosscheck licensees (Fujitsu, Harris, LSI Logic, NEC, Oki Electric, Raytheon, and Sony), provides observability at most every node in your design by adding minimum-sized p-channel transistors.

Using Crosscheck's approach, you design your circuits using library cells that appear and function as conventional cells; the ASIC vendor has already incorporated the additional p-channel transistors into the cells. According to Nitin Deo, applications engineering manager at Fujitsu, and Cliff Vaughan, strategic marketing manager at Oki, the parasitic capacitance of these transistors might add 2 to 3% to propagation times—though long p-channel transistor stacks, such as those in a 4-input NAND gate, may suffer a delay penalty of 6%. In contrast, both John Defalco, manager

of programs, design support, and business development of Raytheon's Microelectronics Center, and Farzad Zarrinfar, product marketing manager at LSI Logic, say that their companies' implementations are nominally faster. Their approaches beef up the p-channel devices to compensate for the additional capacitance, and these larger transistors provide faster switching.

The embedded-matrix approach requires adherence to several minor design rules: the design can't rely on stored charge, and internal free-running oscillators must allow initialization to a known state.

Where the approach exacts a bigger price is in its 4-pin test bus. The bus, compatible with IEEE-1149.1, provides a means for serially shifting the node data off the chip for comparison with "good" data. The 4-pin test bus and the additional observability transistors combine to claim an area penalty



Test functions you insert using Racal-Redac's Vision framework and tools include function- and test-logic synthesis and pattern generation.

Don't test my circuits

Many engineers still misunderstand the purpose of design for test, according to Scott Creekbaum, senior engineer at AT&T's Santa Clara Design Center. Too often, Creekbaum sees designers who get defensive when they are asked to design for test. These designers know that their circuits are good.

No ad-hoc or structured test approach tests or guarantees your design's function. You or your design team are the only ones who can attest to the goodness of your design. You reach this conclusion via extensive simulation, breadboarding, and functional testing of the design.

In contrast, design for test starts with a fundamental

assumption: *The design is good.* Design for test then seeks to qualify the *manufacturing* of the design. In fact, a more appropriate name might be designing to test manufacturing.

Since testing a device requires control and observation of internal logic states, design for test aims to provide it. Using this access, the test seeks to answer such questions as: Are any of the nodes stuck high or low? Does the particular device under test have any opens or shorts? Do signals take too much time to make the transition between voltages? Does the design sink and source reasonable amounts of current? Finally, does the device initialize properly and consistently?

of 30% in lost raw gates on small designs and closer to 20% on larger ones.

What does it cost?

This area penalty may not translate into significantly higher dollar costs. Although several of the licensees will charge a premium for designs that use this test approach, this premium may be deceptive. You can offset the higher charges with savings in test-program development and debug time for circuits without DFT or the additional time to manually design in test.

Currently, the Crosscheck approach offers only massive observation of internal nodes. Toward the middle of this year, the company will introduce a capability to provide control of flip-flops as well.

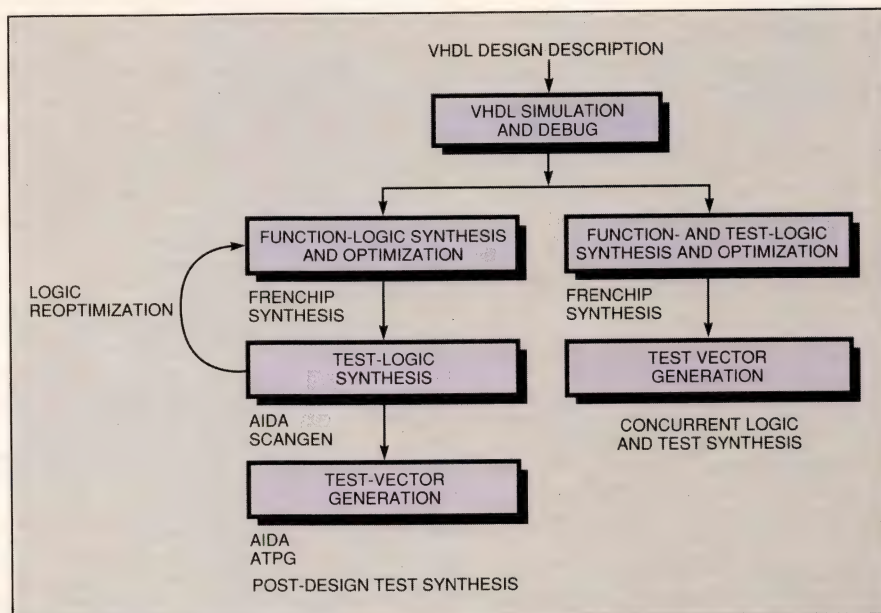
A more common design-modification approach is scan substitution. This approach changes your design by replacing all or most of your non-scan flip-flops with scannable ones. In effect, the scan philosophy converts a sequential logic design into a multitude of combinatorial ones. In these scan designs, each combinatorial circuit contains paths of combinatorial logic terminated by one storage element. Scan then

builds a mechanism to shift data serially to and from each of the storage elements so each storage element acts as a primary input or output to its combinatorial circuit.

Many of the transparent test-synthesis tools offer this scan-insertion capability. Among the tools are Intergraph's Testsyn, Philips' Locam, Racal-Redac's Silcsyn Test Synthesis, Sunrise's Testgen, Synopsys' Test Compiler,

and Teradyne's Frenchip Synthesis. The tools offered from Intergraph, Philips, and Teradyne were developed for internal use (AT&T developed Scan Test and Dassault Electronique developed Frenchip Synthesis) and are being marketed externally to help defray costs.

Two features help distinguish among these scan-test tools. First, designers looking for push-button test insertion will have to push sev-



Post-design test insertion requires evaluating the impact of the added test on your design. Teradyne recommends specifying the test structures from the start.



eral buttons. For example, you insert scan using Test Compiler after synthesizing your logic, but before you optimize the design. Test Compiler does generate test patterns, though, so you needn't run a separate pattern generator. Testsyn inserts the scan chains and generates patterns after synthesis and optimi-

zation. In contrast, Locam and Silcsyn Test Synthesis insert the test logic into the design during synthesis, but neither generate patterns; optional tools from the vendors perform that function.

A third alternative is Testgen, which like Testsyn, is a test-insertion tool rather than a test-synthe-

sis tool. Testgen accepts a "test budget," consisting of acceptable performance and area penalties. Using these design constraints, the software swaps some flip-flops for scan-flops and generates patterns to test the circuit. The tool performs no logic optimization.

Rigorous application of scan

Table 1—Test-logic insertion tools

Company	Product	Function- and test-logic optimization	IEEE-1149.1-controller/multiple internal scan chains/multiple clocks	Input/output formats ¹	Inserts BIST ² /multiplexed isolation	Cost (availability)	Transparency
Compass Design Automation	Test Assistant	Yes	Yes/yes/yes	Schematics, EDIF, VHDL, Verilog	Yes/yes	\$60,000 (now)	Separate operation. Tool generates patterns.
Dazix	Testsyn	No	No/yes/yes	VHDL, Verilog, C, EDIF, Dazix Netlist/VHDL, EDIF	No/no	\$25,000 (2Q '92)	Separate operation.
	Pyramid	No	No/yes/yes	VHDL, Verilog, EDIF, TDL	Yes/yes/no	\$25,000 (2Q '92)	Separate operation.
GEC-Plessey Semiconductor	Gatemap	Yes	Yes/no/no	EDIF or truth table/EDIF	No/no	\$25,000 (now)	Inserts scan chain during synthesis of function logic. Separate tool adds BIST.
LSI Logic	Test Builder	No	Yes/yes/yes	VHDL, EDIF, NDL	Yes/no	\$80,000 (now)	Separate operation. Tool tests megafunctions using multiplexed isolation with your guidance.
Phillips Electronic Design and Tools	Locam	Yes	Yes/yes/yes	EDIF, VHDL, Ella/EDIF, VHDL, Mentor schematic	No/no	\$30,000 (now)	Inserts scan chain during synthesis of function logic.
Racal-Redac	Silcsyn's Test Synthesis	Yes	Yes/yes/yes	VHDL, Silcsyn EDIF, Cadat, Visula/VHDL, Cadat, EDIF, NDL	Yes/no	\$54,000 (March '92)	Test logic is synthesized with function logic.
Sunrise Test Systems	Testgen	No	No/yes/yes	TDL or NDL Netlist, Verilog/TDL or NDL Netlist	No/no	\$95,000 (now)	Separate operation. Tool accepts user-guided "test budget." Generates vectors.
Synopsys	Test Compiler	Yes	Yes/yes/yes	Verilog, VHDL, Netlist, schematic, Boolean equations	No/no	\$40,000 (now)	Separate operation. Generates test vectors.
Teradyne EDA	Frenchip Synthesis	Yes	Yes/yes/yes	VHDL, espresso/VHDL, and netlists in several formats	Yes/no	\$75,000 (now)	Test logic is synthesized with function logic.

Notes: 1. EDIF=Electronic Design Interchange Format, VHDL=VHSIC Hardware Description Language, NDL and TDL=proprietary description languages.

2. BIST=built-in self test.

methods requires integration of all storage elements into the scan chain. The other distinguishing feature of some of the test insertion tools is their ability to build partial scan into designs. Testgen, Silcsyn Test Synthesis, and Frenchip Synthesis all allow partial scan. In fact, each of these tools will choose which storage elements to include in the scan chain based on the software's assessment of efficacy. The pattern-generator partner of these tools will recognize and create high-coverage patterns.

Although Testsyn, Test Compiler, and Locam are full-scan-based tools, they don't force you to trade all storage elements for scannable ones. You can protect portions of your circuit from these tools to ensure timing, area, or logic isn't changed. The downside of protecting sections of your circuit from full-scan-based tools is that the pattern generators can't assure testability.

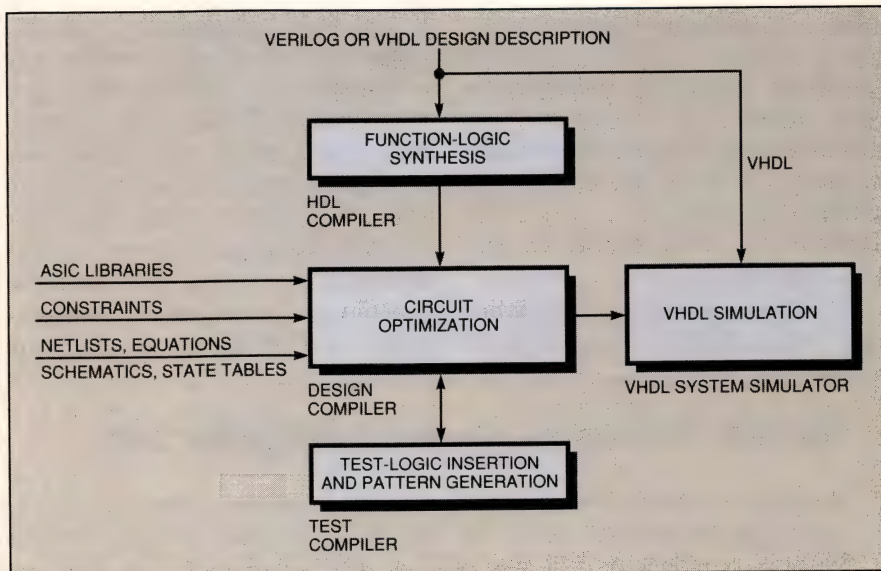
Beyond full- and partial-scan-based tools, several tools can create modules that self-test function blocks. Function blocks that par-

Beginning with either Verilog HDL or VHDL, Synopsys' test strategy is to first synthesize and optimize your function logic, then insert the test logic and generate patterns.

ticularly lend themselves to built-in self-test (BIST) contain highly regular structures and include memories and data paths. LSI Logic's Test Builder includes a module that generates BILBOs for memories. The BILBOs are the logic that perform and grade BISTs. Modules within Compass's

Design Assistant let you generate BILBOs for memories, data paths, multipliers, and circuits of your own design. Frenchip Synthesis also offers BILBO generation for your circuits.

One other design-modification method for test insertion is multiplexed isolation. As the name im-



You can design for test, if you want

Some designers do design for test. If you want to design for test, beyond the tools discussed in the article, you have several ways to do it. Your choices range from manually inserting control and observation points into the design to using test-analysis tools.

Test-analysis tools can be bundled with the test-insertion or pattern-generation tools or they can be offered independently. Among the bundled tools are an analyzer that comes with Teradyne's Aida pattern generator. This tool examines your design against 24 internal rules to let you know whether pattern generation will be successful. Similarly, the AT&T scan-insertion tools, which Dazix, an Intergraph Co, incorporates into its own tool set, performs a design audit looking for testability design-rule violation.

Going a step beyond the rule-checking capability, several tools actually analyze your design. Since Racal-

Redac's Silcsyn Test Synthesis, Sunrise's Testgen, and Teradyne's Frenchip let you constrain the "scannability" of your design, they include analysis capabilities that try to select the most efficient storage elements to include in the scan chains.

Both Dazix and Teradyne also offer independent tools to assist you in choosing test schemes or in selecting control or observation nodes. Dazix's \$5000 Pioneer tool is a rule checker that assures your design is suitable for the company's pattern-generation tools. Although Teradyne's \$50,000 Lasar is primarily a board-design or system-design tool, you can use it to design your ASICs. The software contains two utilities that rank internal nodes based on their control and observation efficacy. When you select a node to make a primary input or output, the software regenerates the list to account for dependencies.



plies, this technique uses multiplexers to provide access to functional blocks or megacells embedded in your design. Via this access, you can independently test these blocks without the effect and influence of peripheral circuits. Only Test Builder and Test Assistant offer this capability.

If you are reluctant to let anyone or anything modify your design, or

if you want to generate test patterns for a circuit after running any of the test-logic insertion tools, you have several choices. One general note about using commercial pattern generators though: Talk to your ASIC vendor before you make a big financial commitment. Automatically generated test patterns are much like simulation results—ASIC vendors insist on qualifying

the models and tools you use to generate them.

Developing test patterns to test strictly combinatorial circuits is relatively easy. So, by extension, is developing test patterns to test full-scan-based circuits. Developing patterns to test circuits with sequential logic is far more complex because the software must move data through storage elements to

The top-10 reasons you don't design for test

At a panel session on the acceptance barriers confronting design for test and built-in self test (BIST), Richard Sedmak, president of Self-Test Services ((215) 628-9700), presented a list of reasons designers don't design for testability. With apologies to David Letterman, we have adapted that list here.

10) There is no push-button answer to designing for testability. And everyone knows how much engineers like to push buttons.

9) Test requirements are usually poorly defined. Failure of the marketing people to put a specification for testability into the statement of work makes it easy for you to meet it.

8) Little or no communication occurs between the design, manufacturing, and service organizations. When you don't know the sort of problems that arise after your designs reach the production floor and ultimately, the customer, you can't improve subsequent iterations.

7) Companies don't do a good job of tracking manufacturing defects and field failures. You aren't the only one who doesn't know what happens once designs leave your hands.

6) Your company has no life-cycle cost-of-test model. Because the company has never tracked the impact of failure to test over the life of a product, the company can't make informed tradeoffs about the up-front cost of designing for test versus the back-end cost of ignoring it.

5) The testing crisis within your organization hasn't reached a critical level. Your company hasn't yet had to recall a high-impact product and placate angry customers because of a design or component problem that test failed to catch.

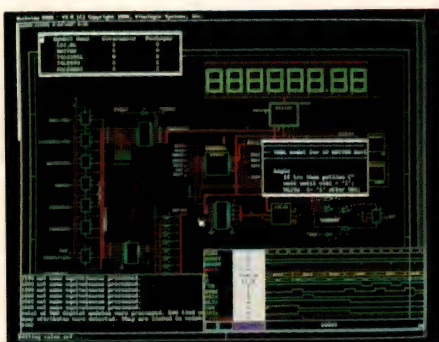
4) Management has no *real* commitment to test. Oh sure, everybody says that test is important. But how do they spend their money? Has your company devel-

oped life-cycle cost-of-test models? Does the testability of your projects influence your raises and promotions? 3) Schedules and budgets make no allowance for increased testability. Because there are no real transparent methods, making a design testable takes time and costs money.

2) Adding testability steals precious nanoseconds from performance and demands high real-estate penalties. This is probably the most common excuse to avoid testability and the most specious. Most designers who do design for test say performance and area impacts aren't design killers. All paths are not critical. You can provide control to and observation of nodes near, but not on, the critical path. Real-estate costs are a function of your chosen testability scheme, the complexity of your design, and the technology you choose for building it. If you're using 50% of a large gate array, for example, adding scan-based testability will lower yield and will appear to cost you pennies. Ultimately, though, you'll save money through reduced failures in test or in the field. In contrast, if you've decided to implement a register-oriented design in a small, highly utilized gate array, adding scan could force you into a larger array and cost substantially more.

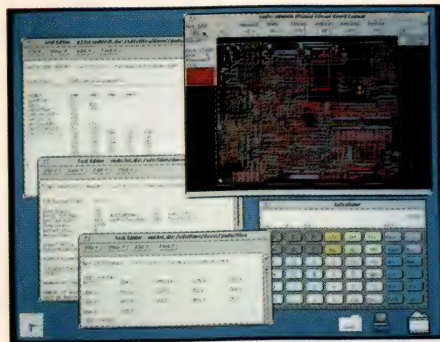
1) You are rarely rewarded if you do design for test and seldom penalized if you don't. If adding testability forces you to slip your schedule, are you praised for adding test or punished for slipping the schedule? Do your gate budgets include an allowance for test? If adding test forces your design into a larger gate array, would your company add the test logic, remove some of the design's function, or keep all the function and shoe-horn a little bit of test logic into the smaller array? Are you promoted based on how easy your designs are to test or on how well your devices meet performance specifications?

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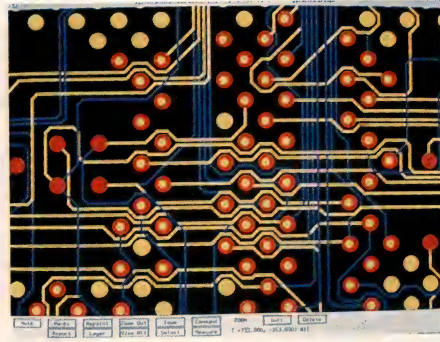
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reach primary inputs and outputs. (Ref 1 is a very good, detailed explanation of the theoretical underpinnings of test-pattern genera-

tion.) The maximum distance, measured in number of storage elements, between any storage element and a primary input or output

is the circuit's sequential depth. Although you may exclude storage elements from a scan chain, full-scan-based pattern generators can

Manufacturers of transparent-test design tools

For more information on transparent-test design tools such as those described in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you saw their products in EDN.

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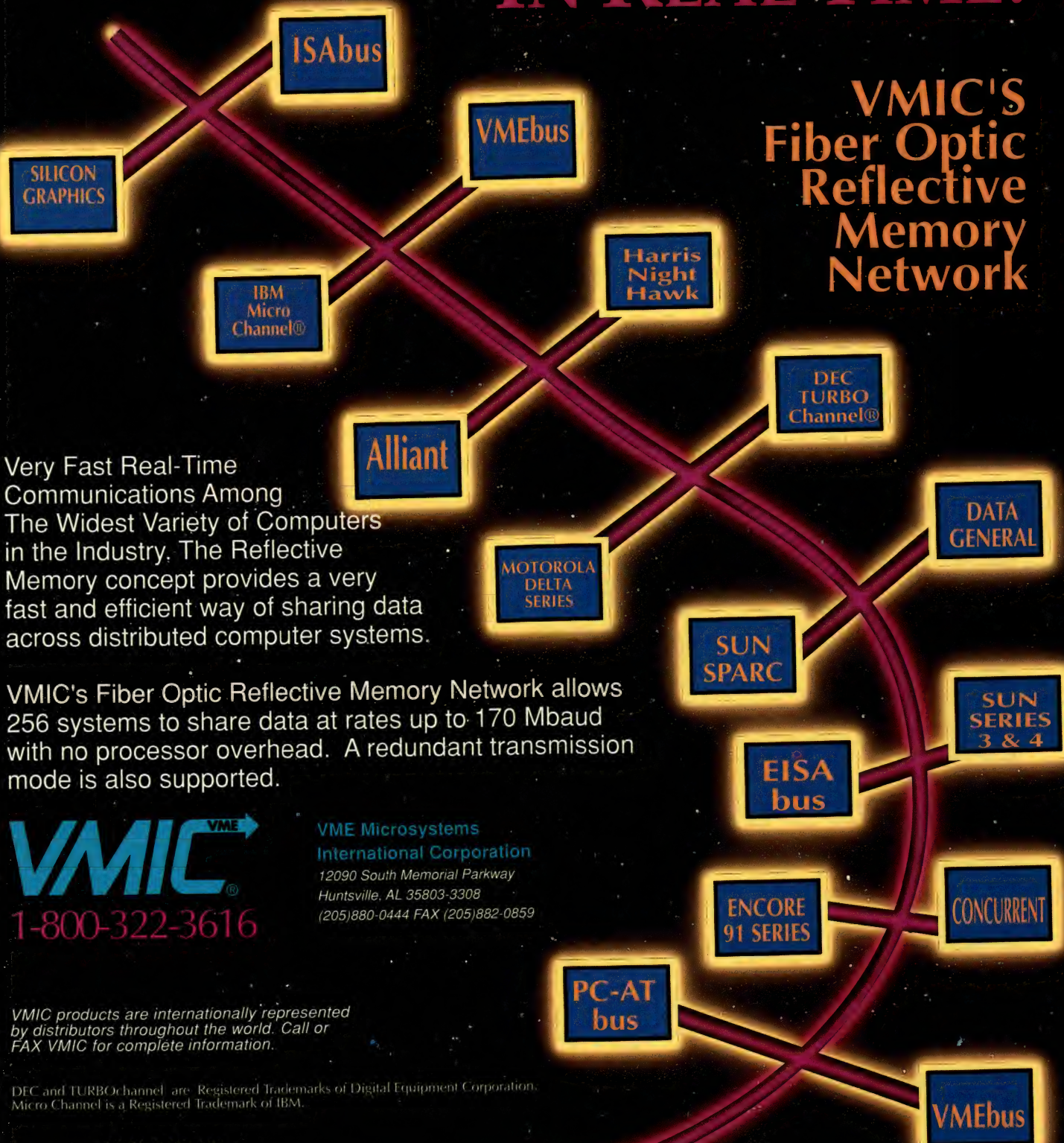
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DESIGN FOR TEST



only generate high-coverage patterns for circuits whose sequential depth is 0.

Some tools want to be alone

Several pattern-generation tools work with logic-synthesis tools. In fact, test-synthesis tools Testsyn and Test Compiler, both full-scan tools, include pattern generators as integral parts of their capabilities. Several other pattern generators don't assume or require any synthesis.

In addition to Testgen, which can swap storage elements for scanable ones based on a user-defined budget before creating patterns to test the design, Racal-Redac's Intelligen automatic test-pattern generator (ATPG) is coupled with the company's function-and test-logic synthesis tool. As a result, you can feed data between the tools to trade off area, speed, and testability. You

can also use the tools independently of logic synthesis to create patterns.

Other pattern-generation tools, such as Expertest's Test Design Expert, Adas's Test Pattern Generator (TPG), and Teradyne EDA's Aida ATPG Toolkit operate independently of synthesis tools. Like pattern generators that work with synthesis tools, these tools may require you to adhere to a particular design style. For example, the Aida ATPG Toolkit does not generate patterns for sequential designs. In contrast, both Adas's TPG and the Test Design Expert will generate patterns for designs ranging from fully synchronous to asynchronous. (Mentor distributes the Adas TPG software via a nonexclusive marketing agreement.)

While the ASIC vendors must qualify automatic pattern generators for mask-programmed devices,

you have greater flexibility in using pattern generators for user-programmed devices, such as PLDs, PLAs, and FPGAs (field-programmable gate arrays). Generally, as long as you can accurately model and present the actual implementation of your design to the pattern generators, you can use any automatic pattern generator to create test patterns for these devices. You also have a lower-cost alternative. Acugen's test pattern generator, the least expensive software listed in Table 2, is specially written for user-programmable devices.

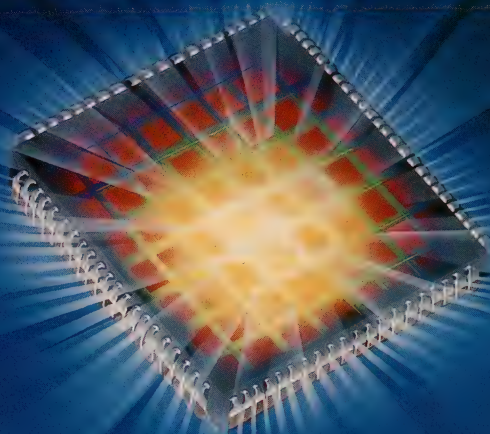
You can use many of the available tools to build testable circuits without designing for testability. On the other hand, as good engineers, you should know that truly transparent test is really an illusion. No tool operates in a vacuum. You can't trust any of the tools to do your job for

Table 2—Test-pattern generators

Company	Product	Direct or control synthesis	Supported design methods	Generate sequential-scan patterns	Cost (availability)
Acugen Software	Acugen	No	PLAs, PLDs, FPGAs ¹	No	\$2000 (now)
Adas Software	Adas TPG	Via optional scan-flop substitution	All	Yes	\$100,000 (early '92)
AT&T	Gentest	No	All	Yes	\$150,000 (May '92)
Compass Design Automation	Scan Test ATVG and Star	No	LSSD ² and multiplexed flip-flop for scan	No	\$40,000 (second quarter)
Dazix	Picasso	No	All	Yes	\$120,000 (second quarter)
Expertest	Test Design Expert	No	All	Yes	\$140,000 (now)
	TDX-130	No	All	Yes	\$100,000 (now)
LSI Logic	SATPG	No	Synchronous design	No	Included with test builder
Philips Electronic Design and Tools	Panther Cub/Sprint	No	Scan and LSSD	No	\$30,000 (now)
Racal-Redac	Intelligen	Yes	All	Yes	\$127,000 (now)
Sunrise Test Systems	Testgen	Yes	Works with most scan techniques	Yes	Included with test-logic insertion tool
Synopsys	Test Compiler	No	Supports several scan methods	No	Included with test-logic insertion tool
Teradyne EDA	Aida ATPG Toolkit	No	Scan	Yes	\$90,000 (now)

Notes: 1. FPGA=field programmable gate array.
2. LSSD=level-sensitive-scan design.

Finally, FPGAs designed for both kinds of engineers.



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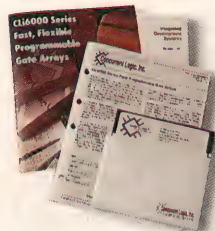
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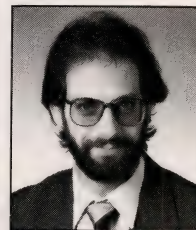
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you. Even if you use the tools to add test to your design, make sure you check the final design against your specification. **EDN**

References

1. Miczo, Alexander, *Digital Logic Testing and Simulation*, Harper and Row, New York, 1986.
2. Markowitz, Michael, "Software adds logic to make designs testable," *EDN*, October 11, 1990, pg 59.



Mike Markowitz, Technical Editor, can be reached at (617) 558-4743; FAX (617) 558-4470.

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CIRCLE NO. 64

Designer's guide to
measuring op-amp distortion
PART 1

Op-amp distortion measurement bypasses test-equipment limits

Jerald Graeme, Burr-Brown Corp

Part 1 of this 2-part series introduces the theory involved in measuring the low distortion levels of state-of-the-art op amps. It also provides simple methods for characterizing some low-distortion op amps.

Until recently, distortion performance was not important in most op-amp applications. Now, common use of the fast Fourier transform (FFT) extends the importance of op amps' distortion beyond audio applications into general signal processing. Any distortion introduced by an amplifier produces erroneous Fourier components. To predict these error components, you must first characterize your op amp's distortion. But op amps' distortion performance often surpasses that of available test equipment, defying characterization. Making the amplifier-under-test part of the test system solves this characterization problem. This solution works exclusively with feedback amplifiers, op amps included.

Feedback reduces an amplifier's distortion—at its output—to minuscule levels. Feedback also separates the amplifier's distortion from the test signal. This separated distortion is none other than the error signal fed back to the op amp's inputs. Once separated, the amplifier-distortion signal is insensitive to any distortion in the incoming test signal. Also, the separated signal has a reduced magnitude that reduces the dynamic range your test equipment has to handle.

Three distortion-measurement methods capitalize on the signal-separating action of op-amp feedback. In the

first method, you measure the separated signal directly. This method circumvents test-equipment limitations. In the second method, selectively amplifying the amplifier's distortion raises this error signal above the threshold of the test equipment. Finally, the third method removes the test signal yet avoids measuring any effects of the added amplifier. This method bootstraps the op amp's power supplies on the test signal itself to remove the test signal from the measurement. Part 1 of this series covers direct measurement and selective amplification; Part 2 covers selective amplification and bootstrapping.

Each approach greatly improves distortion resolution but also has specific constraints. Signal separation adds an amplifier to the test system; selective amplification reduces the measurement bandwidth; and bootstrapping requires using a signal to drive the reference point of the op amp's power supplies.

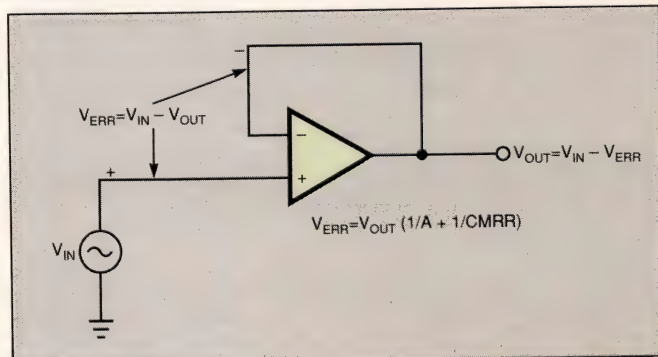


Fig 1—Feedback separates an op amp's distortion products from the test signal by developing a signal V_{ERR} equal to the difference between input and output signals.

MEASURING OP-AMP DISTORTION

Noise seldom limits op-amp-distortion measurement. Only in very low-distortion op amps does noise impose a limit on distortion analyzers. Amplifier noise is almost never a problem for spectrum analyzers because they are highly insensitive to noise.

Translate to ground

First consider how feedback separates the amplifier-distortion products from the test signal. This consideration is fundamental to each of the measurement circuits that follow. You can visualize the signal separation most easily with a voltage follower (Fig 1). In Fig 1, input signal V_{IN} drives the op amp's input to produce output signal V_{OUT} , and a simple loop equation shows that

$$V_{OUT} = V_{IN} - V_{ERR},$$

where V_{ERR} is the differential-input error signal of the op amp.

As trivial as this equation seems, it holds the answer to measuring op-amp distortion with high resolution. The equation states that the output signal, V_{OUT} , is a replica of the input signal, V_{IN} , except V_{OUT} does not include the input error signal V_{ERR} . Thus, any distortion the amplifier introduces is in V_{ERR} .

Measuring V_{ERR} instead of V_{OUT} removes any effects of signal-generator distortion and reduces the dynamic range required of your test equipment. The op amp's open-loop gain and common-mode rejection attenuate whatever test signal remains in V_{ERR} .

Distortion measurement with Fig 1's setup requires additional processing of the signal V_{ERR} . Signal V_{ERR}

rides on the input signal V_{IN} . Consequently, any ground-referenced measurement of V_{ERR} still includes the test signal V_{IN} .

The instrumentation amplifier in Fig 2 references V_{ERR} to ground and increases the signal level presented to the analyzer. Finding a low-distortion instrumentation amplifier is easier than producing a better signal generator and a better signal analyzer. This instrumentation-amplifier alternative serves the measurement of intermediate levels of distortion in feedback amplifiers.

After measuring distortion using the setup in Fig 2, you must adjust your results. These adjustments transform the distortion percentage measured in V_{ERR} , $THD + N_M$, to the equivalent percentage present in V_{OUT} , $THD + N_O$. ($THD + N_M$ is the measured value and $THD + N_O$ is the corresponding output distortion and noise.)

$$THD + N_O = (V_{ERR}/V_{OUT})THD + N_M.$$

When using a spectrum analyzer, adjusting the THD result as you calculate it is the easiest way to go. Taking this tack necessitates two changes. THD expresses distortion as the ratio of the rms sum of the distortion products to the signal fundamental:

$$THD = \sqrt{(V_2^2 + V_3^2 + V_4^2 + \dots)} \times (100\%)/V_1.$$

Here, V_1 represents the fundamental component of the signal, and V_2 , V_3 , V_4 and so forth represent the distortion components. For the measurement shown in Fig 2, the magnitude of V_{OUT} substitutes for the fundamental V_1 to correct for the smaller fundamental signal present in V_{ERR} . Also, the harmonic amplitudes measured require adjusting to account for the gain they receive from the instrumentation amplifier. For this adjustment, divide the overall THD equation by the instrumentation amplifier's differential gain, A_{DIF} .

$$THD_{OUT} = \sqrt{(V_2^2 + V_3^2 + V_4^2 + \dots)} \times 100\% / A_{DIF} V_{OUT}.$$

For the unity-gain amplifier under test, subtraction obviously separates the op amp's distortion from the test signal. However, this condition is a coincidence unique to the voltage follower. In other op-amp configurations, the signal translation of V_{ERR} does not subtract the op amp's output from the input signal.

Fig 3 shows the generalized, noninverting, feedback configuration along with the equations relating V_{ERR} to V_{OUT} . Here, a feedback network attenuates the effect of V_{OUT} on V_{ERR} . Thus, the amplifier-distortion products reflected in V_{ERR} are smaller than those in V_{OUT} .

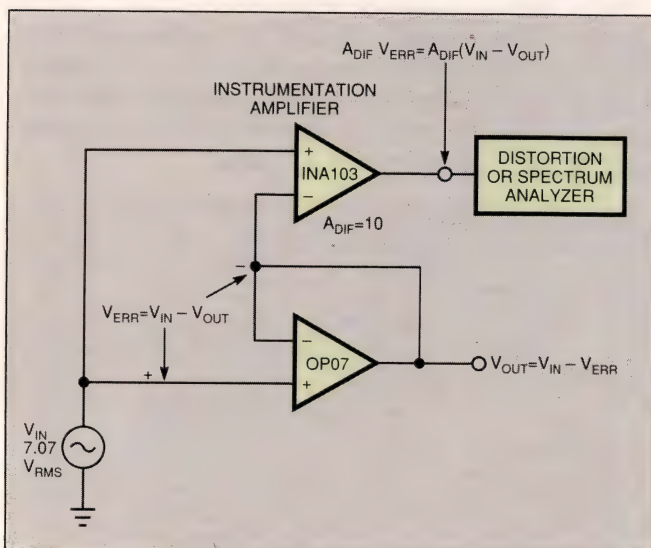


Fig 2—Directly implementing Fig 1's signal separation requires adding an instrumentation amplifier to provide a ground-referenced signal.

As before, you must separate the V_{ERR} signal from the common-mode test signal in Fig 3's circuit. The first method for this separation is translation to a ground-referenced signal (Fig 4). Distortion measurement with this configuration is easiest to see by considering the circuit to be an extension of Fig 2's voltage follower. In Fig 4, the voltage-divider action of the feedback network presents a signal $V_{OUT}R_1/(R_1+R_2)$ to the amplifier's inverting input. For the voltage follower, this signal was the full V_{OUT} . Now, the feedback signal is attenuated, and a simple loop equation shows that for Fig 4,

$$V_{ERR} = V_{IN} - (V_{OUT}R_1/(R_1 + R_2)).$$

Fig 4's circuit amplifies V_{IN} and its distortion in producing V_{OUT} . Thus, subtracting V_{OUT} from V_{IN} , as with Fig 2, would not remove the generator's distortion for Fig 4. However, subtracting an appropriately attenuated V_{OUT} from V_{IN} does remove this distortion. Fig 4 has a gain of $(R_1 + R_2)/R_1$. Then, feedback attenuates V_{OUT} by the *inverse* of this gain or $R_1/(R_1 + R_2)$.

For a distortion-analyzer measurement like that shown in Fig 4, first compensate the result for the smaller fundamental measured through V_{ERR} . Multiply the measured $THD + N_M$ result by V_{ERR}/V_{OUT} as before. This calculation yields the input $THD + N_{IN}$ result, which you then multiply by the $1/\beta = (R_1 + R_2)/R_1$ of the op amp's configuration.

$$\begin{aligned} THD + N_0 &= \frac{V_{ERR} (R_1 + R_2)}{V_{OUT} R_1} THD + N_M \\ &= \frac{R_1 + R_2}{R_1} THD + N_{IN}. \end{aligned}$$

You must also adjust your results for spectrum-analyzer measurements using Fig 4's setup. Once again, you discard the measured fundamental because

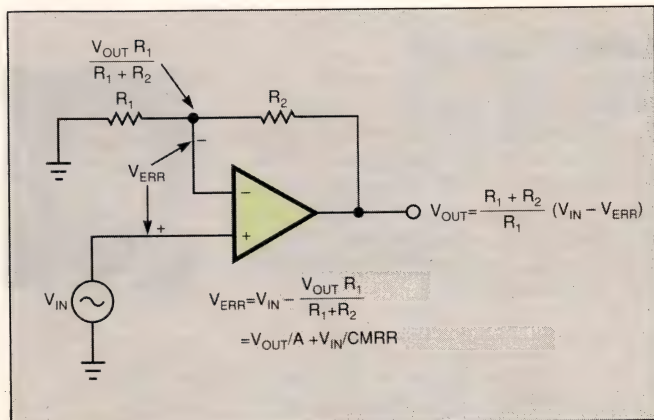


Fig 3—In the generalized feedback case, the output signal, along with its distortion, reflects to V_{ERR} through an attenuation.

it does not represent the output signal. Then, substitute V_{OUT} for fundamental amplitude V_1 in the THD equation and divide this equation by A_{DIF} to remove the effect of the instrumentation amplifier's gain. For Fig 4, also make a gain adjustment for the circuit's gain of $1/\beta = (R_1 + R_2)/R_1$.

$$THD_{OUT} = \frac{(R_1 + R_2) \sqrt{V_2^2 + V_3^2 + V_4^2 + \dots}}{R_1 A_{DIF} V_{OUT}} (100\%).$$

Signal separation extends to inverting case

For the generalized inverting amplifier, distortion resolution is even greater (Fig 5) than for the noninverting amplifier. The most significant improvement with inverting circuits actually results from removing the instrumentation amplifier of Fig 4. The inverting configuration of Fig 5 removes common-mode voltage from the op amp's input and avoids the added amplifier along with the added amplifier's distortion.

For the inverting circuit in Fig 5, the relationship between input and output distortion is not as obvious as with Fig 4's circuit. Previously, the feedback network relayed a large signal to the amplifier's input. But inverting circuits keep this input near zero voltage, balancing V_{IN} and V_{OUT} at the amplifier's input. Both signals influence the voltage at the inverting input through the feedback network. To find the result, consider the two signals separately using superposition. This exercises the feedback network as a voltage divider driven from each end. Then, the amplifier input signal is

$$V_{ERR} = \frac{V_{IN} R_2}{R_1 + R_2} - \frac{V_{OUT} R_1}{R_1 + R_2}.$$

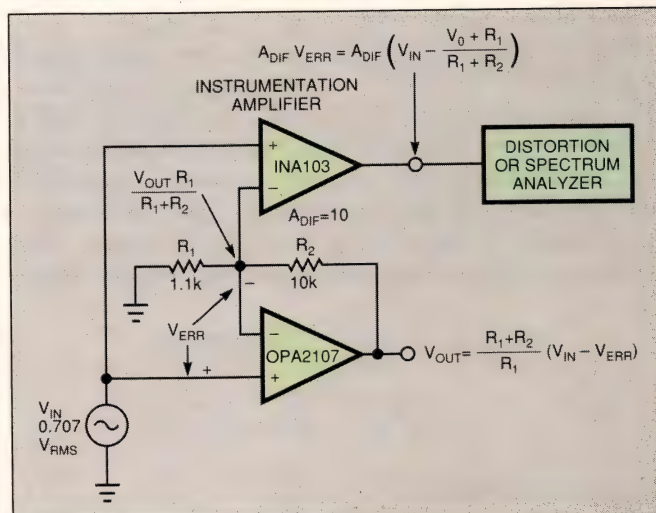


Fig 4—The amplifier's distortion products, included in V_{ERR} , remain separated from the test signal in measurements of the generalized noninverting circuit.

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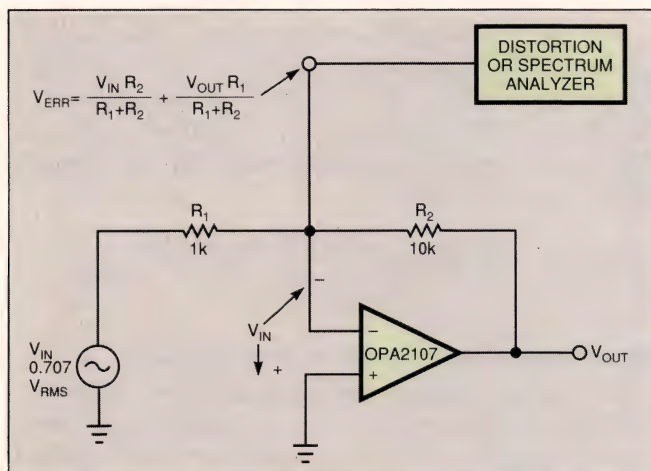


Fig 5—Inverting circuits also separate distortion and test signals. And these circuits obviate the previous measurement amplifier along with its distortion.

Although not immediately obvious, the distortion introduced by V_{IN} still cancels in this V_{ERR} signal. The above equation shows that signal V_{IN} influences V_{ERR} directly in the first term of the equation and then indirectly through feedback in the second term.

In the direct path, V_{IN} contributes to V_{ERR} through an attenuation of $-R_2/(R_1 + R_2)$. Added to this contribution is the V_{IN} component transmitted through V_{OUT} . In this path, V_{IN} and its distortion products first receive a forward gain of $-R_2/R_1$ to produce V_{OUT} . Feedback then attenuates V_{OUT} by a factor of $-R_1/(R_1 + R_2)$. The total gain of this path is the product of the forward gain and the feedback attenuation, or $R_2/(R_1 + R_2)$. This product has the same magnitude as the attenuation of the direct path above, but these two gains have opposite polarities. Thus, the direct and feedback distortion effects of V_{IN} again cancel in the V_{ERR} signal.

Fig 5's measured results require two adjustments to account for the THD_{OUT} of the amplifier's configuration. These adjustments follow directly from the Fig 4 results and use the same equations. One adjustment accounts for the smaller fundamental actually measured and the other corrects for the $1/\beta$ gain that the harmonics included in the measurement don't receive. For distortion-analyzer measurements using Fig 5's setup,

$$THD + N_0 = \frac{V_{ERR} (R_1 + R_2)}{V_{OUT} R_1} THD + N_M$$

$$= \frac{(R_1 + R_2)}{R_1} THD + N_{IN}.$$

And for spectrum-analyzer results,

$$THD_0 = \frac{(R_1 + R_2)}{R_1} \frac{\sqrt{(V_2^2 + V_3^2 + V_4^2 + \dots)}}{V_{OUT}} (100\%).$$

With no common-mode voltage, the inverting connection of Fig 5 provides no information about CMRR-related distortion. This result is desirable for applications having no common-mode signal, and the result proves useful even where such a signal is present. The absence of CMRR distortion in Fig 5 permits separating the gain- and CMRR-distortion effects.

First, a distortion measurement with the inverting circuit of Fig 5 yields the gain-related distortion, THD_A . Then, distortion measurement with the noninverting connection of Fig 4 provides the combined gain and common-mode distortion THD_{ACM} . Subtraction of the two THD results, in rms fashion, reveals the common-mode distortion (THD_{CM}). In equation form, this distortion is

$$THD_{CM} = \sqrt{(THD_{ACM})^2 - (THD_A)^2}.$$

The signal analyzer's loading at the op amp's summing junction also influences the measurement in Fig 5. Connecting the analyzer's input capacitance to this junction can affect both measurement bandwidth and frequency stability. Capacitance at the input of an op amp produces response peaking.

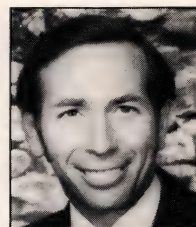
This capacitance reduces measurement bandwidth to no more than $f_p = \sqrt{(f_c / (2\pi R_2 C_1))}$. Here, f_p is the peak frequency, f_c is the unity-gain crossover of the op amp, and C_1 is the capacitance at the op amp's input. A bypass capacitor around R_2 counteracts the response peaking. For 45° phase margin, the value of this capacitor is $1/\sqrt{(2\pi R_2 f_c / C_1)}$. **EDN**

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Author's biography

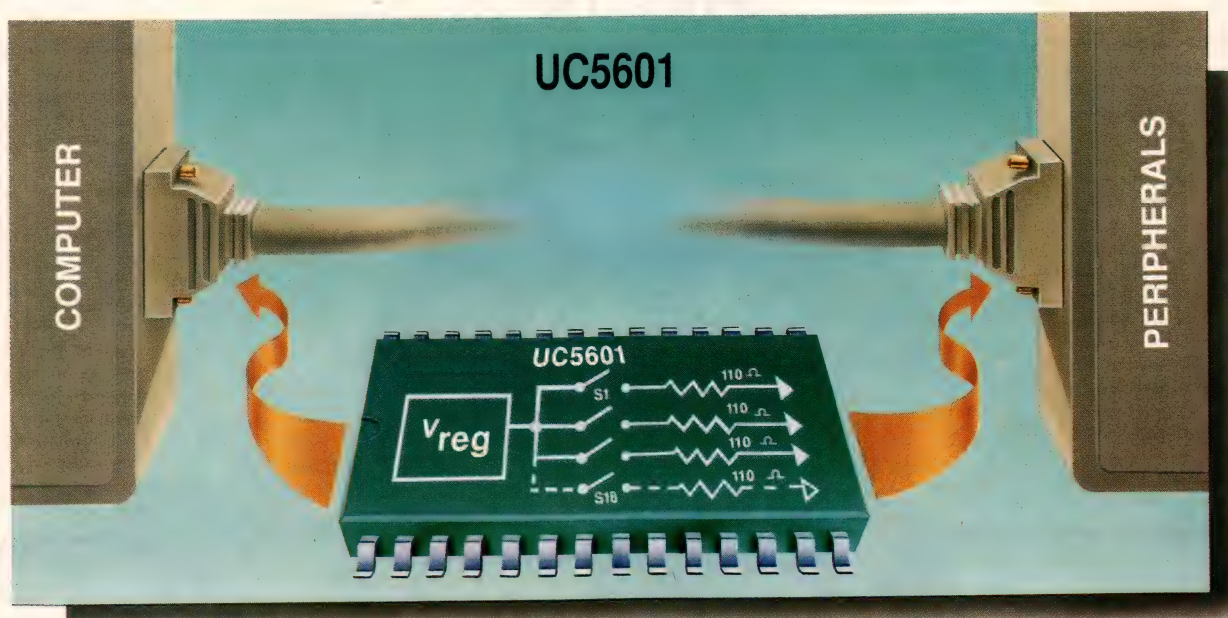
Jerald G Graeme is the manager of instrumentation-components design for Burr-Brown Corp in Tucson, AZ. Jerry directs a linear-IC-development group. He obtained a BSEE from the University of Arizona and an MSEE from Stanford University. His spare time interests include photography, scuba diving, and woodworking.



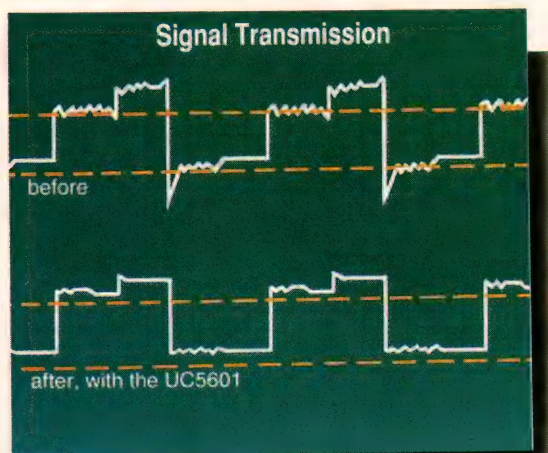
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Designer's guide to
measuring op-amp distortion
PART 2

Advanced techniques tackle advanced op amps' extremely low distortion

Jerald Graeme, Burr-Brown Corp

The second part of this 2-part series describes how to measure the distortion of more complex amplifier circuits and how to handle the highest-performance op amps.

Selective amplification offers an alternative to the added amplifier described in Part 1 of this series. This alternative moderates, rather than negates, the limitations of signal generators and signal analyzers. In addition to separating distortion and test signals, selective amplification makes the amplifier distortion signal dominant in the measurement; however, it also reduces measurement bandwidth.

As with signal separation, the selective-amplification approach is easiest to understand starting with a voltage-follower connection. Fig 1 shows a bootstrapped feedback network added to a voltage follower. In Fig 1, the common-mode rejection of the amplifier-under-test replaces the instrumentation amplifier used before. However, taking this tack moves the measurement back to the amplifier's output.

Resistors R_1 and R_2 form a feedback network that produces gain for V_{ERR} but not for V_{IN} . Signal V_{ERR} , which includes the amplifier's distortion products, appears across resistor R_1 . There, this signal produces a feedback current that goes to resistor R_2 . This operation develops an error-signal gain, $A_{ERR} = 1 + R_2/R_1$, for V_{ERR} alone.

Input signal V_{IN} does not experience this amplification because R_1 is bootstrapped rather than grounded. The resulting output signal for Fig 1 is

$$V_{OUT} = V_{IN} - ((R_1 + R_2)/R_1) V_{ERR}.$$

To V_{IN} , the circuit remains a voltage follower. The amplifier's output follows V_{IN} except for the difference produced by the amplified distortion signal. This difference is small as long as high loop gain keeps error signal V_{ERR} low.

Distortion above the measurement floor

Similarly, signal V_{IN} directly varies the voltage at the amplifier's noninverting input in Fig 1. Feedback forces the amplifier's inverting input to also follow this signal.

The selective amplification in Fig 1 raises the relative magnitudes of the V_{ERR} distortion products for increased resolution. But the signal generator's distortion now remains in the signal measured. However, this distortion signal is not amplified and its relative

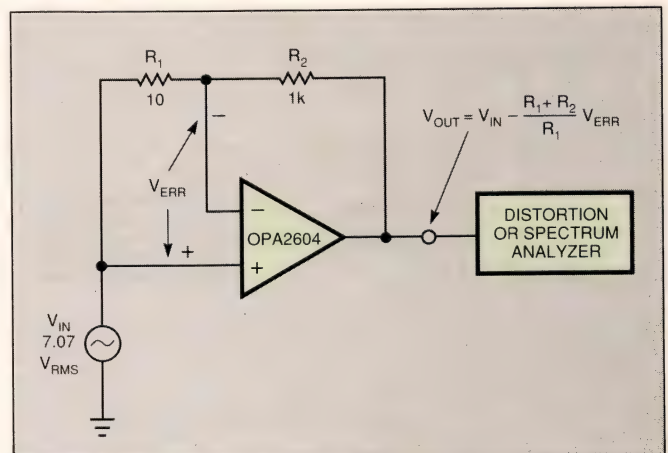


Fig 1—Selectively amplifying V_{ERR} magnifies the amplifier's distortion signal for direct measurement at the output of the amplifier tested.

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significance diminishes in proportion to the gain V_{ERR} receives. Similarly, this gain moderates the dynamic range demands on the signal analyzer. Thus, selective amplification raises the amplifier-distortion signal above the measurement floor of your instruments.

Following the measurement, a THD calculation removes the effect of the selective gain. Divide the measured distortion by the distortion gain of $(R_1 + R_2)/R_1$. For Fig 1 the output-referred distortion for a voltage follower is:

$$THD + N_0 = \frac{R_1}{(R_1 + R_2)} THD + N_M = THD + N_{IN}$$

OR

$$THD_{OUT} = \frac{R_1 \sqrt{(V_2^2 + V_3^2 + V_4^2 + \dots)}}{(R_1 + R_2) V_1}$$

At first blush, you'd think that maximizing the selective gain would achieve the greatest measurement accuracy. However, measurement bandwidth declines because of feedback-factor reduction as this gain increases (Ref 1). Because the op amp is now part of the measurement system, the amplifier's bandwidth limits resolution of higher-order distortion harmonics. Thus, you should choose the selective gain for Fig 1's setup to be as large as possible within your bandwidth constraints. Note that the low-value feedback resistors avoid adding noise.

Generalizing selective gain

The selective-gain approach of Fig 1 extends to generalized noninverting and inverting op-amp configurations. The generalized noninverting version in Fig 2

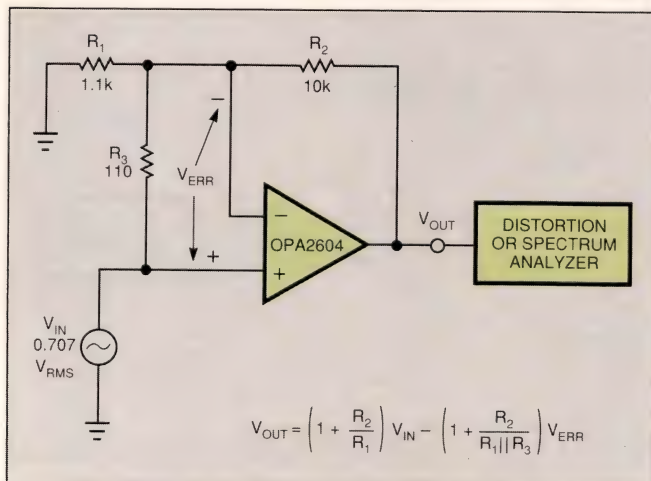


Fig 2—Adding R_3 extends selectively amplifying V_{ERR} to measuring the distortion of a generalized noninverting amplifier.

has R_3 's added gain for selectively amplifying distortion products. Resistors R_1 and R_2 set the normal closed-loop gain presented to V_{IN} . As usual, this gain is simply $A_{CL} = 1 + (R_2/R_1)$. V_{ERR} experiences greater gain because it develops a feedback current through R_3 , as well as through R_1 . The resulting error-signal gain relates the parallel combination of resistors R_1 and R_3 , and is $A_{ERR} = 1 + R_2/(R_1 || R_3)$. The proper choice for R_3 makes V_{ERR} 's distortion dominant at the amplifier's output.

The distortion measurement's resolution remains unchanged between Fig 1 and Fig 2. These circuits differ by the closed-loop gain, A_{CL} , supplied to V_{IN} and its distortion, but practical limits equalize the results. As A_{CL} increases, the magnitude of V_{IN} diminishes to maintain a given output-signal level. Thus, the magnitude of the input-signal distortion decreases by the same amount that its gain increases. The resulting output distortion arising from V_{IN} is, then, unchanged in magnitude from that of Fig 1. Adding R_3 keeps this distortion in the background by ensuring sufficient additional gain for the distortion products of V_{ERR} .

Dynamic-range constraints of the signal analyzer are also independent of A_{CL} in Fig 2. The relative levels of the fundamental signal and the distortion signals determine this range. For a given test condition, the output level is fixed and is essentially the level of the fundamental signal. To reduce dynamic-range requirements, raise the level of the distortion signal by amplifying V_{ERR} . This amplification results from either the intended closed-loop gain of the circuit or from this gain in conjunction with the selective gain R_3 provides. However the gain occurs, it raises the relative proportion of V_{ERR} in the output signal. As long as V_{ERR} receives sufficient gain, you can easily dis-

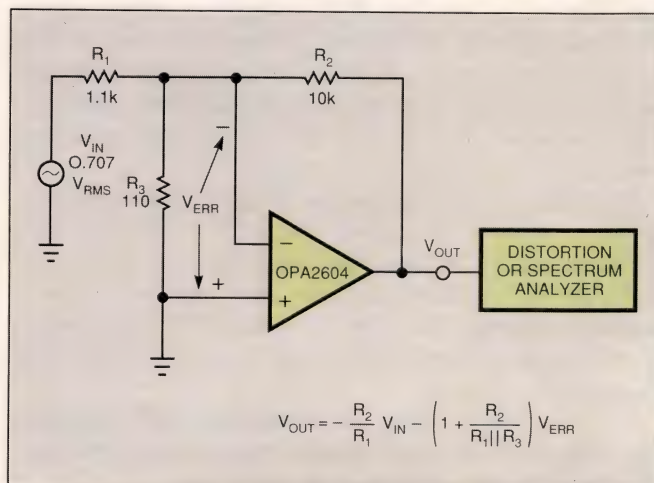


Fig 3—Selective amplification of an inverting amplifier follows directly from the noninverting case of Fig 2.

tinguish amplifier-distortion products in the output signal.

However, you must limit the gain you choose for V_{ERR} , or amplifier-response roll-off will restrict measurement of higher-frequency harmonics. The gain applied to V_{ERR} , not that applied to V_{IN} , sets the amplifier's bandwidth. To determine your measurement's bandwidth, calculate the feedback factor, considering R_3 to be grounded rather than bootstrapped. Then, for the circuit in Fig 2,

$$\beta = (R_1 \parallel R_3) / (R_1 \parallel R_3 + R_2).$$

This feedback factor defines a measurement-bandwidth limit of βf_c , where f_c is the unity-gain crossover frequency of the op amp. Beyond this limit, higher-order harmonics are attenuated in the measurement. Thus, again, you should consider a balance between test-equipment error suppression and higher-frequency resolution when choosing R_3 .

Accounting for gain differences

However, determining the output-referred distortion still requires separating the A_{CL} and A_{ERR} effects on the circuit in Fig 2. Selectively amplifying the distortion signal makes its effect dominant in the measurement. You must again adjust the measured distortion to account for the difference in signal and distortion gains. To adjust the measurement result, remove the selective gain that the amplifier distortion receives. In Fig 2, resistors R_1 and R_2 supply a gain of $A_{CL} = 1 + (R_2/R_1)$ to both V_{IN} and V_{ERR} . R_3 supplies additional gain to V_{ERR} . This added gain $(1 + R_2/R_3)$ amplifies only the distortion signal. To compensate, divide the measured distortion result by this added gain.

$$THD + N_0 = \frac{R_3}{(R_3 + R_2)} THD + N_M = \frac{(R_1 + R_2)}{R_1} THD + N_{IN}$$

OR

$$THD_{OUT} = \frac{R_3 \sqrt{(V_2^2 + V_3^2 + V_4^2 + \dots)}}{(R_3 + R_2) V_1} (100\%)$$

The selective amplification in Fig 2 translates directly for inverting op-amp configurations. To convert Fig 2 to an inverting amplifier, simply switch the circuit connections to the common return and the input signal (Fig 3). This switch returns the op amp's noninverting input and R_3 to ground and causes V_{IN} to drive R_1 . As before, resistors R_1 and R_2 set the gain, A_{CL} , presented to V_{IN} , and resistor R_3 boosts this gain to a higher level, A_{ERR} , for V_{ERR} . This higher gain determines the feedback factor and resulting measurement's bandwidth.

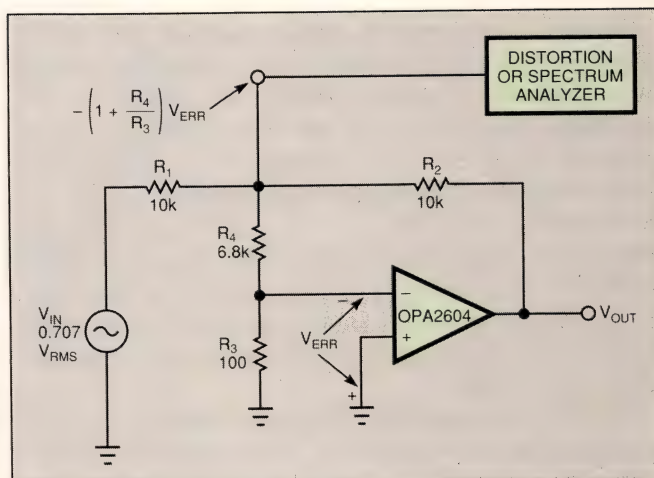


Fig 4—Adding R_4 combines selective amplification with signal separation for the inverting amplifier.

The circuit in Fig 3 retains a measurement resolution that is independent of A_{CL} . Only gain A_{ERR} affects this resolution. Finally, convert the measured THD_M of Fig 3 to THD_{OUT} or THD_{IN} using the equations for Fig 2.

The only way Fig 3 differs from Fig 2 is in the common-mode input signal of the amplifier. In the non-inverting circuit in Fig 2, input signal V_{IN} is a common-mode signal to the amplifier's inputs, and it exercises nonlinearities in the amplifier's CMRR. The inverting circuit in Fig 3 removes this common-mode signal from the amplifier's inputs. Then, only the gain nonlinearity of the amplifier influences the amplifier's distortion. This difference permits you to separate gain and CMRR distortion effects.

Combining the two methods

Selective amplification in the inverting case offers another alternative. Both selective amplification and signal separation work in inverting circuits. However, the combination places greater demands on measurement bandwidth. Selective amplification obviates the instrumentation amplifier used before. To eliminate the instrumentation amplifier, Figs 1 and 2 move the signal measurement to the op amp's output. There, signal separation is compromised because the full test signal remains in the measurement.

This compromise is unnecessary for inverting configurations. As mentioned before, inverting configurations do not require the instrumentation amplifier for the signal-separation measurement. Thus, with inverting configurations you need not move the measurement to the amplifier's output. Instead, signal separation and selective amplification combine at the amplifier's input (Fig 4). There, R_3 develops a feedback current with V_{ERR} just as before.

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However, the circuit in **Fig 4** does not rely on R_2 to convert this feedback current to an amplified output error. Instead, a second resistor, R_4 , added at the amplifier's input, does this job. The feedback current produced in R_3 conducts through R_4 to produce the desired amplification right at the amplifier's input. At the top of R_4 , the signal is $-(1 + R_4/R_3)V_{ERR}$. This amplified error signal remains free of the large test signal present in the amplifier's output. As before, this separated error signal permits measurements free from signal-generator distortion and eliminates large dynamic-range requirements.

The distortion measured in **Fig 4** requires three adjustments for converting it to output-referred distortion. First, compensate the difference in measured and actual fundamental signals as in previous signal-separation measurements. Then, make two gain adjustments. The measured signal receives a measurement gain of $(1 + R_4/R_3)$ but does not receive the circuit closed-loop gain of $A_{CL} = (1 + R_2/R_1)$. To compensate, divide the measured distortion by the measurement gain and multiply it by A_{CL} .

$$\begin{aligned} \text{THD} + N_0 &= \frac{R_3 (R_1 + R_2)}{R_1 (R_3 + R_4)} \frac{V_{ERR}}{V_{OUT}} \text{THD} + N_M \\ &= \frac{(R_1 + R_2)}{R_1} \text{THD} + N_{IN} \\ \text{OR} \\ \text{THD}_{OUT} &= \frac{R_3 (R_1 + R_2)}{R_1 (R_3 + R_4)} \frac{\sqrt{(V_2^2 + V_3^2 + V_4^2 + \dots)}}{V_{OUT}} (100\%) \end{aligned}$$

Fig 4 introduces an added attenuation to the circuit's feedback factor, restricting measurement bandwidth. In addition to the normal feedback attenuation of R_1 and R_2 , a second feedback attenuation results from R_3 and R_4 . R_3 and R_4 also produce a loading effect on the attenuation of R_1 and R_2 . The net **Fig 4** feedback factor is

$$\beta = \frac{R_1 R_3}{R_1 R_2 + R_1 R_3 + R_1 R_4 + R_2 R_4 + R_3 R_4}$$

The relationship of bandwidth to gain bandwidth, $BW = \beta \text{GBW}$, then determines the bandwidth for the circuit in **Fig 4**. For the specific components of **Fig 4**, $\beta = 0.0043$ and $\text{GBW} = 10 \text{ MHz}$ for $BW = 43 \text{ kHz}$.

Because of the low feedback factor, this measurement's bandwidth is below the 80 kHz desired for audio applications. Other choices for R_3 and R_4 offer higher feedback factors to improve bandwidth, but such choices lower the selective gain. With less gain, the

distortion signal's level is closer to the test equipment's measurement floor. Because of this compromise, you should use the circuit in **Fig 4** only where signal-generator distortion must be separated from the test signal. In other cases, the basic selective-gain configuration offers a better compromise.

The input capacitance of the signal analyzer, C_1 , alters the feedback factor in **Fig 4**. This capacitance bypasses R_1 and can cause gain peaking or even oscillation. Such problems occur only if the break frequency of the bypass, $1/2\pi R_1 C_1$, is within the amplifier's closed-loop bandwidth. In this case, add a compensating capacitor in parallel with R_2 to roll off the gain peaking. Choose this capacitor to break with R_2 at the same frequency that C_1 breaks with $R_1 \parallel (R_3 + R_4)$. Then, the feedback-divider action of the R_2 and R_1 legs remains approximately constant with frequency.

Gain variation extends resolution

Some op amps' distortion-measurement requirements exceed test equipment's capabilities even when you use the preceding methods. When your op amp

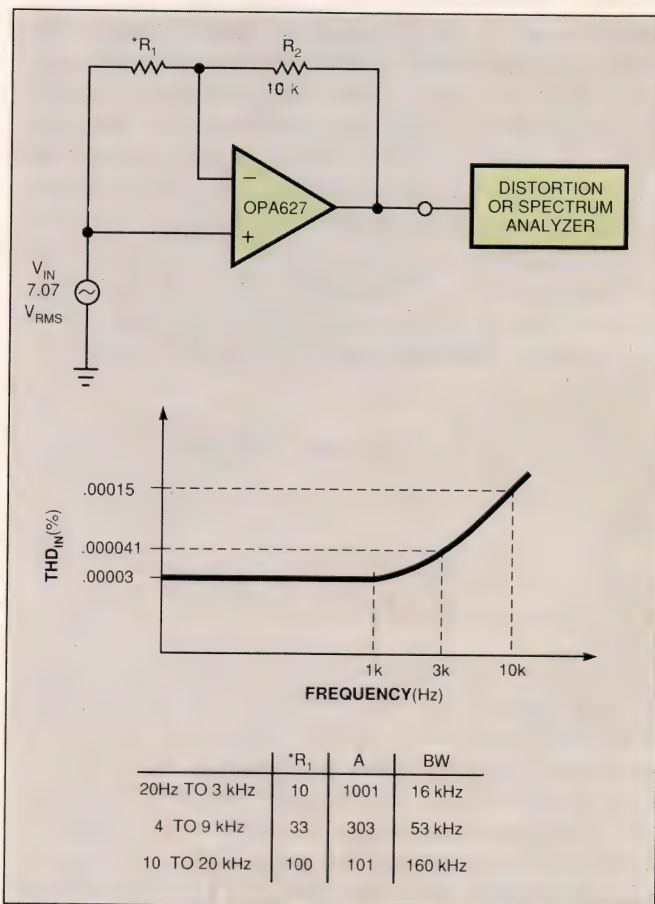


Fig 5—For extremely low-distortion amplifiers, vary the selective gain to retain resolution and bandwidth.

has low distortion over wider bandwidths, or just extremely low distortion, you need variable test configurations to characterize fully its distortion-versus-frequency performance.

First, low distortion levels automatically rule out the basic signal-separation approach of Part 1 because that approach requires an instrumentation amplifier of even lower distortion than the op amp under test. Instead, use selective amplification, which places measurement bandwidth and measurement resolution in competition. You must maintain measurement bandwidth to around 80 kHz to resolve harmonics important to the audio range. This bandwidth limits the selective amplification to a gain of $1/\beta = \text{GBW}/80\text{kHz}$.

However, your setup need not maintain full bandwidth at every test frequency. The amplitude of distortion harmonics drops as their frequencies get further away from the fundamental's frequency. Because of this decline, a measurement bandwidth that spans only five or six harmonics is sufficient. A smaller measurement bandwidth permits the use of higher selective gains to better resolve the lower distortion levels encountered at lower frequencies. Higher test frequencies require the full bandwidth, but they also cause correspondingly higher amplifier distortion. Accordingly, higher test frequencies require less selective gain, extending measurement bandwidth. Thus, the gain/bandwidth compromise of selective amplification

yields to distortion measurement with varied gains.

The OPA627, for example, requires three selective-gain steps, each step providing a different gain/bandwidth combination. **Fig 5** details this gain variation, which revolves around the THD_{IN} -vs-frequency plot. As this plot shows, op-amp distortion typically rises at higher frequencies, where measurement bandwidth is most needed.

Power-supply bootstrapping for noninverters

Signal separation is a complete solution only for inverting configurations. Using a power-supply bootstrap avoids limitations in noninverting solutions. Given care to avoid ground loops, the bootstrapping approach separates the common-mode signal, extending signal separation to the noninverting case.

To permit an optimal analyzer connection, power-supply bootstrapping moves the circuit's common from the normal circuit ground to the op amp's noninverting input (**Fig 6**). As odd as it may seem to consider an op amp's noninverting input to be the common, the common of a circuit is a relative point that you can define to be anywhere you choose. This connection retains the common-mode swing for the amplifier but removes that swing relative to common and, thus, removes it from the analyzer's input.

Theoretical niceties aside, redefining the common introduces ground-loop errors. The effects of these errors depend on the sensitivity of the circuit to voltage drops in its connecting lines. In **Fig 6**, the element most sensitive to such voltages is the signal analyzer because it measures a small signal superimposed on a larger one. For this reason, the figure shows the signal analyzer returned to the circuit's new common. **Fig 6** makes the power-supply connections vulnerable to line drops, but the power-supply rejection of the op amp attenuates the resulting voltages.

For **Fig 6**, the test-equipment demands again decrease by a factor of $1/(1/A + 1/\text{CMRR})$. However, the measurement made in **Fig 6** requires adjustment to account for the reduced fundamental measured. For this figure, the relevant signal swing is that across the load resistor, or V_{IN} . Therefore, multiply the measured distortion by $V_{\text{ERR}}/V_{\text{IN}}$.

The actual adjustment made depends on the type of signal analyzer used. Measurements made with a distortion analyzer directly produce a $\text{THD} + \text{N}$ percentage. Simply multiply this percentage by $V_{\text{ERR}}/V_{\text{IN}}$ and **Fig 6**'s output distortion plus noise is then

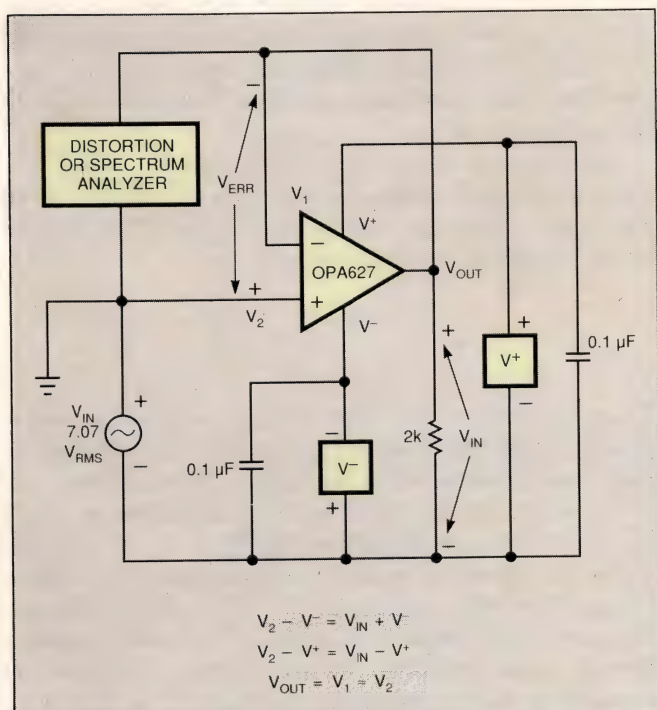


Fig 6—Power-supply bootstrapping permits directly measuring V_{ERR} and does not change an amplifier's internal voltage swings.

$$\text{THD} + \text{N}_0 = \frac{V_{\text{ERR}}}{V_{\text{IN}}} \text{THD} + \text{N}_M = \text{THD} + \text{N}_{\text{IN}}$$

MEASURING OP-AMP DISTORTION

You must measure the magnitude of V_{ERR} separately because distortion-analyzer outputs do not normally indicate this magnitude.

When you measure distortion with a spectrum analyzer, no separate measurement is required. Spectrum analyzers display the magnitudes of the fundamental and harmonic signals individually. You can then calculate distortion from the fundamental THD equation. Multiply this equation by V_{ERR}/V_{IN} , where V_{ERR} is equal to and therefore replaces V_1 , and V_{IN} remains in the denominator. Then, the spectrum analyzer result for Fig 6 is

$$THD_{OUT} = \frac{\sqrt{(V_2^2 + V_3^2 + V_4^2 + \dots)}}{V_{IN}} (100\%).$$

Bootstrapping resolves noninverting cases

The convenience of Fig 6 extends to the generalized noninverting amplifier. As Fig 7 shows, power-supply bootstrapping again permits directly measuring V_{ERR} with a grounded signal analyzer.

Only one difference separates the measurements of the two circuits. The greater gain of Fig 7 results in a larger load signal V_{LOAD} . This gain also amplifies

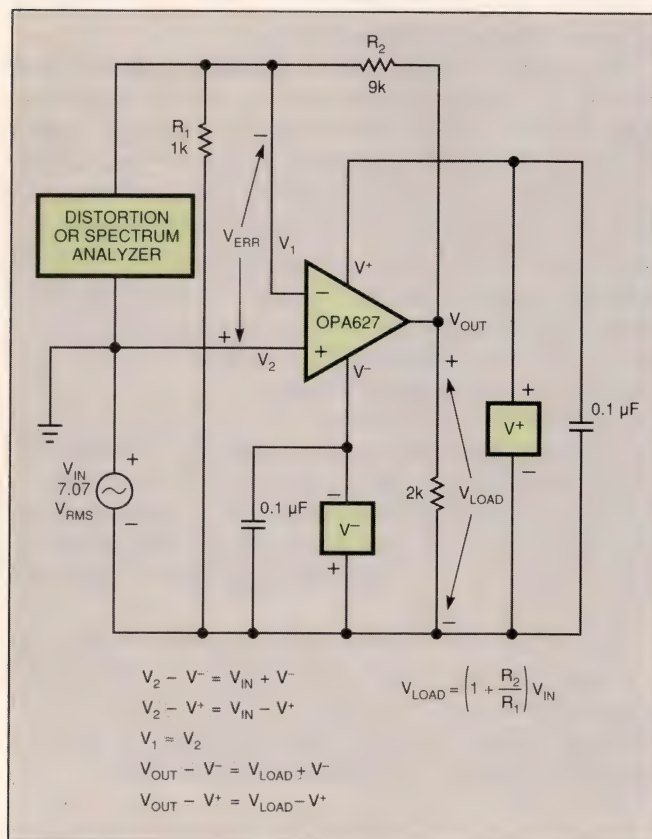


Fig 7—The bootstrapping of Fig 6's voltage follower also applies to general noninverting circuits.

V_{ERR} , making the distortion in V_{LOAD} greater than that measured in V_{ERR} . You can adjust the measured distortion later to compensate for the effect of this gain. Finally, the added gain further reduces the performance requirements of the test equipment. For a given level of V_{LOAD} , V_{IN} is smaller for Fig 7 than for Fig 6. Thus, with Fig 7, V_{IN} 's reacting with the amplifier's CMRR produces a smaller V_{ERR} signal. The noninverting configuration reduces the signal measured by a factor of $V_{LOAD}/V_{ERR} = 1/(1/A + \beta/CMRR)$.

Consider Fig 7 with the common return first at the top and then at the bottom of the signal generator. This change makes no difference in the equations relating amplifier voltages to the V^+ and V^- supply terminals. For both configurations, the $V_2 - V^-$ and $V_2 - V^+$ equations are the same as those for Fig 6. Amplifier feedback forces $V_1 \approx V_2$ to again extend these equations to Fig 7's input. Thus, whether bootstrapped or not, the amplifier distorts the input signal.

Fig 7's greater gain produces a different output result than Fig 6. To define V_{OUT} relative to V^+ and V^- , first determine the load voltage, V_{LOAD} . You can find this voltage from the loop formed by the load resistor with resistors R_1 and R_2 . The input signal, V_{IN} , appears across resistor R_1 , producing a feedback current of V_{IN}/R_1 . This current flows in R_2 to develop a voltage of $V_{IN}R_2/R_1$. Adding the voltages on R_1 and R_2 shows the voltage on the load to be $V_{LOAD} = (1 + R_2/R_1)V_{IN}$. This result portrays the familiar response of a noninverting op-amp configuration and is independent of Fig 7's redefined common. Thus, the bootstrapping does not affect the load voltage and the corresponding amplifier output current.

Similarly, the loops relating V_{OUT} to V^+ and V^- remain unchanged. With the common on either side of the signal generator, the output voltages with respect to the amplifier supply terminals are

$$\begin{aligned} V_{OUT} - V^- &= V_{LOAD} + V^- \\ V_{OUT} - V^+ &= V_{LOAD} - V^+ \end{aligned}$$

Thus, both input- and output-signal conditions are independent of the Fig 7 common connection, and the bootstrapping does not change the amplifier's distortion products.

You must convert the distortion measured in Fig 7 to output-referred distortion. In Fig 7, the circuit amplifies the distortion products in V_{ERR} by $1/\beta$ to produce greater distortion signals in V_{OUT} . This effect changes the correction factor to $V_{ERR}/\beta V_{IN}$. However, because the same gain amplifies the input signal, V_{IN} , the final correction factor becomes $\beta V_{ERR}/\beta V_{IN} = V_{ERR}/V_{IN}$. Thus Fig 7's correction equations are the same as Fig 6's.

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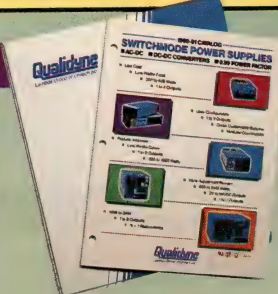
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2.5x5x11"	400W	2-6V/60A	5-15V/12A	5-15V/12A	2-6V/12A	
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2.5x5x11"	400W	12-28V/15A	5-15V/12A	5-15V/3A	5-15V/3A	2-6V/12A
3x5x14.25"	600W	5V/80A	5-24V/10A	5-24V/10A	5-24V/5A	5-24V/5A
4x5x14.25"	750W	5V/100A	5-15V/20A	5-15V/20A	5-24V/5A	5-24V/5A
5x5x11.5"	1000W	5V/120A	5-15V/20A	5-15V/20A	5-24V/5A	5-24V/5A
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3x5x14.25"	600W	2-4V/150A	4-6V/120A	7-12V/50A	12-28V/22A	28-56V/11A
5x5x11.5"	1000W	2-4V/250A	4-6V/200A	7-12V/84A	12-28V/36A	28-56V/18A
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CIRCLE NO. 67

MEASURING OP-AMP DISTORTION

ping and selective amplification achieves even greater distortion resolution. This way, you can test the very lowest distortion amplifiers with a distortion analyzer. This particular amplifier-and-analyzer combination is the one case where noise becomes a limit to op-amp distortion measurement. And for a spectrum analyzer, the ambient noise of the test environment requires your careful attention to avoid coupling stray noise into your circuit. With either type of analyzer, selective amplification expands distortion resolution for the bootstrapped voltage follower.

The benefits of power-supply bootstrapping and selective amplification combine in Fig 8. In this circuit, the only signal developed at the amplifier's output is the amplified error signal:

$$V_{OUT} = -(1 + R_2/R_1)V_{ERR}$$

A signal analyzer measures this amplified signal referenced to ground with no interference from the test signal. In addition, the amplified distortion signal conveniently overrides the background noise of the signal analyzer and the measurement environment. This convenience does not extend to the general noninverting case because added gain there restores the test signal to the amplifier's output.

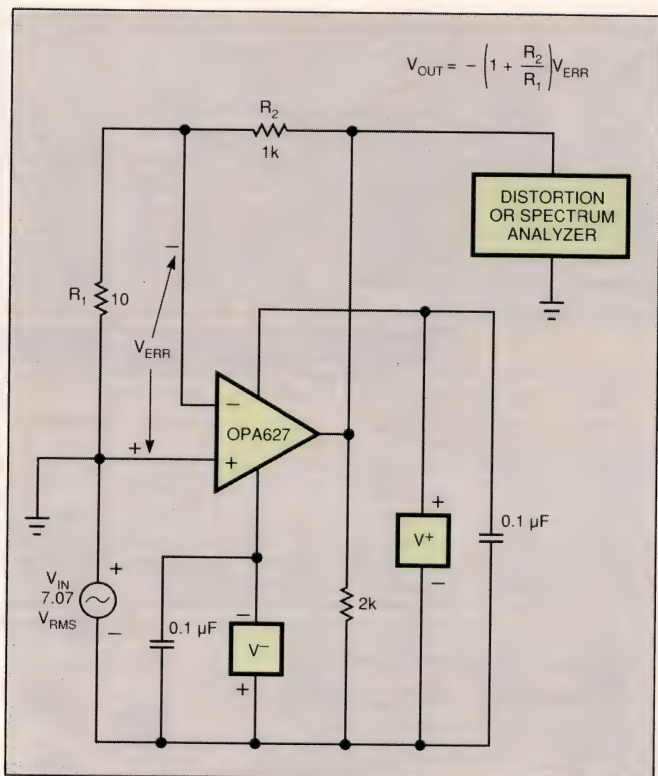


Fig 8—Combined bootstrapping and selective amplification expand distortion resolution for the voltage follower.

Other characteristics of the measurement shown in Fig 8 follow directly from earlier results. Selective amplification reduces the measurement bandwidth from f_c to βf_c . Here, f_c is the unity-gain bandwidth of the op amp. The feedback factor is $\beta = R_1/(R_1 + R_2)$. Fig 8's test-equipment requirements are the same as for the bootstrapped follower of Fig 6. As with that circuit, the distortion and dynamic-range requirements of the test equipment decrease by a factor of $1/(1/A + 1/CMRR)$. Because the selective amplification amplifies both the amplifier's distortion products and the background signal, V_{ERR} , it does not improve this factor. The attenuated generator distortion present in V_{ERR} gets amplified along with the amplifier distortion products. The relative significance of generator distortion is unchanged. Similarly, the selective gain amplifies both the maximum and minimum signals to be resolved by the analyzer. Thus, the dynamic range of the measurement is also unchanged.

For the same reasons, results measured with the circuit in Fig 8 translate output-referred distortion with the same equations as those used in Figs 6 and 7. EDN

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3. Pryce, Dave, "Audio DACs Push CD Players to Higher Performance," EDN, December 7, 1989.

Author's biography

For Jerald Graeme's biography, see Part 1 of this series on pg 133.

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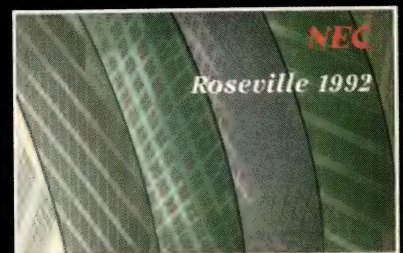
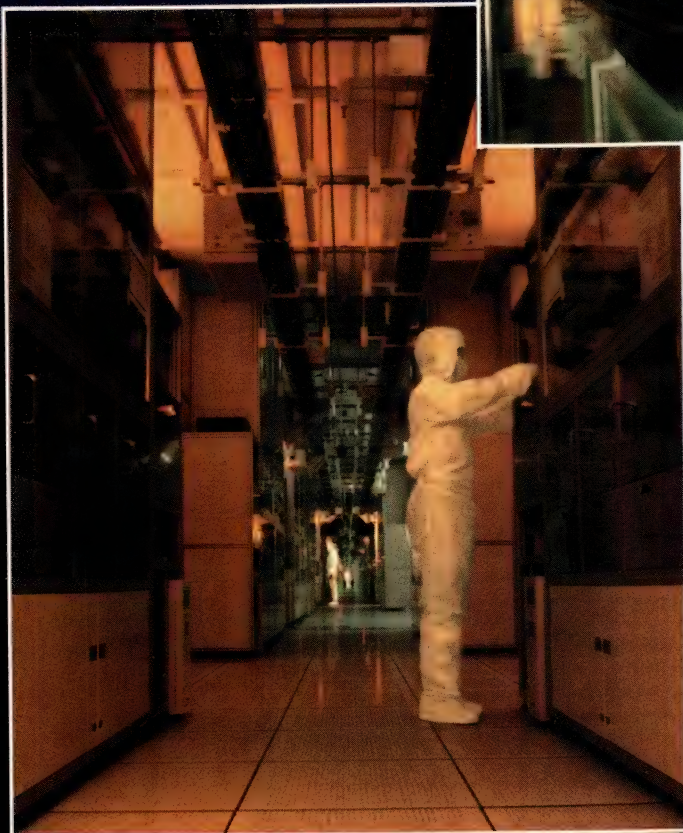
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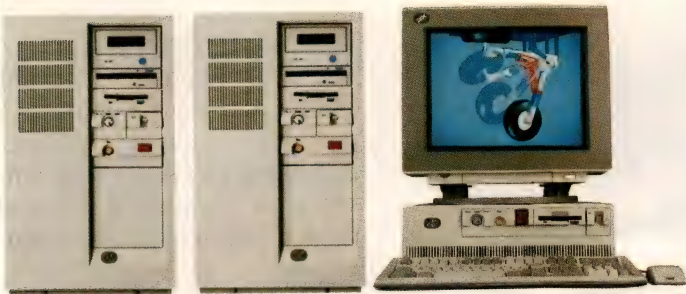
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Miniature power supply works off line

David A Johnson, David Johnson and Associates, Littleton, CO

The circuit in Fig 1 operates off a 120V ac line and is cheaper and smaller than more common circuits that consist of a small iron-core transformer, a bridge rectifier, a filter capacitor, and a voltage regulator. The circuit transfers power from the 120V ac line to a voltage-regulator circuit by discharging a capacitor through a small high-frequency transformer twice each power-line cycle. A bidirectional discharge circuit comprising two small SCRs, CR₁ and CR₂, and two current-steering rectifiers, D₁ and D₂, provides the power switching. A low-cost and common speaker impedance-matching transformer reduces the voltage and provides isolation. SCRs work better than triacs in this design because triacs require more gate drive and higher holding currents than do SCRs.

The resistor-divider network R₁ to R₃ defines a voltage trigger point of approximately 140V for the two SCRs. Each time C₁ discharges, the circuit induces voltage spikes in the primary winding of the transformer. The transformer translates the pulses to its secondary winding, where D₃ and D₄ rectify and C₂ filters the pulses. An inexpensive 78L12 3-terminal regulator provides voltage regulation. With the components in Fig 1, the circuit supplies a 12V output and a maximum current of 15 mA. The circuit will operate with an input as low as 108V ac.

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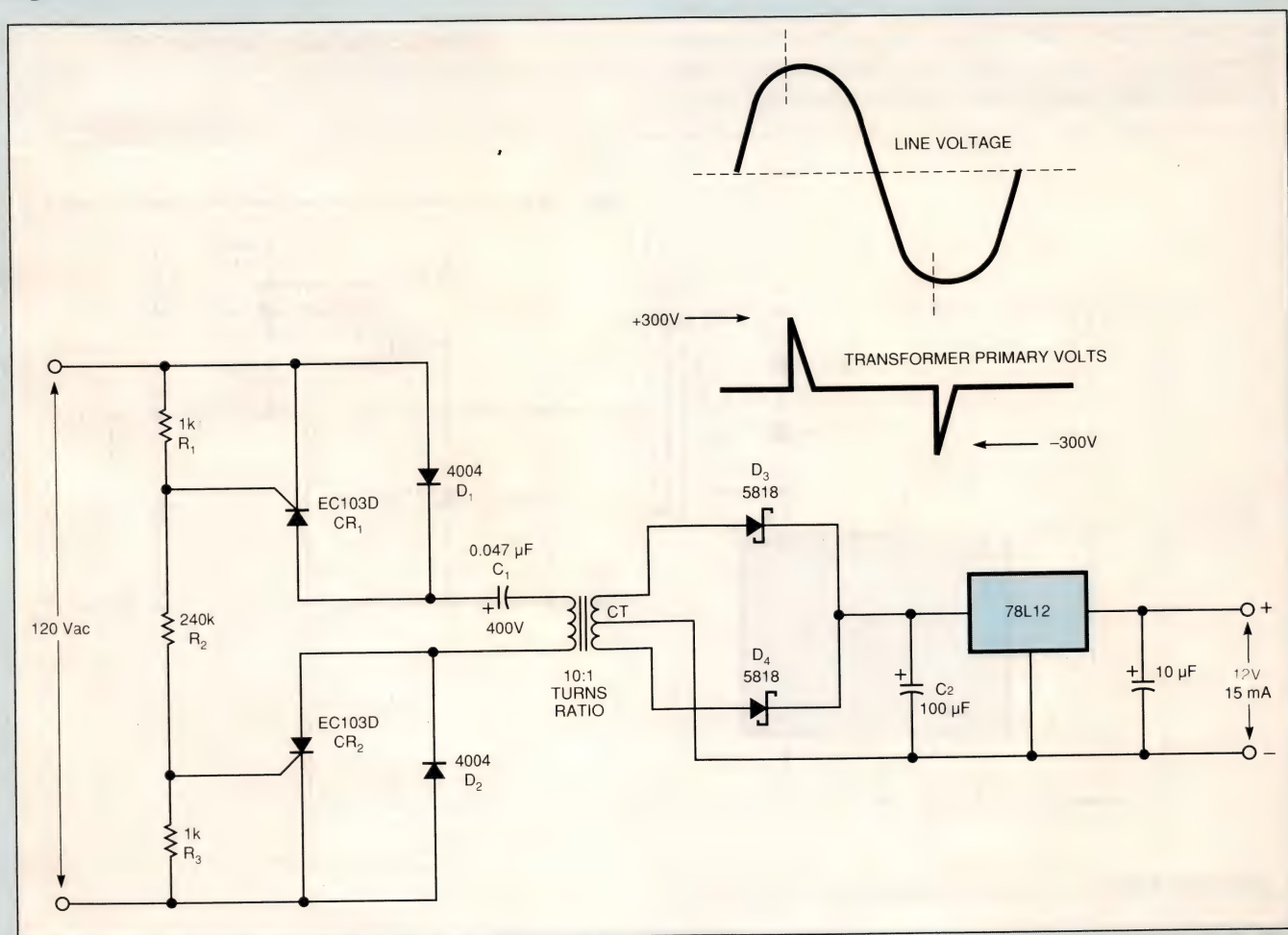


Fig 1—Smaller and cheaper than many other off-line power supplies, this low-power circuit transfers power from a 120V ac line to a voltage regulator by discharging a capacitor through a small, high-frequency transformer.

Split supply operates from a single cell

Mitchell Lee, Linear Technology Corp, Milpitas, CA

Batteries power many portable instruments, but many cells are usually necessary to directly implement a split supply. The circuit in **Fig 1** uses a micropower dc/dc converter to provide $\pm 5\text{V}$ from just one alkaline or NiCd cell. The circuit outputs 100 mW from a fresh cell and 50 mW when the cell's voltage drops to 1.05V. The circuit provides the output power in any current combination; for example, 5 mA from each output, 10 mA from one output, or 7 mA from one output and 3 mA from the other. This flexibility is especially useful for op-amp supplies in which the load current returns to ground. In this case, only one side of the split supply delivers high currents at any given time.

The LT1073 micropower dc/dc converter contains a switching element and regulating loop to maintain a $\pm 5V$ output over a wide range of load currents and over the full life of the battery. If loading on the positive output exceeds the loading on the negative output, R_1 and R_2 feed back to pin 8 and maintain regulation.

If the negative output is more heavily loaded, D_1 and Q_1 provide feedback to pin 8. Positive output regulation is less than 0.2% for loads from 2.5 to 7.5 mA. Negative output regulation is 2% for the same loads. Cross regulation is acceptable with a load imbalance as high as 10 to 1. You can extend cross regulation by adding the optional zener diodes, D_2 and D_3 . The positive output cross regulation is 0.8% with a 2.5-mA load. The negative output cross regulation is 4% with a 2.5-mA load.

Efficiency with a 1-mA load on each output is greater than 75% over the 1.05 to 1.5V input range. Although the circuit suits 1-cell inputs, operation is also possible with two or three cells. When using more cells, the available output power will be somewhat higher.

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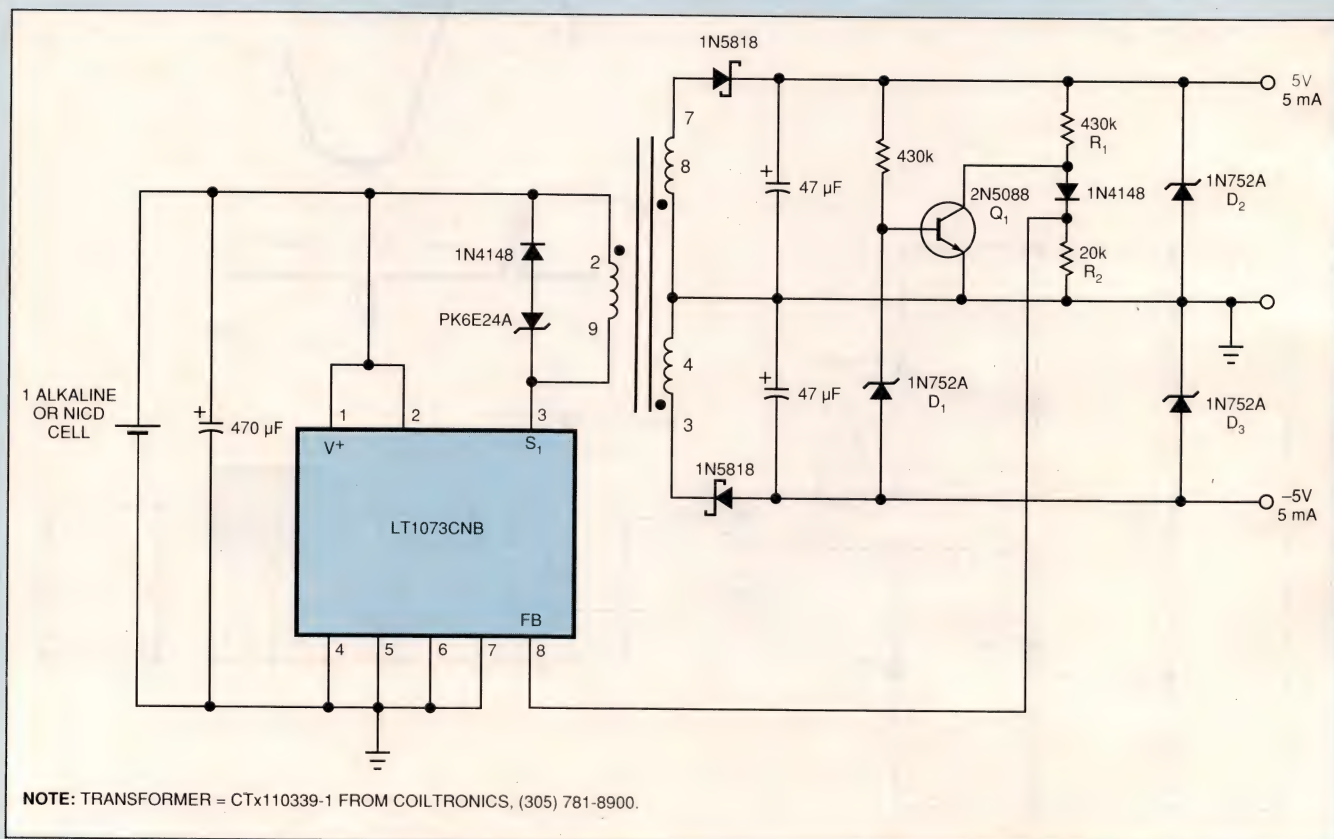
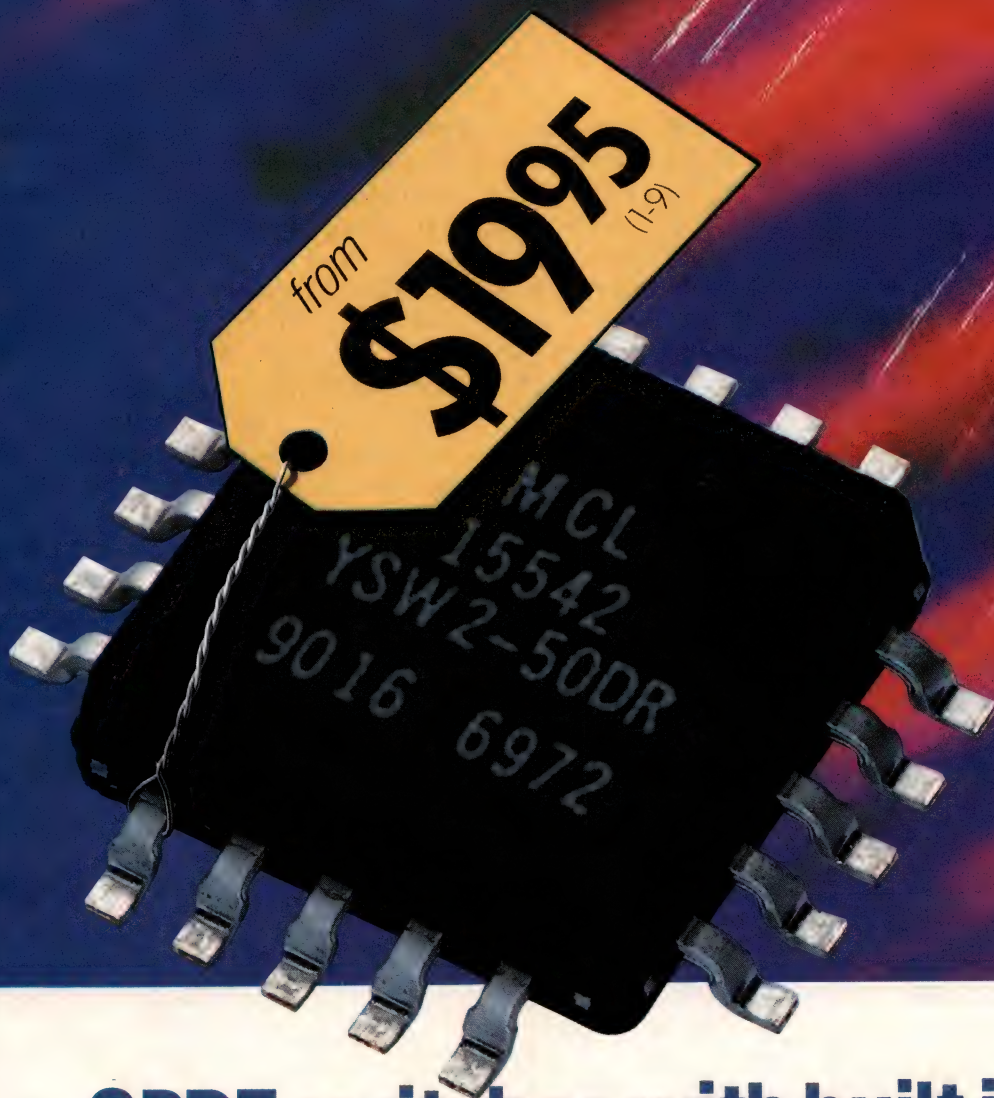


Fig 1—To produce a split supply from a single cell, this circuit uses a micropower dc/dc converter to supply $\pm 5V$ and any 10-mA current combination.

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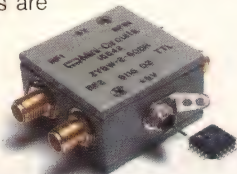


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SPECIFICATIONS (typ)

	Absorptive SPDT YSWA-2-50DR ZYSWA-2-50DR			Reflective SPDT YSW-2-50DR ZYSW-2-50DR		
	dc- 500	500- 2000	2000- 5000	dc- 500	500- 2000	2000- 5000
Frequency (MHz)	500	2000	5000	500	2000	5000
Ins. Loss (dB)	1.1	1.4	1.9	0.9	1.3	1.4
Isolation (dB)	42	31	20	50	40	28
1dB Comp. (dBm)	18	20	22.5	20	20	24
RF Input (max dBm)	18	20	22.5	22	22	26
VSWR "on"	1.25	1.35	1.5	1.4	1.4	1.4
Video Bkthru (mV/p/p)	30	30	30	30	30	30
Sw. Spd. (nsec)	3	3	3	3	3	3
Price, \$	YSWA-2-50DR (pin) 23.95			YSW-2-50DR (pin) 19.95		
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CIRCLE NO. 73

F141 REV. C

Synchronous switch mutes line noise

M J Salvati, Flushing Communications, Flushing, NY

A variety of line-operated devices, such as neon lamps, SCRs, triacs, and fluorescent lamps, produce powerful RF signals that may interfere with nearby radio receivers. The circuit in **Fig 1** improves the intelligibility of the recovered audio by muting the audio path during the noise-pulse interval. This scheme works only when the noise pulse arises from a single dominant nearby noise source. However, the circuit has an advantage over simpler clipping circuits because it doesn't require a steady signal amplitude to operate properly. Also, unlike RF and IF noise blankers, the entire circuit is external to the receiver. Thus, using this circuit doesn't require you to modify existing receivers.

Power-line-related noise generally occurs at a repetition rate of twice the local power-line frequency. Because the same line power drives the noise blanker and the noise source, the output of the bridge rectifier will be frequency and phase coherent with the noise pulses.

The circuit applies a rectified signal to the Schmitt

input, pin 5, of the 74HC4538 dual monostable multivibrator. The first monostable delays the blanking pulse that the second monostable produces. This delay, which you can vary using the position potentiometer, lets you position the blanking pulse to coincide with the noise pulse in the audio signal.

The width potentiometer of the second monostable lets you adjust the blanking pulse to the minimum width sufficient for effective blanking while minimizing distortion. The blanking pulse appears at the inverted output of the second monostable. This normally high output level keeps the p-channel FET cut off. When the blanking pulse appears, this output goes low, and the FET conducts, thus shorting the audio-signal path. The RC filter at pin 9 of the second monostable also helps minimize distortion of the recovered audio by slowing the fast rise and fall times of the blanking pulse. **EDN BBS /DL SIG #1085**

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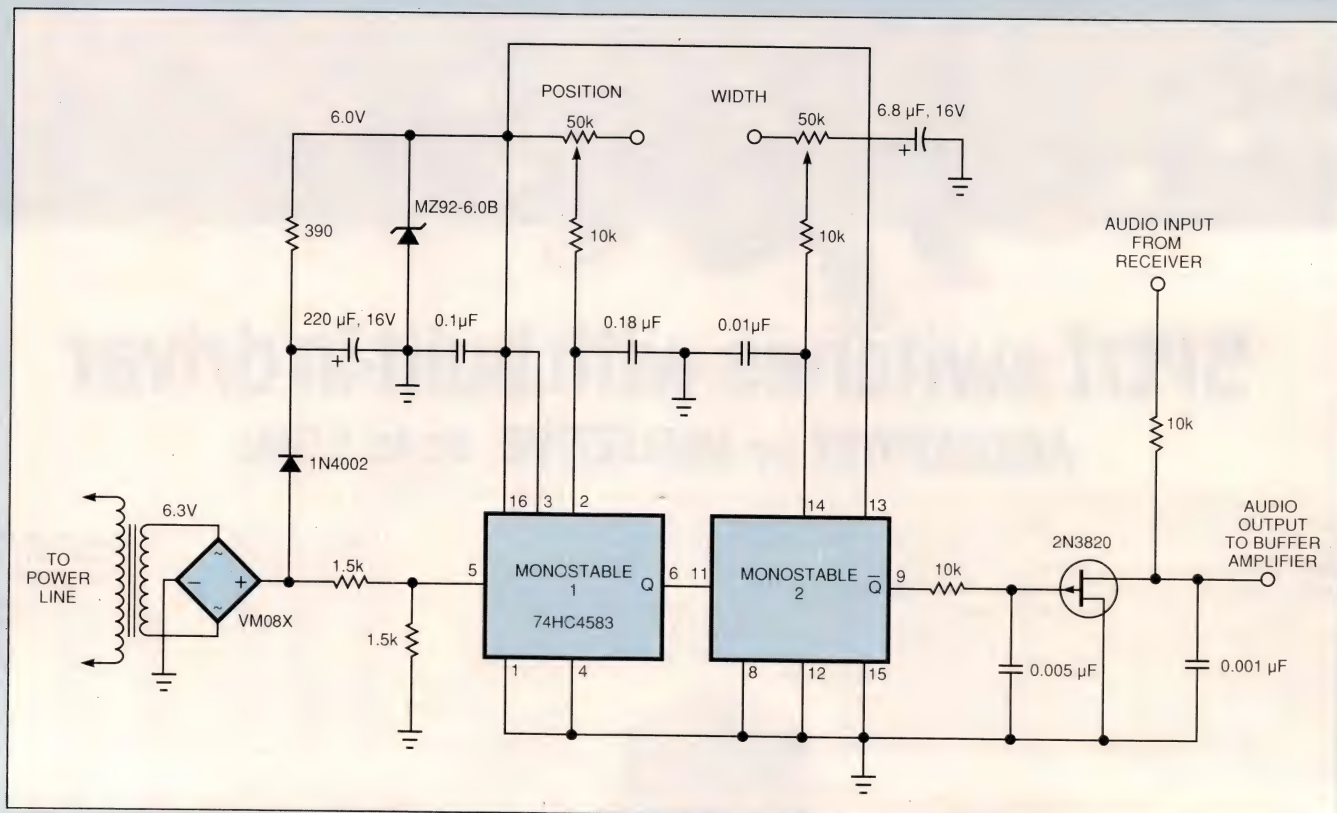


Fig 1—The position adjustment of this noise-muting circuit lets you align the blanking pulse to coincide with the audio-signal's noise pulse. The width adjustment helps minimize distortion.

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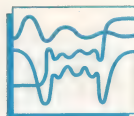
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Large capacitor serves as battery backup

Michael Grimm, Maxim Integrated Products, Sunnyvale, CA

A large capacitor—on the order of 0.1F—can replace your backup battery in certain applications. Though limited in storage capacity, the capacitor offers sufficient backup for low-dissipation equipment in which typical power outages last from a few seconds to several hours. The simple implementation that Fig 1 shows combines the capacitor with a battery-switch-over IC, a device that monitors the supply and switches the load to the battery voltage when the main supply fails or browns out.

The Fig 1a circuit includes various features to ensure proper operation of the switch-over IC. The 100-k Ω resistor, whose current comes from the main supply, keeps D_1 forward biased and ensures the typical V_{BE} drop of 0.6V across D_1 . The resistor maintains a safety

margin of one V_{BE} against droop in the V_{DD} supply. D_2 prevents this resistor from discharging the capacitor during backup. You can increase the margin by adding diodes in series with D_1 .

Fig 1b improves on the original circuit by replacing D_1 and D_2 with R_2 and Q_1 , respectively. In Fig 1a, the charging path via the diode has a time constant that postpones the availability of backup power following power on. For Fig 1a, the power delay would be $10\text{-k}\Omega \times 0.1\text{F} = 1000\text{ sec}$, or more than 16 minutes. Fig 1b divides this delay by the transistor's beta, which is typically 100. EDN BBS /DI_SIG #1086

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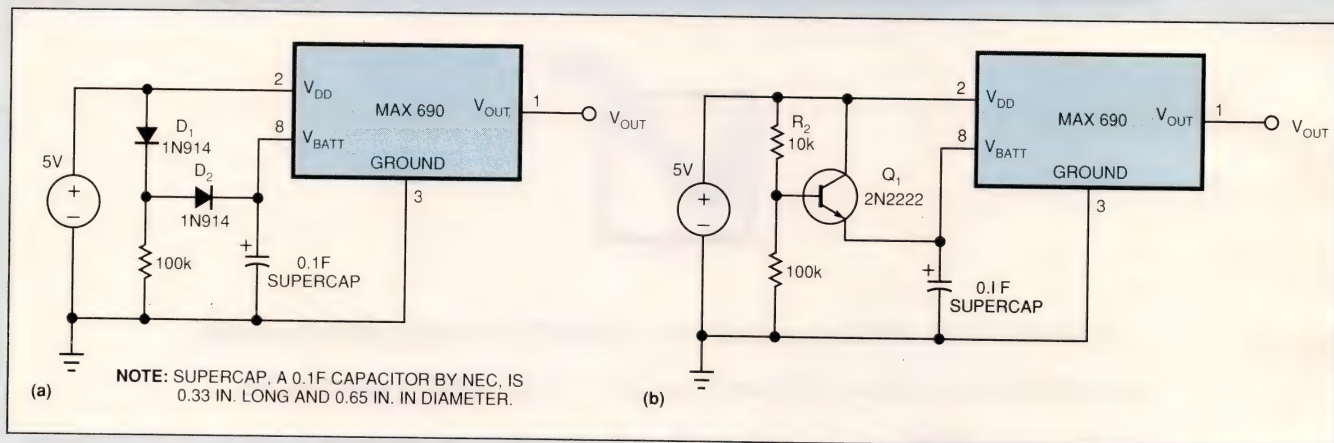


Fig 1—Teamed with a switch-over IC, large capacitors can serve as battery backup in certain applications. The 100-k Ω resistor in (a) ensures that D_1 is forward biased so that normal variations in V_{DD} don't mistakenly trip the IC. The presence of Q_1 and its associated resistors in (b) shorten the delay between power on and backup capability.

Spice model mimics reference

Joe Buxton, Analog Devices Inc, Santa Clara, CA

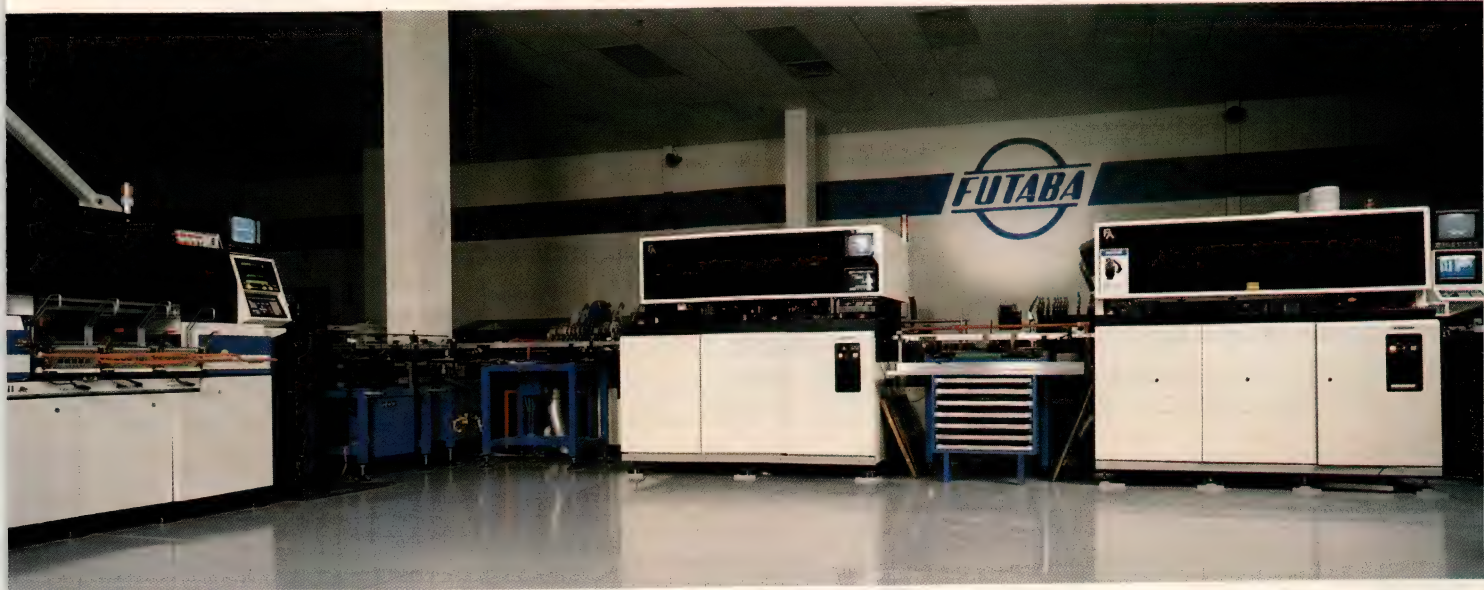


Seemingly simple dc components can cause simulation inaccuracies if you don't have correct models for them. For example, the common practice of modeling a voltage reference using a Thevenin equivalent circuit doesn't produce accurate simulations under dynamic and transient conditions. When driving a successive-approximation ADC, step

changes in load current cause voltage disturbances at the reference output. The reference's recovery time after this disturbance affects the accuracy of the ADC's result. Other non-ideal reference characteristics include load and line regulation, current limiting, temperature coefficients, turn-on and turn-off conditions, and short-circuit current.

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The macromodel in **Fig 1** and **Listing 1** (which is also posted on the EDN BBS (617) 558-4241,300/1200/2400,8,N,1—from main menu, enter (s)ig, <s/di_sig>, rk1087) for the REF-01 10V voltage reference includes features to account for some of these real-world characteristics. You can apply many of the concepts and techniques used to create this model to creating more accurate models of other simple dc devices.

An important feature of this model is its temperature sensitivity. By including the temperature coefficient for R1, which creates the model's internal 1.23V refer-

ence in conjunction with I1, the output voltage varies linearly with temperature. The thermal noise of R1 also models the reference's output noise. The value of R1 that this models uses was calculated from the data sheet's output-noise specification. C1 sets the dominant pole and the slew rate of the reference, and thus controls the turn-on and transient-load settling times. The model's output stage sets the impedance and controls current limiting. **EDN BBS /DI_SIG #1087** **EDN**

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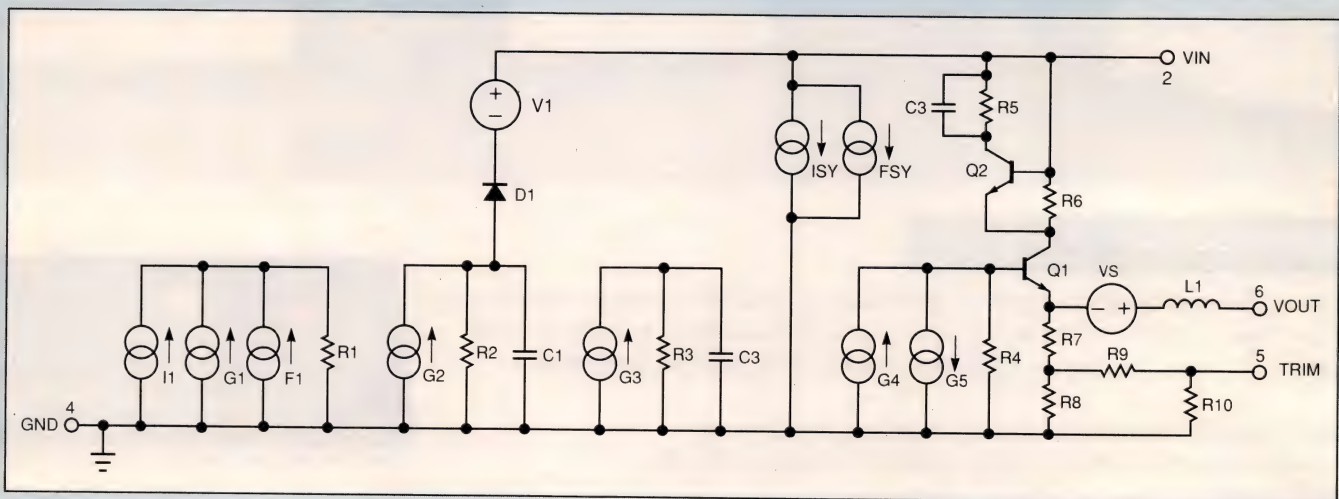


Fig 1—Simple dc components, such as voltage references, need accurate models. This REF-01 model includes the temperature coefficient for R1, so that the output voltage varies linearly with temperature. The model does not include second-order, nonlinear drift effects.

Listing 1—Spice REF-01 model

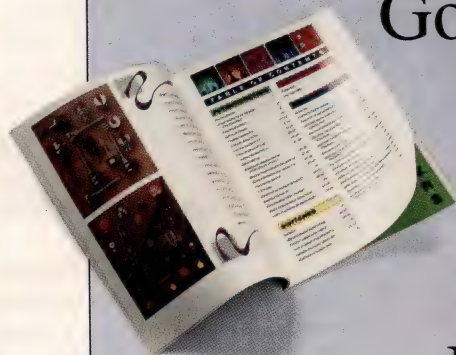
```

*
*  NODE NUMBERS
*
*      VIN
*      |
*      GND
*      |
*      TRIM
*      |
*      VOUT
*
*
.SUBCKT REF01 2 4 5 6
*
* 1.23V REFERENCE
*
I1      4 10      1.22889E-6
R1      10 4      1000E3 [TC = 3E-6]
G1      4 10      2 4 73.9E-12
F1      4 10      VS 61.5E-9
*
* INTERNAL OP AMP
*
G2      4 11      10 19 2E-3
R2      4 11      150E6
C1      4 11      2.1E-10
D1      11 12      DX
V1      2 12      1.3
*
* SECONDARY POLE
*
G3      4 13      11 0 1E-6
R3      4 13      1E6
C2      4 13      1.2E-13
*
* OUTPUT STAGE
*
ISY      2 4      0.38E-3
FSY      2 4      V1 -1
G4      4 14      13 0 25E-6
R4      4 14      40E3
R7      17 19      14.2602E3
R8      19 4      2E3
R9      19 5      50E3
R10     5 4      1E12
Q1      16 14      17 QN
VS      18 17      DC 0
L1      18 6      1E-7
*
* OUTPUT CURRENT LIMIT
*
Q2      15 2      16 QN
R6      2 16      21
R5      2 15      18E3
C3      2 15      1E-6
G5      14 4      2 15 1
*
.MODEL QN NPN(IS=1E-15 BF=1000)
.MODEL DX D(IS=1E-15)
.ENDS REF01

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The winning Design Idea for the October 24, 1991, issue is entitled "Offset varies PPL's phase shift," submitted by Donald G Stetani of LeRoy, NY.

ISSUE WINNER

The winning Design Idea for the November 7, 1991, issue is entitled "Battery charger straddles input voltage," submitted by Isaac Eng of University of Ottawa (Ottawa, Ontario, Canada).

Program mirrors brilliant circuit

Jim Williams's brilliant circuit in DI #945, "Transistor sensor needs no compensation" (EDN, April 25, 1991, pg 180), uses a transistor as a temperature transducer. It eliminates trimming by measuring the base-emitter voltage of the transistor at two different currents, and then uses the difference in V_{BE} to calculate temperatures.

For automated measurements, connect the transistor directly to a computer-controlled multimeter such as the HP-3478A and select the resistance function. The meter sources a test current through the transistor, measures the resulting voltage, and returns a reading. The HP-3478A produces a 100- μ A test current in the 30-k Ω range and 10 μ A in the 300-k Ω range.

A simple test program that makes measurements in both ranges can then calculate the temperature from

$$T(^{\circ}\text{K}) = (V_{BE}(100 \mu\text{A}) - V_{BE}(10 \mu\text{A})) / 199 \mu\text{V}.$$

The following HP-Basic program (Listing) makes two such measurements and averages them to eliminate drift. The measurement takes about 1.3 sec. An assortment of 2N2222A and 2N4401 transistors generated readings that varied over a 1 $^{\circ}$ C range—not quite as tight as Mr Williams reports.

Carl Spearow, Senior Engineer

Sundstrand Corp

4747 Harrison Ave

Rockford, IL 61125

Listing—Temperature measurement program

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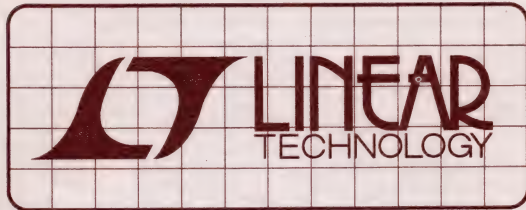
70  INTEGER I
80  Dvm=723 ! HP1B address of multimeter (DVM).
90  OUTPUT Dvm;"F3 NS D3RUNNING..." ! resistance; 5.5 digit resolution; autoz
100 FOR I=1 TO 10000
110  OUTPUT Dvm;"R4 T3" ! 30k ohm range (100uA bias); single trigger.
120  ENTER Dvm;V100u1 ! Read value from DVM.
130  OUTPUT Dvm;"R5 T3" ! 300k ohm range (10uA bias); single trigger.
140  ENTER Dvm;V10u
150  OUTPUT Dvm;"R4 T3" ! 30k ohm range (100uA bias); single trigger.
160  ENTER Dvm;V100u2
170  V100u=(V100u1+V100u2)/2 ! Average first and second 100uA readings.
180  Tk=(V100u*10-V10u)/19.9 ! Temperature in Kelvin.
190  IF Tk<173 OR Tk>500 THEN Tk=0 ! Check for measurement error.
200  PRINT USING "K,DDD.D,K,DDDD.D,K";"Temperature = ",Tk," K = ",Tk-273," de
210  NEXT I
220  OUTPUT Dvm;"D1" ! Normal display
230  LOCAL Dvm ! Return DVM to local mode.
240  END

```

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DESIGN NOTES

3V Operation of Linear Technology Op Amps – Design Note 56

George Erdi

The latest trend in digital electronics is the introduction of numerous IC's operating on regulated 3V or 3.3V power supplies. This is a logical development to increase circuit densities and to reduce power dissipation. In addition, many systems are directly powered by two AA cells or 3V Lithium batteries. Clearly, analog IC's which work on 3V with good dynamic range to complement these digital circuits are, and will be, in great demand.

Many Linear Technology operational amplifiers work well on a 3V supply. The purpose of this design note is to list these devices and their performance when powered by 3V. The op amps can be divided into two groups: single and dual supply devices. The single supply op amps are optimized for, and fully specified at, a 5V positive supply with the negative supply terminal tied to ground. Input common mode voltage range goes below ground, and the output swings to within a few millivolts of ground while sinking current. Members of the single supply family are the micropower LT1077/LT1078/LT1079 single, dual and quad op amps with 40 μ A

supply current per amplifier, the LT1178/LT1179 dual and quad with 13 μ A per amplifier. The LT1006/LT1013/LT1014 single, dual and quad have faster speed and lower voltage noise, at the expense of 300 μ A per amplifier.

The performance of these devices at 3V is quite similar to the 5V specs. Clearly, input voltage range and output voltage swing have to be reduced by 2V since the supply is 2V less. Offset voltage change from 5V to 3V is determined by the power supply rejection ratio specs. At 114dB or 2 μ V/V the degradation in offset voltage is only 4 μ V (= 2V \times 2 μ V/V). Input bias and offset currents, voltage and current noise, as well as offset voltage drift with temperature, are practically unchanged compared to the 5V specifications.

Table I summarizes the performance of the low cost grades of these single supply devices at 3V. One note of caution: the minimum operating voltage for the LT1013/LT1014 is 2.95V. All other devices work on lower supplies, ranging from 1.7V to 2.6V.

Table I. Single Supply Op Amps: Low Cost Grade Specifications $V_S = 3V$, 0V. $T_A = 25^\circ C$.

PARAMETER		LT1077CN8 LT1078CN8 LT1079CN		LT1178CN8 LT1179CN		LT1006CN8 LT1013CN8 LT1014CN		UNITS
		TYP	MIN/MAX	TYP	MIN/MAX	TYP	MIN/MAX	
Offset Voltage	Single	15	80	—	—	35	95	μ V
	Dual/Quad	45	140/170	45	140/170	95	470	μ V
Input Voltage Range		-0.3	0	-0.3	0	-0.3	0	V
		+1.8	+1.7	+1.9	+1.7	+1.8	+1.7	V
Output Swing	No Load	0.003	0.006	0.006	0.009	0.015	0.025	V
		2.4	2.2	2.4	2.2	2.4	2.2	V
	2K to Ground	0.0006	0.0010	0.0002	0.0006	0.007	0.015	V
		2.1	1.9	2.0	1.8	2.3	2.0	V
Voltage Gain	$R_L = 50K$	500	110	180	60	1000	500	V/mV
0.1Hz to 10Hz Noise		0.6	—	1.0	—	0.5	—	μ Vp-p
Minimum Supply Voltage		—	2.3	—	2.2	—	2.6/2.95	V
With 300 μ A V_{OS} Degradation		—	1.8	—	1.7	—	—	V
Gain Bandwidth Product		160	—	50	—	700	—	KHz

The LT1101 micropower ($= 75\mu\text{A}$) instrumentation amplifier completes the single supply family. Again, this in amp in 8 pin packages is fully specified at 5V. Minimum supply voltage is 1.8V; the performance change in going from 5V to 3V supply is minimal.

The second group of devices are dual supply op amps, i.e., the common mode input voltage and the output swing are limited to a diode voltage ($= 600\text{mV}$) above the negative supply terminal for proper operation. In addition, dual supply op amps are traditionally optimized for $\pm 15\text{V}$ operation. Thus, reducing the total supply voltage to 3V represents a significant change. Table II lists the performance of four op amps: the LT1008 and LT1012 are actually fully tested at reduced supplies. The LT1097 and LT1001 performance is inferred from device evaluation data. Dual versions in 14 pin packages are also available: the LT1002 is a dual LT1001; the LT1024 is a dual version of the LT1012.

In most 3V applications the single supply op amps of Table I are more flexible and desirable, since no special biasing is needed to shift the input and the output into the operating range. However, the offset voltage drift with temperature performance of the dual supply devices is better. And, most importantly, when pico-ampere input bias currents are needed, the LT1008/LT1012/LT1097 have no competition. The op amps of

Table I are all at least 6nA. The traditional ways of achieving pico-ampere bias current are not available either: JFET input or CMOS chopper-stabilized op amps do not function at 3V supply.

Figure 1 shows an application using the LT1078 to monitor the condition of the 3V battery. One output warns that the battery voltage is dropping, the other output shuts the system down as the battery voltage falls below the threshold value.

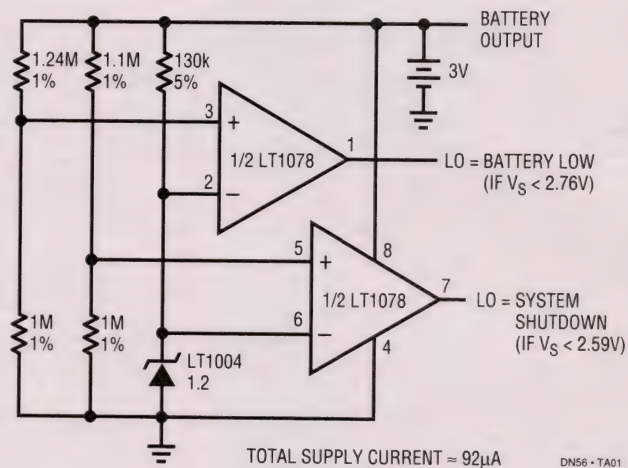


Figure 1. Low Battery Detector with System Shutdown

Table II. Dual Supply Op Amps at $V_S = 3\text{V}, 0\text{V}$. $T_A = 25^\circ\text{C}$. Low Cost Grade Electrical Characteristics.

PARAMETER	LT1097CN8		LT1008CN8		LT1012CN8		LT1001CN8		UNITS
	TYP	MIN/MAX	TYP	MIN/MAX	TYP	MIN/MAX	TYP	MIN/MAX	
Offset Voltage	20	100	40	180	25	120	40	150	μV
Drift with Temperature	0.3	1.3	0.3	1.6	0.3	1.3	0.3	1.3	$\mu\text{V}/^\circ\text{C}$
Input Bias Current	40	280	40	150	40	200	600	3500	pA
Input Offset Current	40	260	30	150	30	200	350	3200	pA
Input Voltage Range	0.65	0.80	0.65	0.80	0.65	0.80	0.75	0.90	V
	2.3	2.2	2.3	2.2	2.3	2.2	2.2	2.1	V
Output Swing	0.62	0.8	0.62	0.8	0.62	0.8	0.55	0.7	V
	2.25	2.1	2.25	2.1	2.25	2.1	2.2	2.05	V
Voltage Gain $R_L = 10\text{K}$	600	250	500	200	500	200	300	150	V/mV
0.1Hz to 10Hz Noise	0.5	—	0.5	—	0.5	—	0.35	—	$\mu\text{Vp-p}$
Minimum Supply Voltage	—	2.4	—	2.4	—	2.4	—	1.9	V
Supply Current	350	560	380	600	380	600	390	550	μA
Gain Bandwidth Product	500	—	500	—	500	—	600	—	KHz

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Intel 8032	24 MHz
Intel 80C31	32 MHz
Intel 80C32	24 MHz
Intel 80C51FA	16 MHz
Intel 80C152	16 MHz
Intel 8048/49/50	11 MHz
AMD/Siemens 80515	16 MHz
AMD/Siemens 80535	16 MHz
AMD/Siemens 80C535	16 MHz
Siemens 80537	16 MHz
Siemens 80C537	12 MHz
Siemens 80C517	16 MHz
Signetics/Philips 80C451	16 MHz
Signetics/Philips 83C451	16 MHz
Signetics/Philips 87C451	16 MHz
Signetics/Philips 80C552	16 MHz
Signetics/Philips 8XC552	16 MHz
Signetics/Philips 83C751	16 MHz
Signetics/Philips 87C751	16 MHz
AMD 80C321	16 MHz
AMD 80C325	16 MHz
AMD 80C525	16 MHz
AMD 87C525	16 MHz

Intel 8096/196

(KB, KC, KR, KQ, JR, JQ)

8096/80196	16 MHz
8098/80198	12 MHz

Zilog Z8. Super-8

Z8	20 MHz
86C94	30 MHz
Super-8	20 MHz

Texas Instruments DSP's

320C10/15	33 MHz
320C16	35 MHz
320C17	20 MHz

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8096/196
in-circuit
emulation.
... and
DSP's too!

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Signum Systems' in-circuit emulators offer more standard features than you'd expect, and some you wouldn't.

Features You'd Expect

- Windowed/mouse interface
- Flash download 115 k-baud
- Debug in C and PL/M
- Non-intrusive to target or PC
- Full speed emulation

Signum Extras

- C-51 and C-96 HLL debugger with locals support
- Full bank switching support
- Up to 256K emulation program RAM
- Graphic trigger window
- 32K x 80 real-time trace
- Access on-the-fly to:
 - All emulation RAM contents
 - 3 complex trace triggers
 - 8 level sequencer
 - Trace and execution displays
 - 256K address breakpoints
 - 2 16-bit event counters
- Performance analysis
- Unlimited user support

Performance ... Ultimately Depends on You

See what **Graphic Triggering** can do for you. For the first time you can have intuitive, precise control of the full debugging power of your emulator. You'll avoid errors and get more done.

Debugging in a High Level Language means that eventually you will have to track something right down to a member of a local complex structure. Signum lets you zoom in on any structure— **with just the click of a mouse.**

Opportunity ... The Signum Advantage

The right tools do make a difference, and there's no equality among emulators. You have to actually use them to appreciate what they can do for you. Better features that are easier to use mean you're finished sooner. That's performance, and that is exactly what we are about at Signum Systems.

Prove it to yourself, check out a Signum emulator today! Write or call to evaluate the Signum advantage.

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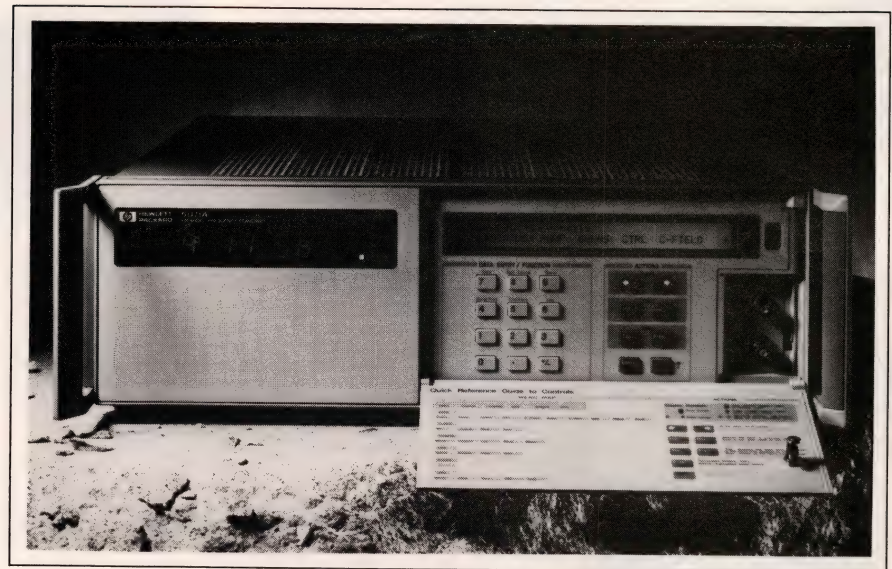
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µP-Controlled Atomic Clock

- Accurate to <1 sec in 1.6×10^6 years
- Meets specs despite variations in temperature and humidity

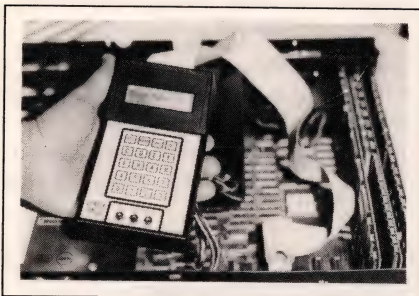
The 5071A atomic clock is five times as accurate as its predecessor, which held the record as the world's most accurate clock. Though the vendor does not guarantee the instrument to run that long, if the clock kept going for 1.6 million years, it would lose <1 sec. Averaged for >5 days, its stability is better than two parts in 10^{14} . Like its predecessors, the clock uses cesium-beam technology, but it achieves full accuracy within 30 minutes of turn-on. After warmup, the stability specs apply over a range of temperature and humidity;



most extremely accurate instruments meet their specs only under laboratory conditions. \$54,000; high-performance cesium-beam tube,

\$12,000. Delivery, 16 weeks ARO.

Hewlett-Packard Co., 19310 Pruneridge Ave, Cupertino, CA 95014. Phone (800) 752-0900. **Circle No. 405**



Logic-Debugging Tool

- Includes 32-bit digital comparator with individual masks
- Provides programmable scope trigger

The LA-32 logic debugger is a battery-powered, handheld tool for testing µP-based systems that operate at clock frequencies to 24 MHz. It incorporates a 32-bit comparator with programmable masks and set points; a generator that produces pulse trains having programmable pulse widths, pulse spacings, and numbers of pulses; and an autoranging frequency counter that can take its input from any of the instrument's inputs or the compara-

tor output. The unit, which includes a 16-character LCD, can display 32 channels at once and can produce a scope trigger upon satisfaction of conditions that you specify. In the autoselect mode, the unit automatically configures the pins of its chip clip to match the pinouts of popular EPROMs. \$379; cables and adapters, \$50 to \$75.

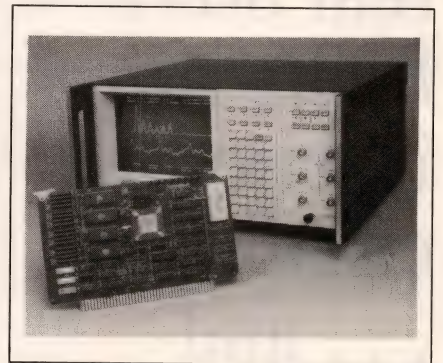
Logix Inc., 1725 Roselawn Ave W, St Paul, MN 55113. Phone (612) 646-2324. **Circle No. 406**

Waveform Analyzer With Real-Time DSP Capability

- Incorporates processor rated at 25 Mflops
- Cross-correlates two 16-ksample records in <1 sec

Using the 683 DSP board, the 6100 waveform analyzer performs signal-analysis $300 \times$ as fast as similar units not so equipped. The instrument executes more than 50 mathematical operations. It can calculate an 8k-point FFT in msec

and cross-correlate a pair of 16-ksample records in <1 sec. The heart of the board is a 32-bit floating-point DSP µP slaved to



the analyzer's CPU. The two processors exchange data via DMA and simultaneous register transfers. The analyzer, which accepts plug-in front-end modules, handles signals to 1 GHz. You can install the DSP board in the analyzer. \$2995.

Analogic Corp., 8 Centennial Dr, Peabody, MA 01961. Phone (508) 977-3000. FAX (508) 532-6097. TLX 6817144. **Circle No. 407**

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Frequency synthesizer. The DS-102 synthesizer provides two completely independent $5\frac{1}{2}$ -digit-resolution synthesizers in a 19-in.-wide enclosure. It operates from 0.1 Hz to 16 MHz. The reference is stable to ± 10 ppm from 0 to 50°C. \$1585. Delivery, six to eight weeks ARO. **Syntest Corp.**, 40 Locke Dr., Marlborough, MA 01752. Phone (508) 481-7827. FAX (508) 481-5769.

Circle No. 408

Flash-converter-based data-acquisition board. The ANA100 half-length ISA-bus board includes an 8-bit, 2.5- μ sec flash ADC and a DAC with full-scale output ranges of 2.5, 5, and 10V. \$99. **BSoft Engineering Inc.**, 444 Colton Rd., Columbus, OH 43207. Phone (614) 491-0832. FAX (614) 497-9971.

Circle No. 409

Clamp-on, true-rms digital ammeters. The 30 series permits investigating problems such as false tripping of breakers protecting nonlinear loads. They measure to 700A and handle signal components to 10 kHz. The meters also



measure frequency. Model 33 can also calculate and retain the minimum, maximum, and average values of a long sequence of readings. Model 31, \$179; Model 33, \$249. **John Fluke Mfg Co Inc.**, Box 9090, Everett, WA 98206. Phone (800) 443-5853; (206) 347-6100. FAX (206) 356-5116. TLX 185102.

Circle No. 410

Data-acquisition system. The L-Tech data-acquisition module connects to the serial port of a Macintosh or an MS-DOS-based PC. The unit includes two 14-bit ADCs that make 100,000 con-

versions/sec. The menu-based software supports many processing functions including averaging and FFTs with or without windowing. \$1995. **Onsite Instruments**, 855 Maude Ave, Mountain View, CA 94043. Phone (415) 964-9800. FAX (415) 964-9808.

Circle No. 411

Test station for mixed-signal ICs.

The mixed-signal ATS performs digital testing to 400 Mbits/sec with 100-psec accuracy. For analog testing, the system's noise floor is at least 100 dB below full scale. Analog measurements beyond 1 GHz are possible. \$630,000 for a 224-pin configuration. **Integrated Measurement Systems Inc.**, 9525 SW Gemini Dr., Beaverton, OR 97005. Phone (503) 626-7117. FAX (503) 644-6969

Circle No. 412

Data-acquisition and processing system.

The Presys 1000 system has a self-diagnostic capability that simulates the ADC's output using 16-bit counters. System with 64 channels, 500-ksample/sec ADC, 128-ksample FIFO buffer, and computer interface, \$14,200. Deliv-

A relay line designed to be



ery, five weeks ARO. **Preston Scientific**, 805 E Cerritos Ave, Anaheim, CA 92805. Phone (714) 776-6400. **Circle No. 413**

Software for disk-drive test and fault diagnosis. The GR2288 focused-application package allows suppliers of disk drives and data-storage peripherals to test the devices on the vendor's GR228X test systems. From \$210,000. Delivery, 12 weeks ARO. **GenRad Inc**, 300 Baker Ave, Concord, MA 01742. Phone (508) 369-4000, ext 2101.

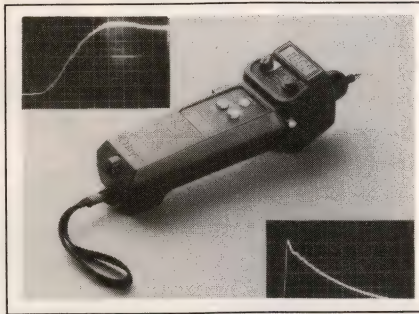
Circle No. 414

Programmable video generator. The Astro VG-815 generator allows comprehensive evaluation and testing of CRT displays. It works with displays whose horizontal-scan rates range from 10 to 180 kHz and pixel frequencies range from 5 to 135 MHz. From its front panel, you can make the generator store or recall 40 programs or patterns. The unit has RS-232C, TTL, and analog interfaces. \$5350 to \$18,950. **Team Systems**, 2934 Corvin Dr, Santa Clara, CA 95051.

Circle No. 415

MS-Windows driver for IEEE-488 bus. The Driver-488/Win dynamic-link library helps you integrate the control of IEEE-488 instruments into MS-Windows applications. The driver, which supports Microsoft and Borland languages, allows multiple tasks to access the same IEEE-488 interface card simultaneously. \$195; with interface card, \$395. **Iotech Inc**, 25971 Cannon Rd, Cleveland, OH 44146. Phone (216) 439-4091. FAX (216) 439-4093.

Circle No. 416



Handheld ESD tester. The model 6/1 Zapmaker tests devices and systems for susceptibility to electrostatic dis-

charges (ESD). The unit supplies human-body-model waveforms in accordance with draft standard MIL 1686B. Previously, competitive units used resistor and capacitor values taken from the MIL standard but did not comply with the standard's waveform requirements. \$7250. Delivery, 8 to 12 weeks ARO. **Keytek Instrument Corp**, 260 Fordham Rd, Wilmington, MA 01887. Phone (508) 658-0880. FAX (508) 657-4803.

Circle No. 417

8-to-32-channel chart recorder. The MT95K2 recorder incorporates a vacuum-fluorescent monitor and can include 64 event channels, 34 annotation channels, signal conditioning, a floppy-disk drive, a 120-Mbyte hard disk, and 32 Mbytes of RAM. The monitor makes signals immediately visible, before the chart comes into view. The maximum sampling rate is 500 ksamples/sec. The maximum chart speed is 500 mm/sec. Resolution is 300 dpi. From \$16,000. **Astro-Med Inc**, Astro-Med Industrial Park, West Warwick, RI 02893. Phone (800) 343-4039; (401) 828-4000.

Circle No. 418

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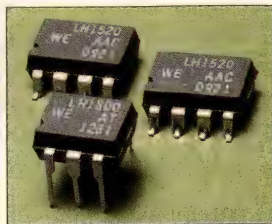
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CIRCLE NO. 79

Graphics Accelerator

- Attaches to the SBus in SPARCstation desktops
- Stand-alone tower chassis contains 40-MHz i860 CPU

The ViCOM VT is a graphics accelerator for desktop SPARCstation computers. A stand-alone chassis contains the company's ViCOM VX VMEbus graphics board and a VMEbus to SBus adapter. The adapter attaches to the SBus in a SPARCstation computer. The graphics board contains a 40-MHz i860 CPU and a 2M×8-bit frame buffer that is compatible with Sun's GX frame buffer. The accelerator drives Sun's 1152×900 and 1280×1024-pixel 19-in. monitors. In addition, the chassis has a VMEbus expansion slot that accepts the company's ViCOM MVX board. The ViCOM MVX has four i860 CPUs, which boost the accelerator's performance from 40 to 160 MIPS and from 80 to 320 peak single-precision



Mflops. ViCOM VT, \$32,000; ViCOM VX, \$24,000; optional ViCOM MVX, \$30,000.

ViCOM Visual Computing, 46107 Landing Pkwy, Fremont, CA 94538. Phone (510) 498-3200. **Circle No. 419**

Stand-Alone Single-Board Computer

- Contains an 8- or 16-MHz 80C186EB μ P
- Has four iSBX expansion ports and 512 kbytes of static RAM

The SBX-C186EB stand-alone single-board computer (SBC) for embedded applications contains an 80C186EB μ P and an 80C187 coprocessor, which run at 8 or 16 MHz. The board has as much as 512 kbytes of static RAM and 512 kbytes of EPROM or flash EPROM. Other features include an 8570 real-time calendar clock, an interrupt controller, five 16-bit counter/timers, 32 parallel I/O ports, two serial I/O ports, a watchdog timer, and power-fail detection. Its four iSBX expansion ports attach to a variety of off-the-shelf SBX modules. You can develop programs in assem-

bly code or Borland's C++ language. An optional extended temperature range is available for -40 to +85°C operation. 8-MHz version, \$425; 16-MHz version, \$465.

RLC Enterprises, 4800 Templeton Rd, Atascadero, CA 93422. Phone (805) 466-9717. FAX (805) 466-9736.

Circle No. 420

Solid-State Disk Emulator

- Transfers data at 4 Mbytes/sec on the ISA bus
- Nonvolatile-memory capacity ranges from 2 to 56 Mbytes

The Blue Flame III card emulates a solid-state disk drive in 386 and 486 ISA bus computers. Each card contains from 2 to 56 Mbytes of non-volatile memory. The card is mapped to the host's I/O space and

accepts 14 1M×9-bit or 4M×9-bit single in-line memory modules. You can install 16 cards in a system to provide a maximum capacity of 896 Mbytes/drive. The cards have a 16-bit data path and can transfer data on the ISA bus at 4 Mbytes/sec. Onboard rechargeable NiCd batteries provide backup during power interruptions, and an optional external battery provides battery backup that exceeds 100 hours. A wall-mounted power supply lets you switch off the host computer without losing data. A device driver, which occupies less than 1 kbyte of RAM, runs with PC-DOS, MS-DOS, and Concurrent DOS. \$595 for a 2-Mbyte version.

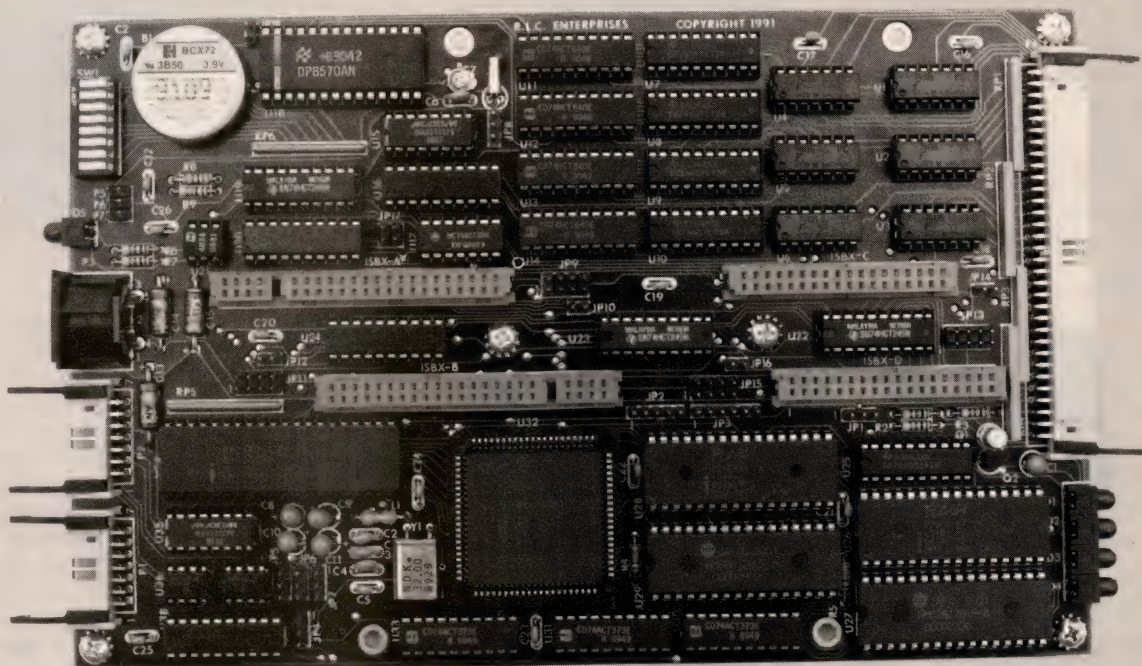
Semidisk Systems Inc, Box GG, Beaverton, OR 97075. Phone (503) 626-3104. FAX (503) 643-0625.

Circle No. 421

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80C186EB

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Compare our new **SBX-C186EB** to ANY Single Board Computer on ANY bus. Our new **Powerful, Expandable, Inexpensive, Easy to Program** Single Board Computer was designed to eliminate expensive and complicated Bus systems. All of the basic functions needed for most embedded applications are on-board. Additional I/O expansion is provided by four on-board iSBX ports which may be used to accommodate any of the iSBX modules currently available.

HARDWARE FEATURES

- * 16-Bit 80C186EB Up To 16 MHz
- * On-Board 80C187 Co-Processor
- * 8570 Real Time Clock
- * Four 8/16-Bit iSBX Expansion Ports
- * Watch Dog Timer And Power Fail Detect
- * Two Serial Ports (RS-232/422/485)
- * 10 Year Lithium Battery For RTC And RAM
- * Up To 512K Of EPROM/FLASH EPROM
- * Up To 512K Of Battery Backed Static RAM
- * 32 Parallel I/O Lines With Open-Collectors
- * Five 16-Bit Interrupt Timers
- * Program Controlled Dip-Switch And LED's
- * Available In -40 to +85 C Temperature Range



SOFTWARE FEATURES

- * On-Board FLASH EPROM Programming
- * Borland Turbo C++ Fully Supported
- * Borland Turbo Debugger Supported
- * I/O Driver Library Provided Free
- * Demo Programs Provided Free
- * No Software Royalties
- * No DOS Required

QTY(1) \$425
QTY(100) \$319
 EXCLUDING OPTIONS

Turbo C++ and Turbo Debugger may be trademarks of Borland, DOS is a trademark of IBM, iSBX is a trademark of Intel

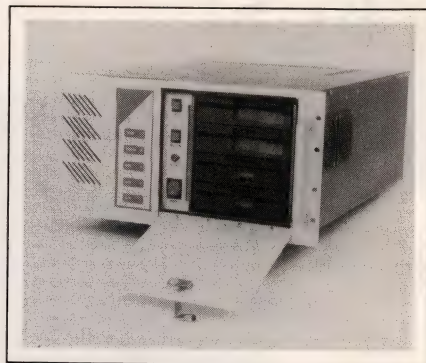
R.L.C. Enterprises

4800 Templeton Road Atascadero, CA 93422 Phone (805) 466-9717 FAX (805) 466-9736

Tape backup system. The SSCH40 4-mm digital-audio-tape backup system supports VAX cluster computers. It backs up 96 Gbytes on a 12-cartridge magazine and as much as 192 Gbytes, using a dual-drive loader configuration. The tape loader utilizes a robotic arm to insert and remove tapes in HP's 8-Gbyte, 4-mm tape drive. The system resides in a 19-in. enclosure and transfers data to and from the host at a sustained rate of 732 kbytes/sec. System

with 8-Gbyte, 4-mm drive, ST01 channel card, and a 12-cartridge magazine, \$15,340. **Emulex Corp.**, Box 6725, Costa Mesa, CA 92626. Phone (800) 854-7112; (714) 662-5600. **Circle No. 422**

19-in. rack-mount computer. Versions of the rackmountable CRM/816 industrial computer have 10, 14, or 16 ISA bus slots or 10 or 14 EISA bus slots. Modular bays let you install as

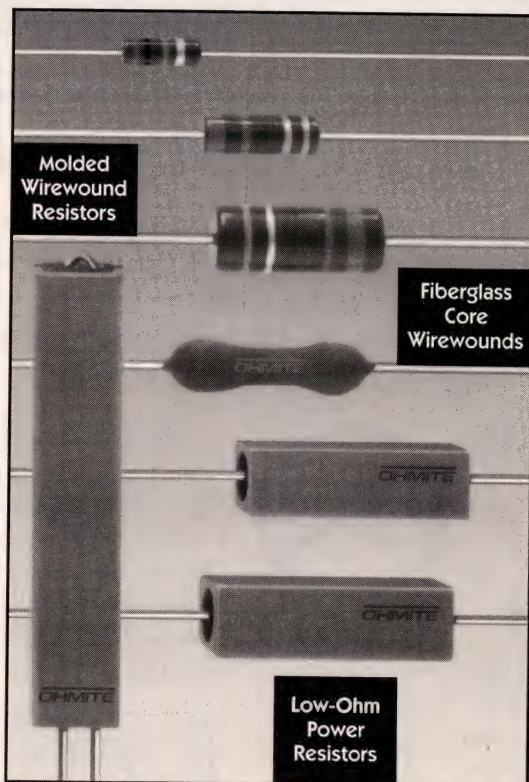


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many as eight 5¼-in. peripheral devices such as hard-disk, floppy-disk, and tape drives. Dual 70-cfm fans cool the chassis, and a 22-cfm fan cools the power supply. You can lock a front-panel door to prevent unauthorized access. Power-supply options range from 250 to 350W when using 120V ac power input. A 14-slot ISA bus version having a 250W power supply, from \$1295. **Diversified Technology Inc.**, Box 748, Ridgeland, MS 39158. Phone (601) 856-4121. TLX 585326. **Circle No. 423**

2.6-Gbyte tape drive. The Ciera 2.6 tape drive offers 2.6 Gbytes of storage on an 8-mm tape cartridge. The subsystem comes with a host adapter, which fits in a workstation's expansion slot; it also provides cable, software, and documentation. The drive transfers data at 800 kbytes/sec and supports Novell and Unix client/servers. \$6995. **Cipher Data Products Inc.**, 10101 Old Grove Rd, San Diego, CA 92131. Phone (619) 693-7713. **Circle No. 424**

Motion controller. The DMC-120-10 STD Bus board has a μ P that controls two independent axes of motion. The μ P decodes position feedback signals, generates velocity profiles, and provides a PID (proportional-integral-differential) filter for the control-loop error signal. You specify the position, speed, and acceleration for each axis using 2-letter ASCII commands. The controller produces motor drive signals in the ± 10 V range. \$595. **Galil Motion Control Inc.**, 575 Maude Ct, Sunnyvale, CA 94086. Phone (408) 746-2300. FAX (408) 746-2315. **Circle No. 425**

SCSI host adapters. The DTC 3182 and DTC 3282 host adapters support direct-memory-allocation transfers on the 16-bit ISA bus. They control seven SCSI devices; the DTC 3282 controls four additional floppy-disk drives. The

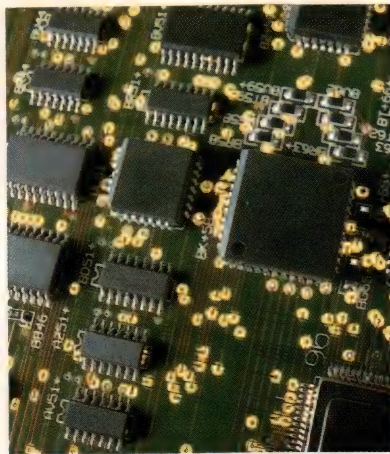


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GE Electromaterials

boards feature scatter-gather or bus-master transfers on the host bus and operate with DOS, OS/2, Unix, Xenix, and Netware software. Features include a custom μ P, a SCSI chip, and a 15-byte FIFO buffer to provide continuous data transfer to each drive. DTC 3182, \$159; DTC 3282, \$189 (OEM qty). **Data Technology**, 500 Yosemite Dr, Milpitas, CA 95035. Phone (408) 262-7700. FAX (408) 942-4052. TWX 910-338-0232.

Circle No. 426

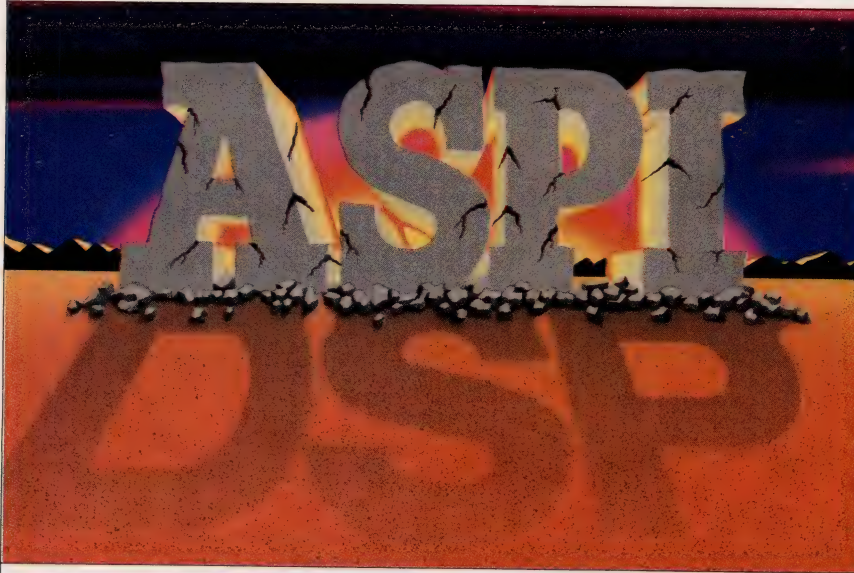
Industrial PC card. The 5016 Micro PC is a half-length ISA bus card containing an IBM PC/AT-compatible computer. It operates over the industrial temperature range of -40 to $+85^{\circ}\text{C}$. One solid-state disk contains DOS 3.31, and two additional solid-state disks are available for adding RAM and EPROM. The card has 4 Mbytes of dynamic RAM, as well as a COM1 serial port, keyboard port, speaker port, watchdog timer, calendar/clock, and coprocessor

socket. \$595. **Octagon Systems Corp**, 6510 W 91st Ave, Westminster, CO 80030. Phone (303) 430-1500. FAX (303) 426-8126.

Circle No. 427

Fiber-optic data-link adapter. The AC40 adapter permits devices having an RS-485 port to communicate over a fiber-optic link. It also has a host fiber-link port, and a repeater fiber-link port. Features include 115.4-kbaud communications; 4-km distance between nodes; ST style fiber-optic connectors; and 2- or 4-wire hook-up to the RS-485 port. The unit comes in a metal enclosure. \$550. **Opto 22**, 43044 Business Park Dr, Temecula, CA 92590. Phone (800) 321-6786; (714) 695-9299. FAX (714) 695-2712.

Circle No. 428



Each technological terrain has its most prominent landmark

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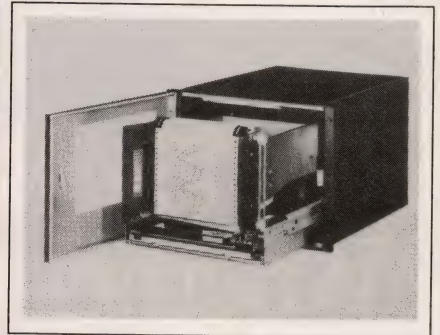
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CIRCLE NO. 83



Industrial printer. The IP-80 printer uses a 9-pin dot-matrix mechanism to print bidirectionally at 200 cps. It mounts in control panels or on a standard 19-in. rack. The unit has a Centronics parallel port, a 4-kbyte buffer and 24 resident fonts; an RS-232C serial port is optional. \$2395. **Dianachart Inc**, 101 Round Hill Dr, Rockaway, NJ 07866. Phone (201) 625-2299. FAX (201) 625-2449.

Circle No. 429

Communications modules. The E-PAK family of modules extends the capabilities of the company's VMEbus single-board computers. The Model D contains a Zilog Z16C35 IC to manage four synchronous serial I/O ports at 1 Mbps. The Model E has a 79C900 32 IC to communicate with an Ethernet 10Base-T network. The Model F contains both Model D and F functions. The Model G has a Cirrus CL-CD180 IC to manage 16 asynchronous serial I/O ports. Model D, \$560; Model E, \$485; Model F, \$795; Model G, \$485 (100). **Performance Technologies Inc**, Computer Products Div, 315 Science Pkwy, Rochester, NY 14620. Phone (716) 256-0200.

Circle No. 430

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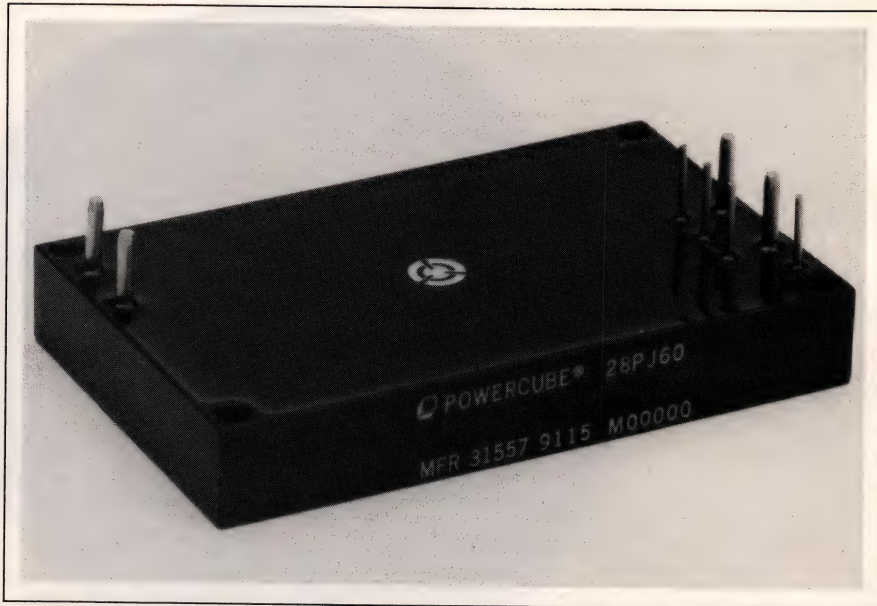
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Components & Power Supplies

DC/DC Converters

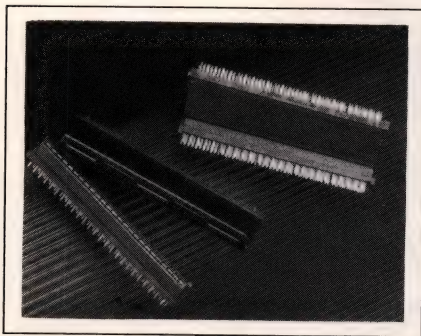
- Have 60 W/in.³ density
- Develop a single output

PJ Series dc/dc converters develop a 210W output from a package measuring 2×3.5×0.5 in.—60W/in.³ power density. They use integrated magnetics and feature efficiencies ranging to 87%. The converters operate from an input range of 20 to 36V as designated in MIL-STD-704D and are available in versions with regulated outputs of 5, 12, 15, and 28V. They can operate in parallel and feature remote shut-down, remote sensing, external trimming, current limiting, and overvoltage protection. Module components have been derated to meet or exceed NAVSO P-3641 guidelines from -55 to +100°C. Output ripple measures 80 mV p-p max, and temperature coefficient



equals 0.008%/°C. Line and load regulation are 0.2%, and MTBF equals 1.2×10^6 hours min. From \$500.

Powercube Corp, 8 Suburban Park Dr, Billerica, MA 01821. Phone (508) 667-9500, ext 324. FAX (508) 667-6280. **Circle No. 392**



PC-Board Connector

- Emulates a stripline
- Has a 50Ω impedance

The FCN260 half-pitch (0.05-in.) pc-board connector emulates a stripline circuit. The design minimizes crosstalk to 3.8% max at a 1-nsec rise time by confining the signal conductor with a ground plane. Characteristic impedance, achieved by controlling the dimensions, construction, and insulator permittivity, equals $50\Omega \pm 10\%$. Connector construction consists of large ground planes on the center line and a metal ground shell around the

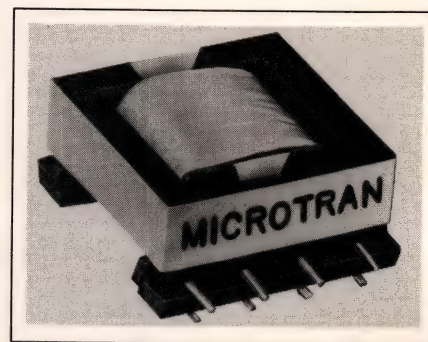
plug. This construction maintains signal integrity across the board and eliminates the need for dedicated ground contacts—all contacts function as signal contacts. The connector is available in a 100-pin version. Plug-and-jack pair, \$0.20 per mated line (2500).

Fujitsu Microelectronics Inc, Electronic Components Div, 3545 N First St, San Jose, CA 95134. Phone (800) 642-7616; (408) 922-9000. **Circle No. 393**

Surface-Mount Transformers

- Feature a low profile
- Have a 300- to 3500-Hz response

TS3000 Series surface-mount transformers meet FCC Part 68 regulation. Their mounted height is 0.32 in. The units are designed for dry-circuit, 600Ω line applications. They have a ± 0.5 -dB frequency response of 300 to 3500 Hz over a -45 to +7-dBm power-level range. The transformers are available for both



coupling and hybrid applications. They feature 0.5% max distortion, 26-dBm return loss, 60-dB min longitudinal balance, and 1500V rms dielectric strength. The transformers are constructed from materials that have a UL 94V-0 flammability rating. Units with pins for through-hole-mounting applications are also available. The units measure $0.87 \times 0.66 \times 0.32$ in. and weigh 0.2 oz. Approximately \$3 (OEM qty).

Microtran Co, Box 236, Valley Stream, NY 11582. Phone (516) 561-6050. FAX (516) 561-1117.

Circle No. 394

Oh no. Please, not now. Not with manufacturing release next week.

THE PROTOTYPE DOESN'T WORK.

Six ASICs, fifteen PLDs and the whole thing's gone south. Maybe I should go south too. Yeah, hop a bus. Head for Mexico.

THE PROTOTYPE DOESN'T WORK.

Software? Could be. Hardware? Might be. So where do I start? At the beginning, of course. And just where is that, smart guy?

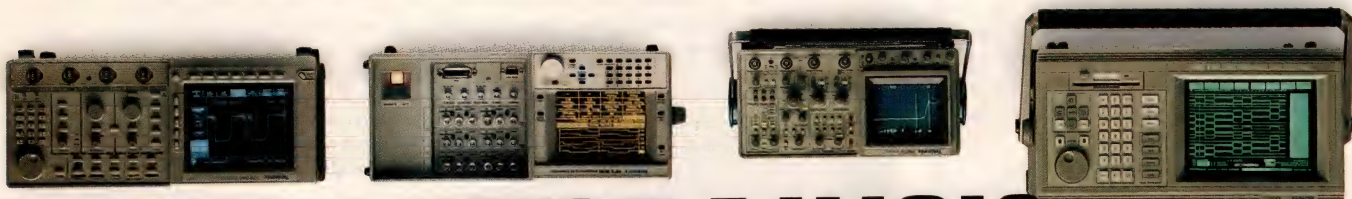
THE PROTOTYPE DOESN'T WORK.

And my performance review comes up next month. Maybe they'll just forget about all this, right? Yeah. Sure.

THE PROTOTYPE DOESN'T WORK.

Wait. What about that glitch in the handshake on the first pass? Couldn't reproduce it. Maybe it just reproduced itself.

THE PROTOTYPE DOESN'T WORK.



These are just a few of the reasons Tek makes a complete line of scopes, logic analyzers and signal

sources. Instrumentation that can quickly get to the core of your prototype's problems. Whether they're digital, analog

or software. Because even when your prototype doesn't work, Tek does. **Talk To Tek/1-800-426-2200**

Tektronix

Test and Measurement

CIRCLE NO. 85

EDN February 17, 1992 • 181

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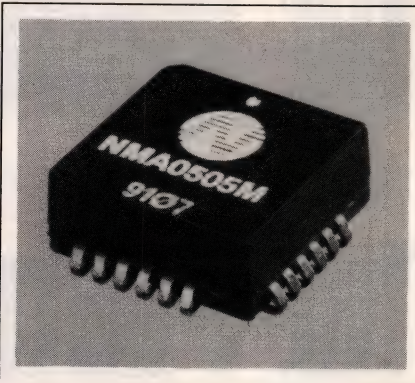
EDN-NEW PRODUCTS

Components & Power Supplies

Ethernet transceiver. The ENT-4312 transceiver allows you to establish a 10BaseFL data link or fiber-optic inter-repeater link (FOIRL) through a user-selectable switch. Various interface options are available via an onboard SQE (signal-quality-error) switch. Other features include ST or SMA type connectors and a set of seven diagnostic LEDs, which indicate link status jabber, collision, receive, transmit, SQE, and power. The transceiver measures $1.75 \times$

0.92×3.8 in. and weighs 2.34 oz. \$295. **Lancast**, 10 Northern Blvd, Unit 5, Amherst, NH 03031. Phone (800) 752-2768; (603) 880-1833. FAX (603) 881-9888. **Circle No. 395**

DC/DC converters. NMA surface-mount dc/dc converters are housed in a J-leaded package, which measures $11.81 \times 11.81 \times 6.09$ mm. The units accept 5 or 12V inputs and offer outputs

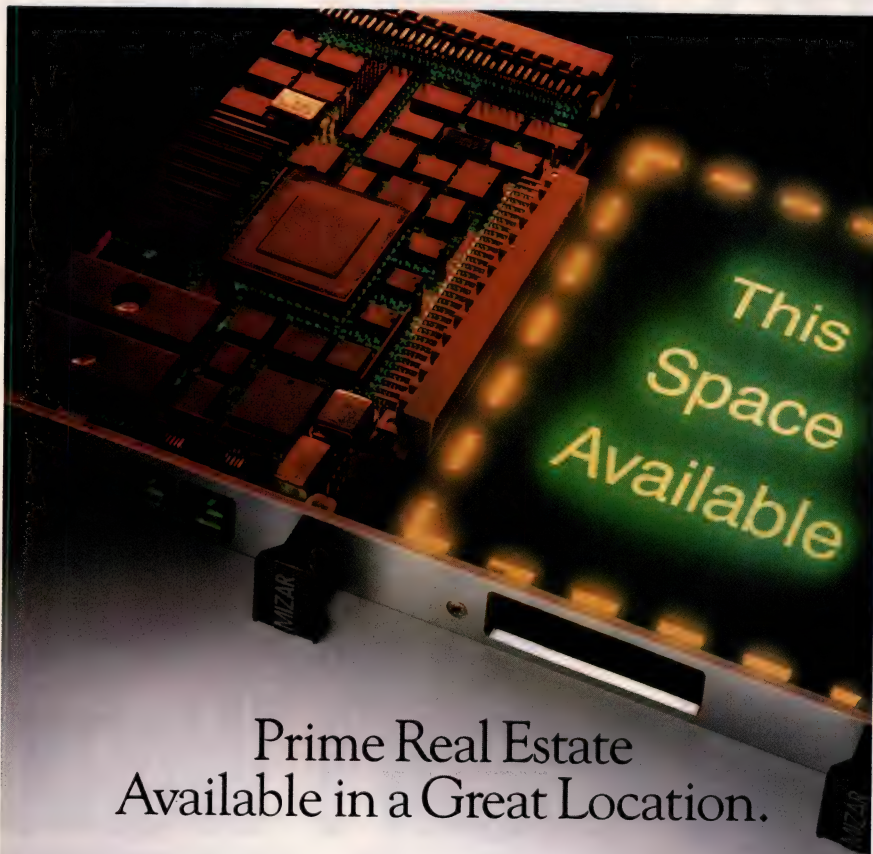


of ± 5 , ± 9 , ± 12 , or ± 15 V. Each output provides 1W of output power. The converters feature 1000V dc isolation, 80% efficiency, and operate over a -50 to $+85^\circ\text{C}$ range with no derating. \$19.50. **International Power Sources Inc.**, 200 Butterfield Dr, Ashland, MA 01721. Phone (508) 881-7434. FAX (508) 879-6669. **Circle No. 396**

Multichip module socket. This multichip-module socket is designed for a 256-pin, 0.65-mm, 45×45 -mm body. It's suitable for high-density test and burn-in applications and features a novel lid, which simultaneously distributes a uniform mating force along all four package sides. Insulators are made of PPS (polyethersulfone), and contacts are beryllium copper with gold over nickel plating. \$162.92 (100). **Nepenthe**, 2479 E Bayshore Rd, Suite 800, Palo Alto, CA 94303. Phone (800) 637-3684; (415) 496-6666. FAX (415) 856-8650. **Circle No. 397**

Extraction tool. The CT-2102 tool accommodates 4-sided plastic-leaded-chip-carrier (PLCC) packages having from 20- to 124-pin leads spaced on 0.05-in. centers. The tool precisely borders the object chip only—without interference with any components surrounding the PLCC socket. \$16. **Method Electronics Inc.**, 1700 Hicks Rd, Rolling Meadows, IL 60008. Phone (800) 323-6864; (708) 392-3500. **Circle No. 398**

Coaxial attenuator. Model PE7022 is a 50 Ω , 100W coaxial attenuator. Designed for operation over a dc to 1.5-GHz range, the device is available with attenuation values of 6, 10, 20, 30, and 40 dB. The attenuator features a built-in heat sink. VSWR equals 1.15:1 max, and operating range spans -65 to $+125^\circ\text{C}$. \$350. **Pasternack Enterprises**, Box 16759, Irvine, CA 92713. Phone (714) 261-1920. **Circle No. 399**



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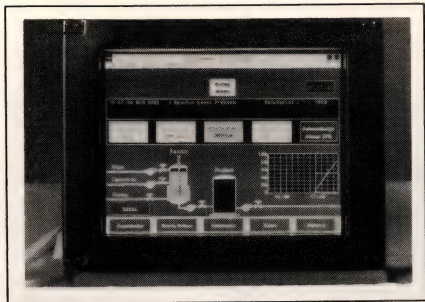
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1-800-635-0200 FAX 214-242-5997

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CIRCLE NO. 86



Flat-panel touch system. Modular/1 and Modular/2 infrared touch systems are available with software-based, hardware-based, or RS-232C controllers. Each controller is equipped with digital circuitry and provides plug-and-play capability. Both systems feature servo-loop circuitry that compensates for environmental factors. Programmable amplification makes both systems impervious to severe ambient light conditions. Modular/1, \$285; Modular/2, \$289 (100). **Carroll Touch Inc.**, Box 1309, Round Rock, TX 78680. Phone (512) 388-5614. FAX (512) 244-7040.

Circle No. 400

Pulse transformers. Housed in a package measuring $0.65 \times 0.85 \times 0.2$ in., these pulse transformers suit either through-hole or surface-mount applications. The units meet applicable provisions of MIL-T-21038 and are characterized for operation over a -55 to $+125^\circ\text{C}$ range. They support $2500\text{V}/\mu\text{sec}$ and feature rise times of less than 100 nsec. \$25 (OEM qty). Delivery, stock to eight weeks ARO. **Controlex Corp.**, 16005 Sherman Way, Van Nuys, CA 91406. Phone (818) 780-8877.

Circle No. 401

Coaxial attenuators. Series 2082 5 and 10W coaxial fixed attenuators are designed for dc to 18-GHz operation. Standard units with SMA connectors are available in 3-, 6-, 10-, and 20-dB attenuation values. The 5W unit is also available in 30-dB versions. The manufacturer uses no hazardous beryllium oxide in constructing the device. 5W version, \$77; 10W version, \$162. **MA/COM**, Control Components Div, 21 Continental Blvd, Merrimack, NH 03054. Phone (603) 424-4111. FAX (603) 424-6580.

Circle No. 402

R and C networks. MRGF Series resistor networks come in 16-pin SOIC packages and feature resistor values from 33Ω to $2.2\text{M}\Omega$. Five circuit con-

figurations are available: as many as 8 isolated double-ended resistors or 15 single-ended resistors with a common tap; ladder networks; divider networks; and terminator arrays. Temperature coefficient equals ± 200 ppm/ $^\circ\text{C}$, and power rating at 70°C measures $500\text{ mW}/\text{package}$. \$0.30 (10,000). Delivery, eight weeks ARO. **Raltron Electronics Corp.**, 2315 NW 107th Ave, Miami, FL 33182. Phone (305) 593-6033. FAX (305) 594-3973.

Circle No. 403

Miniature shunts. SNM Series microshunts mate with 0.018-in. square headers with pins located on a 0.05×0.1 -in. grid. The terminals can pass through the shunt so the shunt can accept any post that has a minimum height of 0.12 in. The shunts are available with gold or tin plating over the phosphor-bronze contacts. From \$0.088. **Samtec Inc.**, Box 1147, New Albany, IN 47151. Phone (800) 726-8329; (812) 944-6733.

Circle No. 404

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- 100 Hz to 100 kHz measurement frequency
- Two 5 digit displays for simultaneous readout of major and minor parameters.
- Auto, R+Q, L+Q, C+D, C+R, Series and Parallel measurement modes
- 100 mV to 1.0 V test signals
- Internal and External Bias
- Binning and Limits for production testing and component inspection.
- RS232 interface
- GPIB and Handler interface (optional)

SR715 **\$1495**

- Same as SR720 except:
- 0.2% basic accuracy
- 100 Hz to 10 kHz measurement frequency



STANFORD RESEARCH SYSTEMS

1290 D Reamwood Avenue, Sunnyvale, CA 94089
TEL (408)744-9040 FAX 4087449049 TLX 706891 SRS UD
CIRCLE NO. 87

Low-Power, High-Speed 12-Bit ADC

- Includes on-chip S/H amplifier
- Has 750-ksample/sec speed

The 12-bit AD7886 A/D converter combines a fast sampling rate of 750-ksamples/sec with 350-mW power consumption. The ADC features a triple-pass flash architecture that provides a data-access time of 57 nsec and a total conversion time of 1 μ sec. These characteristics make the device suitable for use in high-frequency instrumentation applications. Other guaranteed ac characteristics include integral nonlinearity of ± 2 LSB (max), a S/N ratio of 65 dB, and total harmonic distortion of -75 dB. Second- and third-order intermodulation distortion are typically

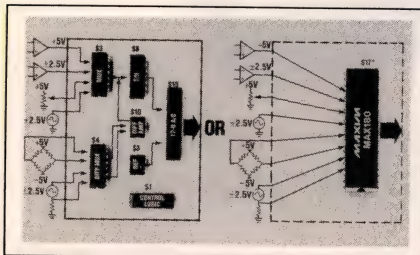


-80 dB. The AD7886 operates from ± 5 V supplies and offers pin-strappable input spans of 0 to 5V, 0 to 10V, and ± 5 V. Package options include 28-pin DIPs and plastic

leaded chip carriers. From \$55 (100).

Analog Devices, 181 Ballardvale St, Wilmington, MA 01887. Phone (617) 937-1428. FAX (617) 821-4273.

Circle No. 358



8-Channel, 12-Bit Data-Acquisition System

- Has a programmable multiplexer
- Sampling rate is 100 kHz

The MAX180, a 100-kHz data-acquisition system, includes a 12-bit ADC, a 6-MHz track-and-hold (T/H) amplifier, a -5 V (25-ppm/ $^{\circ}$ C) reference, a parallel μ P interface, and an 8-channel multiplexer. The multiplexer allows independent programming of each channel for either differential or single-ended inputs, and unipolar 5V or bipolar ± 2.5 V operation. The T/H amplifier's bandwidth allows undersampling of periodic signals having bandwidths exceeding the ADC's sample rate. You can use a reference input supplied by the internal reference or

an external source. The internal reference value and the system offset are adjustable to allow nulling of the overall system offset and gain errors. The MAX180 interfaces to 8- or 16-bit buses and operates from 5 and -12 V supplies. The device is available in 40-pin DIPs and 44-pin plastic leaded chip carriers. From \$17 (1000).

Maxim Integrated Products, 120 San Gabriel Dr, Sunnyvale, CA 94086. Phone (408) 737-7600.

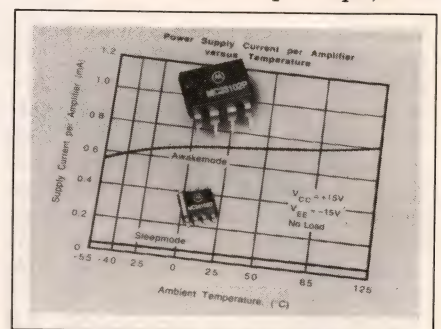
Circle No. 359

Dual Op Amp With Micropower Sleep-Mode

- Reduces current drain to 45 μ A
- Has industry-standard pinouts

Suiting a range of applications such as cordless telephones, portable computers, and handheld equipment, the MC33102 dual op amp features a "sleep" mode that reduces current drain to approximately 45 μ A/amplifier. Triggered by an input signal, each amplifier changes to the "awake" mode in 4

μ sec when output current exceeds 160 μ A. The device returns to the sleep mode when the output current drops below its threshold. Each amplifier consumes approximately 750 μ A when operating in the awake mode, with a $\times 10$ improvement in bandwidth and slew rate. You can also use the device as a micropower amplifier. ESD clamps protect the inputs. A drop-in replacement for many other dual op amps, the



MC33102 comes in 8-pin DIP and SO packages. \$1.60 (10,000).

Motorola Semiconductor, EL340, 2100 E Elliot Rd, Tempe, AZ 85284. Phone (602) 897-3615. FAX (602) 897-4193.

Circle No. 360



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The SPARC™ CPU-1E engine. It's a complete implementation of SPARCstation™ 1, fully supported by the powerful SunOS™ and the real-time expertise of FORCE.

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The SPARC CPU-1E accommodates up to 80 Mbytes of DRAM. You can run real-time, UNIX®, Sun Windows™ and utility programs. Standard DMA-driven SCSI and Ethernet interfaces give you full network access. There's even an SBus™ interface for I/O expansion.

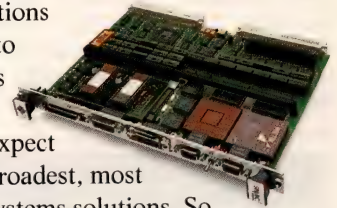
We also provide such leading real-time operating systems as VxWorks™, VADSWorks™, VRTX™, MTOS™, PDOS™ and OS-9/9000™ products. Along with over 2100 third-party applications from Sun's Catalyst™ program.

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OUR NEW PARTNERSHIP IS AS HOT AS IT GETS.

CIRCLE NO. 54



Communications controller. The COM20010, a token-passing communications controller, is targeted for high-speed data highways in factory process controls and building automation applications. You can use the device with coaxial, twisted-pair, or fiber networks. The controller interfaces with Intel, Motorola, Zilog, and NEC microcontrollers. A 1k x 8-bit RAM handles message storage. The device supports as many as 255 nodes at a data rate of 2.5 Mbps.

From \$11.36 (1000). **Standard Microsystems Corp.**, Component Products Div, 35 Marcus Blvd, Hauppauge, NY 11788. Phone (516) 273-3100.

Circle No. 361

Light sensor. Linking directly to a microprocessor (μ P), the TSL220 light-to-frequency converter converts small changes in light intensity to digital signals. The device, which has a dynamic



range of 118 dB, typically produces a 100-kHz signal in office desk lighting and 1 Hz in darkness. An external capacitor can adjust the output frequency for a given light level to match the sensor to the input frequency range of a μ P. \$4.61 (1000). **Texas Instruments Inc.**, Semiconductor Group (SC-91086), Box 809066, Dallas, TX 75380. Phone (800) 336-5236, ext 700; outside US and Canada, (214) 995-6611, ext 700.

Circle No. 362

Triport bus exchanger. The IDT 73720 is a 16-bit triport bus exchanger for interbus communication in multiway interleaving memory systems and in high-performance multiplexed address and data buses. The device, which features a maximum port-to-port delay of 6.5 nsec, supports bidirectional read and write operations between the CPU and two memory ports, eliminating bus contention. 68-pin plastic leaded chip carrier, \$9.70 (100). **Integrated Device Technology**, Box 58015, Santa Clara, CA 95052. Phone (408) 727-6116. FAX (408) 492-8674.

Circle No. 363

Smartcard microcontrollers. The ST16623 and ST16301 combine an 8-bit CPU with on-chip ROM, RAM, EEPROM, and hardware and software security features. The 16623 and 16301 offer 6 and 3 kbytes of ROM, 224 and 126 bytes of RAM and 3 and 1 kbytes of EEPROM, respectively. The devices have a 5-MHz operating speed and are available in die or micromodule form. ST16301, \$2.78; ST16623, \$3.82 (5000). **SGS-Thomson Microelectronics**, 1000 E Bell Rd, Phoenix, AZ 85022. Phone (602) 867-6100. FAX (602) 867-6290.

Circle No. 364

Servo driver/controller chip set. This 2-chip set is for 2.5-in. hard-disk drives. The SSI-32H6510 servo driver is for systems employing linear or rotary

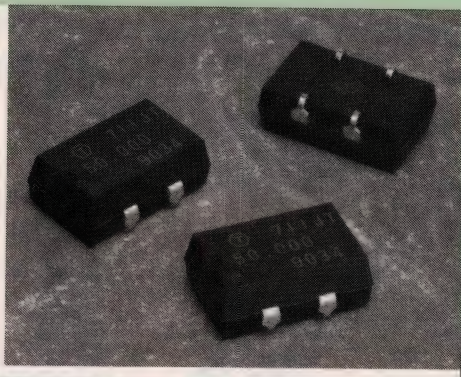
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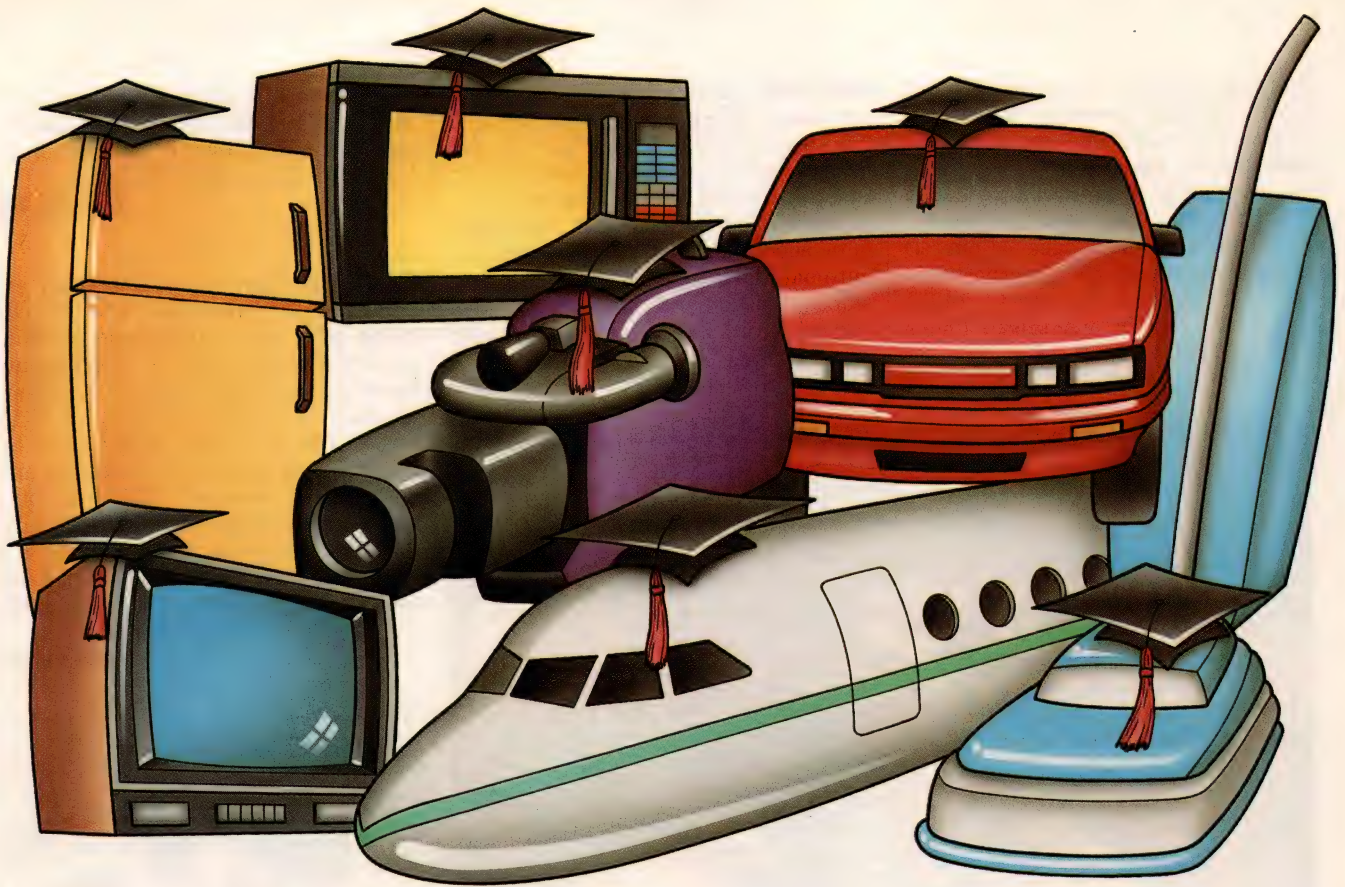
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TIMING IS EVERYTHING

CIRCLE NO. 92



How single-chip fuzzy logic can move your product to the head of its class

Need to make your product more intelligent? Fuzzy Logic is the solution of choice. Need to do it quickly and economically, with maximum flexibility? Then the NeuraLogix NLX230 Fuzzy MicroController™ is in a class by itself!

The NLX230 is a single-chip solution. One 40-pin package delivers Fuzzy Logic mastery to the most complex control problems.

The NLX230 is flexible. It can be easily configured for your specific control problem, usually in a matter of hours.

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voice-coil motors. The SSI-32H6520 servo controller provides four area-detection circuits and includes embedded-servo burst processing, fault-detection logic, D/A circuitry, and a CPU/DSP bus interface. Driver and controller chips in 36- and 44-pin SO packages, \$3.50 and \$5.50, respectively (10,000). **Silicon Systems**, 14351 Myford Rd, Tustin, CA 92680. Phone (714) 731-7110. FAX (714) 669-8814.

Circle No. 365

SCSI disk controller. The AIC-8010 automated SCSI controller is for 1.8-, 2.5-, and 3.5-in. SCSI and SCSI-2 disk drives. Key features include automating SCSI operations through hardware implementation and control, full-track data access without μ C intervention, automated buffer management, constant-density recording with embedded servo control, and 88-bit Reed-Solomon error correction. The AIC-8010 supports SCSI-2 data transfers of 10 Mby-

tes/sec and disk NRZ data rates of 36 MHz. In a 100-pin quad flatpack, \$18.95. **Adaptec**, 691 S Milpitas Blvd, Milpitas, CA 95035. Phone (408) 945-8600.

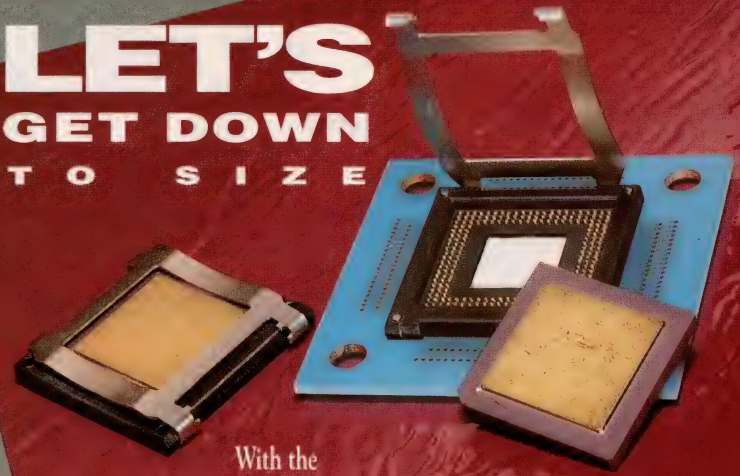
Circle No. 366

Graphics chip. Compatible with existing MS-DOS programs, the OTI-087 24-bit color chip can increase graphics performance as much as 10 times and boost the speed of Windows programs as much as 5 times over existing VGA chips. The chip obtains its speed by communicating directly to 80386 and 80486 CPUs over the 32-bit local bus, instead of through the 16-bit AT bus. Available in a 160-pin quad flatpack, \$31 (1000). **Oak Technology Inc.**, 139 Kifer Ct, Sunnyvale, CA 94086. Phone (408) 737-0888. FAX (408) 737-3838.

Circle No. 367

CIN::APSE

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With the
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low profile
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Socket

Today, Cinch provides all the functional advantages you need in one small, highly reliable package – the extremely low profile Cinch LGA Socket. It was specifically designed to interface the Intel386™ SL microprocessor device – or others in the same package – to a printed circuit board without solder.

The Cinch LGA Socket provides optimum performance in applications where space, weight, thermal management and ease of assembly are critical. Utilizing Cinch's patented CIN::APSE technology with low inductance contacts on .050 inch centers, the Socket is appropriate for use in high-speed, dense and hostile environments.

Two mounting types are available – both utilizing the Intel-recommended footprint. One uses conventional mounting hardware; the other, a unique push-pin technique allowing for socket assembly without access to the board's underside. The overall mounted height of the Socket (above the printed circuit board), including the package and integral compression spring cover, is less than .200 inches.

For more information about the new Cinch LGA Socket and your free CIN::APSE Design Guide, call 708.981.6000, Ext. 4291.

CINCH Connectors, 1500 Morse Avenue,
Elk Grove Village, IL 60007.

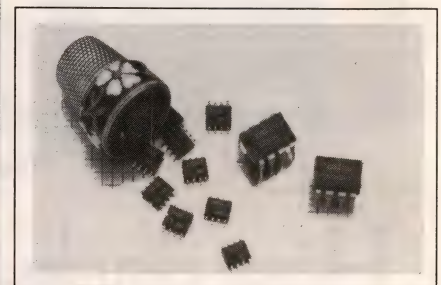
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CINCH

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CIRCLE NO. 93

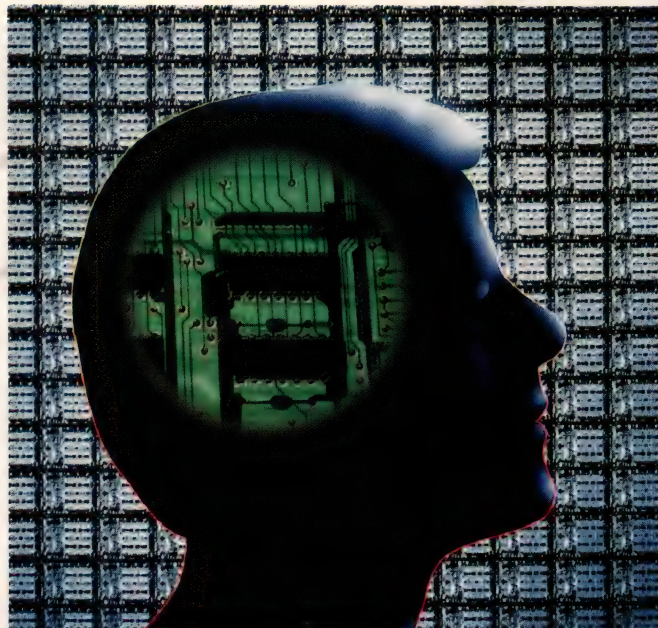


I²C EEPROMs. Compatible with the 2-wire I²C bus, the XL24C04 operates from a 5V supply and features a V_{CC} lockout to ensure data integrity during power-up and power-down cycles. The companion XL24C04-3 has a range of 2.7 to 5.5V for battery operation. Internally organized as 256 × 8 bits, the low-power devices draw only 1 mA (active) and 2 μ A (standby). A 16-byte page-write mode and a self-timed write cycle minimize the total-per-byte write time. In 8-pin DIP and SO packages, the XL24C04 and XL24C04-3, \$1.49 and \$1.94, respectively, (10,000). **Exel Microelectronics**, Box 49038, San Jose, CA 95161. Phone (408) 432-0500. FAX (408) 434-6444.

Circle No. 368

Dual-port video RAMs. Available in two versions, these 2-Mbit video RAMs can handle the high-speed data and fast display-refresh rates inherent in advanced graphics applications. Both the fast-page version (μ PD482234) and the hyper-page version (μ PD482235) include dual ports. With one port for the CPU and one for the display, processor efficiency is doubled. The devices come in 40-pin SOJs and ZIPs, and 44-pin

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Reduce interference problems and costs at their source: The initial design and material selection stage.

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When a system exceeds restrictions, designers are often forced to trade efficiency for acceptable EMC performance—with undesirable results. As a finished design is modified to accommodate necessary remedial shielding measures, weight and volume inevitably increase, and overall efficiency drops.

Planned EMC controls and testing during the design phase, on the other hand, not only help you maintain the in-

tegrity of the original design, but allow modifications in favor of greater system efficiency. In computer design, for example, EMC considerations such as selecting lower clock frequency, maintaining the smallest possible circuit layout areas, utilizing multi-layer boards, and minimizing the use of multiple shielding all contribute to optimum design efficiency.

The three EMC design techniques.

Achieving EMC is largely a function of three control techniques: Suppression, Isolation, and Desensitization. Through a combination of these methods, undesirable signals (EMI/RFI) are suppressed at their origin...generating circuits are isolated...and susceptible circuits are desensitized. When applied from the beginning, these techniques help you create fully integrated designs that offer both optimum performance and the best possible production economies.

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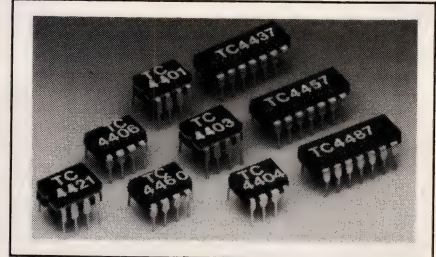
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TSOPs. \$30. NEC Electronics Inc, Box 7241, Mountain View, CA 94039. Phone (415) 960-6000.

Circle No. 369



Power drivers. The TC4421 and TC4422 can drive large MOSFETs or IGBTs (insulated gate bipolar transistors) at 9A at high speed. The TC44xx family includes quad drivers with current ratings of 1.2A and switching times of 20 nsec, as well as open-drain drivers with current ratings of 1.5 to 6A and switching times of 25 nsec. All of the drivers feature ESD protection on every pin. In 8- and 14-pin packages, \$2.95 (1000). **Teledyne Components**, 1300 Terra Bella Ave, Mountain View, CA 94039. Phone (800) 888-9966; (415) 968-9241.

Circle No. 370

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TK114xx



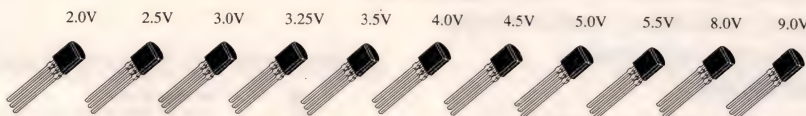
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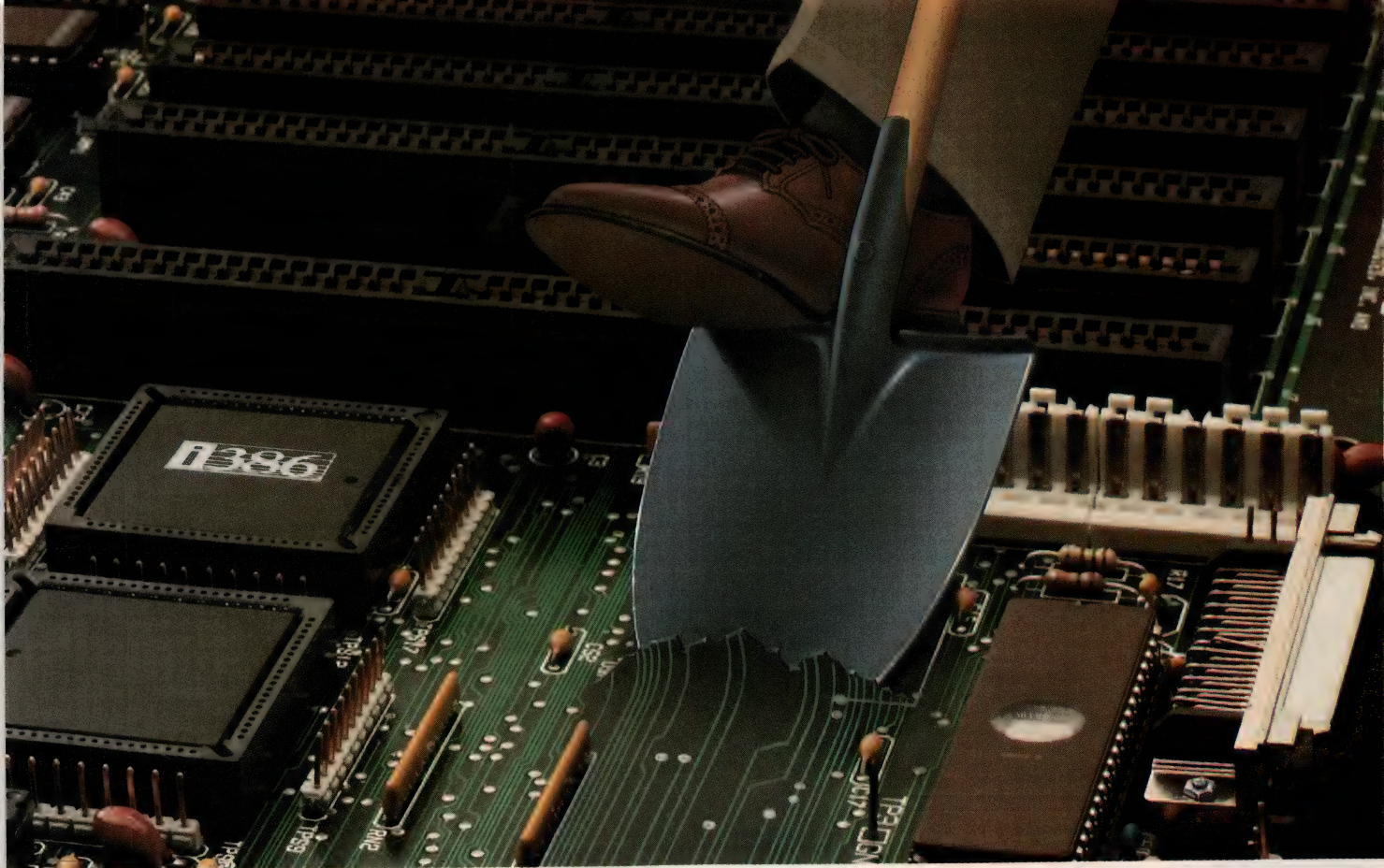
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code can be denser, more reliable, and easier to maintain. The software consists of an application-builder module, which provides project management on 80386- and 80486-based computers, and an application server. The server is a computer-dependent runtime module that loads the interface descriptions, paints the displays, and receives and interprets messages from the operating system. Application-builder module, \$995; application server, \$495.

Guideware Corp., 2483 Old Middlefield Way, Suite 224, Mountain View, CA 94043. Phone (415) 969-6851.

Circle No. 371

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- *Has an X-Window graphical interface*
- *Supports software, electronic, and mechanical engineering projects*

The Teamnet Unix-based configuration- and data-management tool tracks and controls files around an NFS (Network File System) Network. The software is based on an Openlook graphical user interface. The software resolves file sharing and edit conflicts using a 2-phase mechanism for checking in changes and managing your work area. File-merge capabilities allow a visual side-by-side comparison of conflicting file changes. A virtual-copy capability improves software performance in creating work areas, checking in changes, and building baselines. License, from \$3000.

TeamOne Systems Inc., 710 Lakeway Dr, Sunnyvale, CA 94086. Phone (408) 730-3500. **Circle No. 372**

Numeric Computation Software

- *Allows sparse-matrix approach to problem solving*
 - *Allows visual and audio analysis*
- Matlab version 4.0 expands the

software's analysis and presentation capabilities. Flexible File I/O allows you to import and export large data sets. To improve the software's ability to solve problems using these large data sets, the tool offers sparse-matrix algorithms that define computation time as a function of the nonzero elements in the matrix. The software solves problems written in the company's programming language, allowing you to bypass traditional program/compile/debug cycles. Debugging features that bypass the traditional include breakpoint control, context changing during debugging, and single stepping. Application toolboxes provide special functions for DSP, filter, and control-system design and analysis, among others. You can output audio data or create color 3-D surfaces, mesh plots, contour plots, scatterplots, and a host of other graphical representations. The software will be available in early 1992, and it runs under X Windows. \$2995.

The Mathworks Inc., Cochituate Pl, 24 Prime Park Way, Natick, MA 01760. Phone (508) 653-1415. FAX (508) 653-2997. TWX 910-240-5521.

Circle No. 373

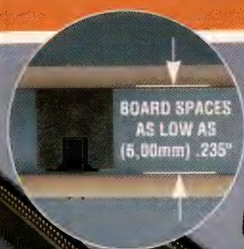
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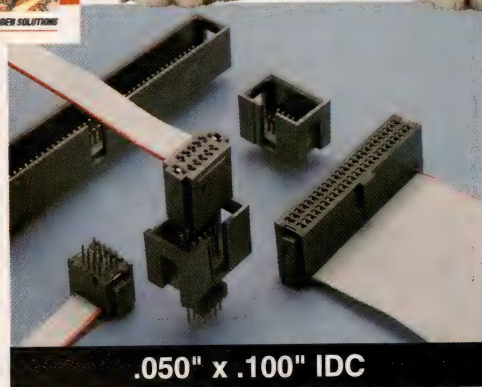


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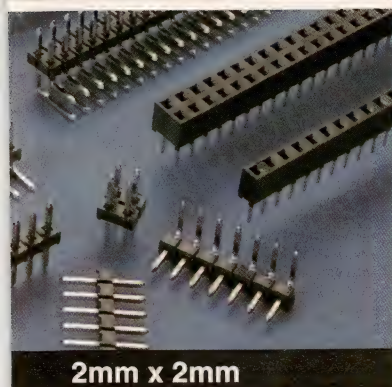
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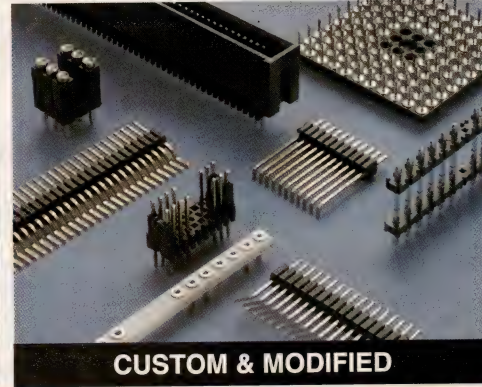
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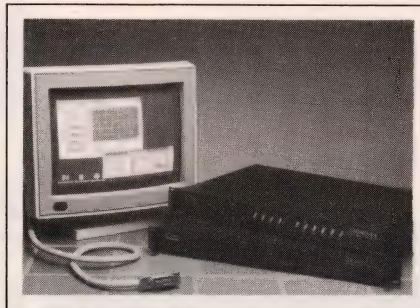
CIRCLE NO. 97

EDN February 17, 1992 • 195

EDN-NEW PRODUCTS

CAE & Software Development Tools

Design validation software. DDA software evaluates each net and interconnection on a pc board using circuit-board and line characteristics, power-supply attributes, line/trace length, and IC-manufacturer-supplied operating specifications. The software performs 66 tests on each net to achieve 98% fault isolation. Purchased licenses, \$6995; leased licenses, \$2400. **Digital Design Analysis**, 150 El Camino Real, Suite 200, Tustin, CA 92680. Phone (714) 573-8730. FAX (714) 573-8736. **Circle No. 374**



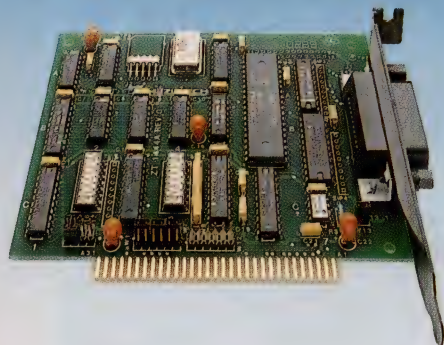
Windows Driver for IEEE-488. Driver488/Win facilitates integration of IEEE-488 instrument control into Windows applications. The driver allows multiple tasks to simultaneously access the same interface board and conforms to Windows' event-handling system. The software includes an application that aids in creating and testing driver command lines. \$195. **IOtech Inc.**, 25971 Cannon Rd, Cleveland, OH 44146. Phone (216) 439-4091. FAX (216) 439-4093. **Circle No. 375**

Router between VMS and MS-DOS. The Reliable Transaction Router for MS-DOS software allows you to integrate DOS-based PCs into multivendor networks where at least some of the machines run VMS. The router permits information sharing and protects against system faults and site failures. The software also supports MS-Windows and both DECnet and TCP/IP (Transfer Control Protocol/Internet Protocol). Licenses, \$275/CPU. **Digital Equipment Corp.**, 200 Forest St, Marlborough, MA 01752. Phone (508) 467-5111. **Circle No. 376**

DSP source-code generator. The Codegen generator provides both a macroprocessor and a template. The macroprocessor reads files you create using the template and interprets the embedded macros. After converting it

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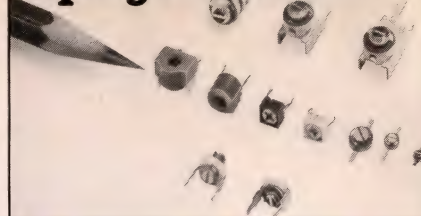
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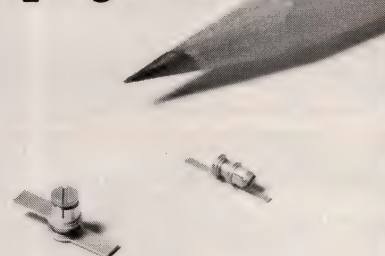
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Timer	8-bit timer: 2ch Basic interval timer/Watchdog timer: 1ch			
Serial interface	1 channel (usable as a port pin)			
Stack	5 levels			
Power-on reset	Provided			
System clock	RC oscillation	Ceramic oscillation	RC oscillation	Ceramic oscillation
Instruction execution time	8μs (2 MHz)	2μs (8 MHz)	8μs (2 MHz)	2μs (8 MHz)
Standby function	STOP/HALT			
Power supply	2.7 to 5.5V (5V ±10% when A/D in use)			
Package	28-pin plastic shrink DIP/28-pin plastic SOP			
One-time PROM	μPD17P136A	μPD17P137A	μPD17P136A	μPD17P137A

SIMPLEHOST: Trademark of NEC Corporation. MS-WINDOWS: Trademark of Microsoft, Inc.

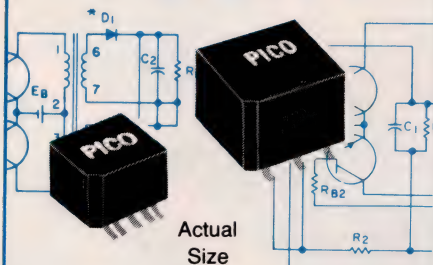
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to the format and sequence the host processor requires, the software writes the result to a file for assembly or compilation. The MS-DOS-based software doesn't contain assemblers or compilers. \$89.95. **Dynacomp Inc.**, 178 Phillips Rd, Webster, NY 14580. Phone (716) 671-6160. **Circle No. 377**

IC design tools. Owing to a recent agreement, Integrated Silicon Systems' layout editor, verification software, and mask-pattern-generation software will be included in the Dazix tool suite. LTL-100 layout editor, from \$23,900; verification software, including design- and electrical-rules checkers, layout/schematic compare, and layout-parameter extraction, approximately \$90,000; PG-100 pattern generator, from \$12,900. **Dazix**, 1 Madison Industrial Park, Huntsville, AL 35894. Phone (205) 730-2000. FAX (205) 730-8344. **Circle No. 378**

Security software. Menuworks Total Security software provides data encryption; passwords; directory, file, command, and function-key locking; and boot protection. It also scans file changes caused by viruses. A utility searches your hard disk for more than 2500 programs and categorizes the programs to build useful system menus for MS-DOS-based computers. \$149.95. **PC Dynamics Inc.**, 31332 Via Colinas #102, Westlake Village, CA 91362. Phone (800) 888-1741; (818) 889-1741. FAX (818) 889-1014. **Circle No. 379**

Scan-test tester software. The version 1.5 upgrade to the GR228X tester has a Scan Pathfinder Boundary-Scan Toolkit option. This option can test IEEE-1149.1 test-access port, the boundary-scan path, and connections between boundary-scan devices. In addition, the software aids in identifying and diagnosing the faults between boundary scan and nonboundary scan parts. The upgrade also includes a hardware fault-insertion capability. Scan Pathfinder, from \$35,000. **GenRad Inc.**, 300 Baker Ave, Concord, MA 01742. Phone (508) 369-4400, ext 2101. **Circle No. 380**

Data-acquisition software. The Macintosh System 7-version of Labview 2.2 is a high-performance version of the data-acquisition software. It generates in-line floating-point instruction that utilizes Mac Quadra on-chip floating-

EDN REPRINTS

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This original, 186-page collection by Jim Williams offers a wealth of analog design information. It includes practical and efficient ways to use op amps, comparators, data converters, and other analog ICs.

A Designer's Guide to Linear Circuits

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Jim Williams' analog design articles - from 1983 to 1986 - in Volume II. Volume II covers more complex circuits and systems in 66 pages.

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This 48-page, four-color reprint follows the progress of EDN editor Steve Leibson as he designs a 2M-byte memory board using surface-mount technology. He includes typical problems you might encounter and objectively reports about both good and bad design decisions made along the way.

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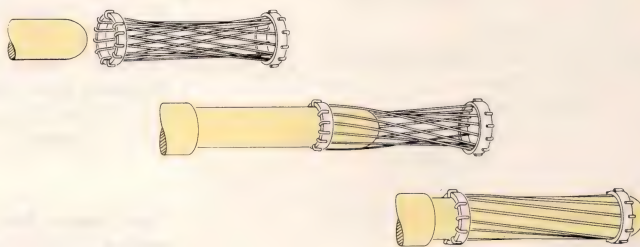
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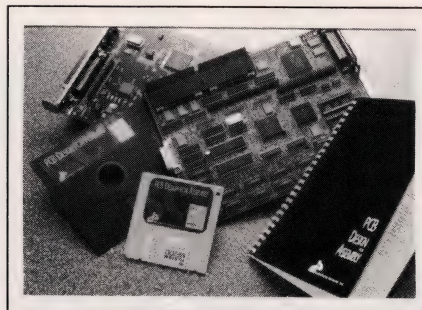
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200 • EDN February 17, 1992

EDN-NEW PRODUCTS

CAE & Software Development Tools

point processing. The tools acquire data from IEEE-488, VXI, or RS-232C instruments or from the vendor's own plug-in data-acquisition boards. \$245 to \$4995. **National Instruments Corp.**, 6504 Bridge Point Pkwy, Austin, TX 78730. Phone in US and Canada, (800) 433-3488; (512) 794-0100. **Circle No. 381**



PC-board design-for-assembly software. Using parts-based analysis, PCB Design for Assembly analyzes the cost of component assembly and provides indices that reflect the difficulty of board manufacture. The indices in the DOS-based tool weigh the analysis of such criteria as component placement, density, height, autoinsertion, quality, labor, and cost. \$9500. **Boothroyd Dewhurst Inc.**, 138 Main St, Wakefield, RI 02879. Phone (401) 783-5840, FAX (401) 783-6872. **Circle No. 382**

Texas Instruments Inc., Information Technology Group, Box 869305, MS 8404, Plano, TX 75086. Phone (800) 336-5236, ext 1400. **Circle No. 383**

Reliability-rating program. The Enhanced Component Stress Analysis Program analyzes electrical, electronic, and electromechanical equipment in accordance with USAF, Naval Air Systems Command, NASA, and Department of Defense requirements. The stress-analysis tool is an enhancement to the vendor's Reliability Prediction Program. The option generates seven reports. Option, \$1000. **Powertronic Systems Inc.**, Box 29109, New Orleans, LA 70189. Phone (504) 254-0383, FAX (504) 254-0393. **Circle No. 384**

Test tools for software development. Software Testworks uses an OSF/Motif user interface and runs on X Window System workstations. The software consists of two tool suites: STW/COV is a test-coverage analysis suite, and STW/REG automates software testing. A minimum configuration allows three users. \$18,300. **Software**

Research Inc., 625 Third St, San Francisco, CA 94107. Phone (415) 957-1441. FAX (415) 957-0730. **Circle No. 385**

Raster-image software. Jetview Plus and Jetview Professional allow you to retrieve, view, and print raster images. Both packages sense a raster file's format before loading the file. Once loaded, you can measure lines and angles or print to output devices that have appropriate drivers. Jetview Professional includes adds such file-manipulation features as deskewing, rotating, cropping, or file conversion. From \$595. **Houston Instrument**, 8500 Cameron Rd, Austin, TX 78753. Phone (512) 835-0900. **Circle No. 386**

Localtalk network debugger. Localpeek works like a telephone tap on a Macintosh network to create and analyze network statistics. The software keeps such statistics as network utilization, and evaluates error packets such as cyclic redundancy check/checksum, overruns, underruns, and transmit errors. Decoders within the software allow you to look inside error packets and discern the source of the errors. \$495. **The AG Group Inc.**, 2540 Camino Diablo, Suite 202, Walnut Creek, CA 94596. Phone (510) 937-7900. FAX (510) 937-2479. **Circle No. 387**

Network backup software. Arcserve 4.0 backup and restore package for Novell networks achieves backup speeds of more than 20 Mbytes/minute. Features include automated tape rotation for removing files that you don't use for a specified period of time, and a disaster recovery feature that rebuilds all or part of a network by reading a stored database from the backup tape. DOS-based software, from \$295 for five users. **Cheyenne Software Inc.**, 55 Bryant Ave, Roslyn, NY 11576. Phone (516) 484-5110. **Circle No. 388**

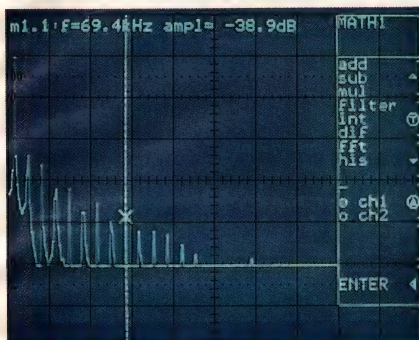
Fortran compiler for System 7. Fortran version 3.0 makes use of the Macintosh System 7 features such as AppleEvents, Publish and Subscribe, aliases, and virtual memory. In addition to optimized code for 68000-based microprocessors and Cray pointers, the software adds such debugging features as heap validity checking, useful error dialogues, and execution window tracing. From \$495. **Language Systems Corp.**, 441 Carlisle Dr, Herndon, VA 22070. Phone (703) 478-0181. **Circle No. 389**

Text continued on pg 204

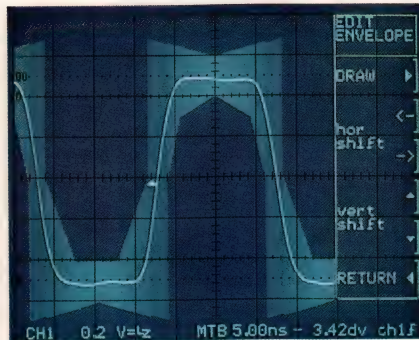
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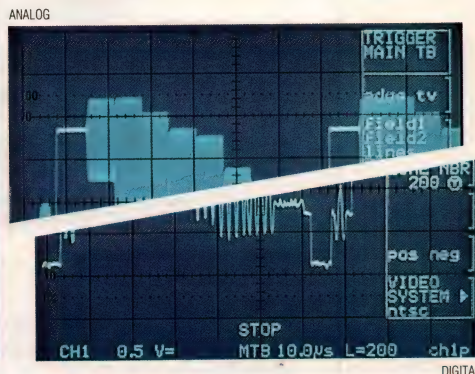
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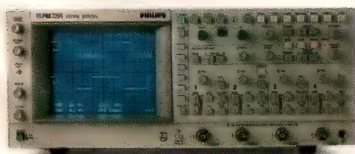
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CIRCLE NO. 107

Ethernet analyzer. Netminder Ethernet is a network analyzer that runs on Macintosh computers; it debugs, troubleshoots, and monitors Ethernet networks. The analyzer provides features such as packet filtering, postfiltering, triggering, and traffic-level alarms. Among the Ethernet protocols the software can decode are Appletalk, TCP/IP (Transfer Control Protocol/Internet Protocol), DECnet, Netware, Bridge/3Com, and Banyan Vines. \$595. **Neon Software Inc.**, 1009 Oak Hill Rd, Suite 203, Lafayette, CA 94549. Phone (510) 283-9771. FAX (510) 283-6507.

Circle No. 390

Network printer software. The Newsprint 2.0 upgrade allows you to print files from networks containing heterogeneous computers and workstations. As long as the network contains a SPARC workstation, the software uses this CPU to handle page imaging of Postscript and non-Postscript language files. \$695. **Sunpics**, 2550 Garcia Ave, Mountain View, CA 94043. Phone (415) 960-1300. FAX (415) 969-9131.

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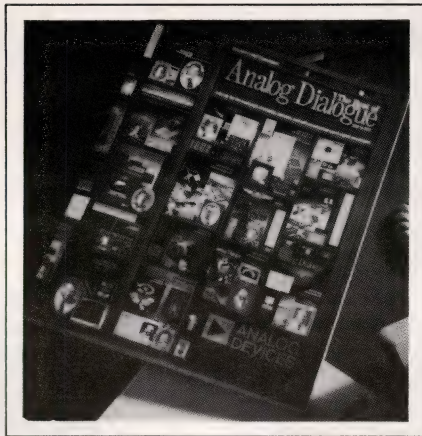
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CIRCLE NO. 109

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Abstracting analog information.

This 224-pg collection, *The Best of Analog Dialogue*, consists of application articles, tutorials, and problem-solving products judged by readers as the most helpful and useful. The collection, which covers 25 years, is arranged in chronological order and has an index. **Analog Devices, Literature Center**, 70 Shawmut Rd, Canton, MA 02021. FAX (617) 821-4273. **Circle No. 351**

HDL Reference Manual. The Language Reference Manual, Release 1.0 describes the vendor's hardware description language (HDL). The 300-pg publication explains how you can create HDL-based tools and descriptions. \$50. **Open Verilog International**, 1016 E El Camino Real, Suite 408, Sunnyvale, CA 94087. Phone (408) 987-5417.

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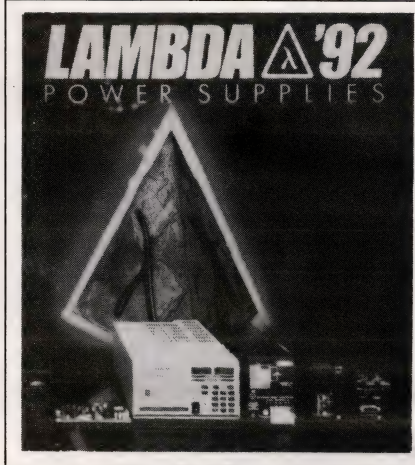


Instrument Handbook. *The Monitor & Control Handbook* presents data sheets, illustrations, specifications, and applications for a line of LED and LCD digital panel meters, printers, process monitors, and calibrators. Also included is a summary guide for data-acquisition

boards, dc/dc power converters, and other data-conversion products. The 210-pg publication highlights a series of hybrid digital voltmeters in a choice of 30 colors, including red, green, yellow, amber, orange, and blue. **Datel Inc**, 11 Cabot Blvd, Mansfield, MA 02048. Phone (508) 339-3000. FAX (508) 339-6356. **Circle No. 352**

Digital-signal-processing databook.

This databook describes DSP products for commercial and military applications and includes application notes. It also summarizes 1- and 2-D filters, multipliers, signal synthesizers, and special-function devices. **Harris Semiconductor**, Box 883, Melbourne, FL 32901. Phone (800) 442-7747, ext 1047; (407) 724-3704. **Circle No. 353**



Switching and linear supplies. The 1992 catalog of power supplies provides specifications, mechanical drawings, and prices for more than 1300 standard power supplies, power systems, and accessories. In addition to the large selection of standard-switching and linear supplies, the 208-pg publication introduces eight product series. **Lambda Electronics Inc**, 515 Broad Hollow Rd, Melville, NY 11747. Phone (516) 694-4200. **Circle No. 354**

Catalog of software and hardware.

A 544-pg, 4-color catalog covers the vendor's line of software and hardware products for developing instrumentation systems. The catalog is color-coded by section—Application Software, GPIB, Data Acquisition, VXI/MXI, and Training. Tutorials provide applications illustrated with diagrams that the reader can use as templates to create similar systems for instrument control, data acquisition and analysis,

test and measurement, and other applications. **National Instruments**, 6504 Bridge Point Pkwy, Austin, TX 78730. Phone in USA and Canada, (800) 433-3488; (512) 794-0100. **Circle No. 355**



Catalog of small-sized pc boards.

The 88-pg *Micro PC Catalog* discusses a line of small pc boards and accessories that operate over an extended temperature range. The book provides technical information and pricing for control and expansion boards, cables, displays, keypads, terminal boards, and other items for configuring a system. **Octagon Systems Corp**, 6510 W 91 Ave, Westminster, CO 80030. Phone (303) 430-1500. FAX (303) 426-8123. **Circle No. 356**

Trimmer capacitor catalog.

This 26-pg catalog describes RF and microwave trimmer capacitors and tuning devices. The capacitor-selection guide provides profiles that show the size of units. The catalog concludes with prototyping kits that let you identify and evaluate products discussed in the



publication. **Johanson Manufacturing Corp**, Rockaway Valley Rd, Boonton, NJ 07005. Phone (201) 334-2676. TWX 710-987-8367. **Circle No. 357**

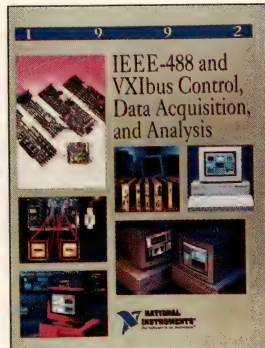
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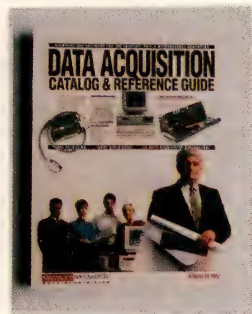
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Circle # 205

1992 DATA ACQUISITION CATALOG

From Keithley MetraByte-New Free 288 page full-color Data Acquisition Catalog and Reference Guide. It introduces many new products and provides facts on all their plug-in boards, Data Acquisition and Analysis Software, IEEE-488.2 interfaces, Precision Data Acquisition Systems, and PC Instrumentation for use with IBM PC/XT/AT, PS/2 and Micro Channel computers. Includes helpful selection charts and application notes.



Circle # 206

Keithley MetraByte

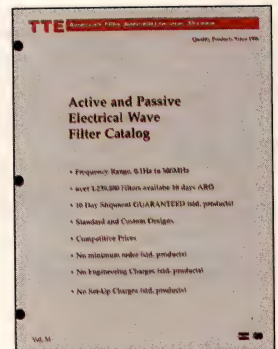
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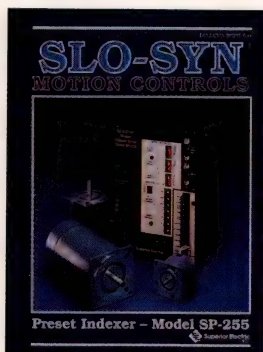
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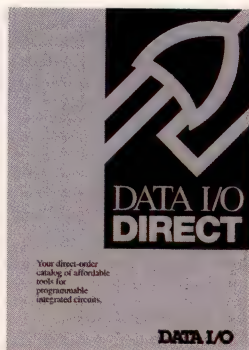
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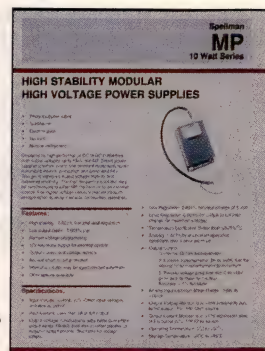
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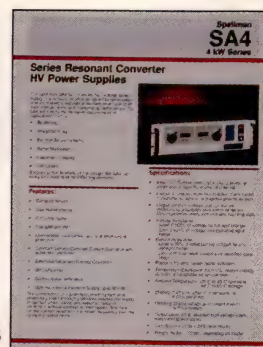
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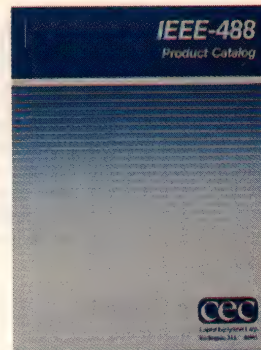
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This catalog introduces CEC's newest and fastest IEEE-488 hardware and software. Support for Visual BASIC, Turbo Pascal for Windows, a Windows DLL, Turbo C++, BASIC 7, and Quick Pascal are shown. A code generator and instrument libraries for QuickBASIC, Turbo Pascal, Microsoft C and FORTRAN are described along with the latest IEEE-488.2 software.

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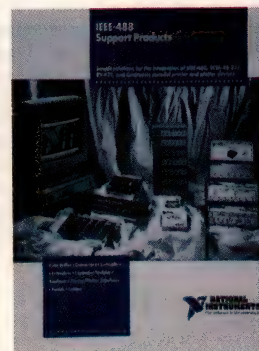
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IEEE-488 SUPPORT PRODUCTS

This brochure describes the complete line of National Instruments IEEE-488 support products including, converters, controllers, bus extenders and expander/isolator, data buffer, and switch box. These products provide simple solutions for the integration of IEEE-488, SCSI, RS-232, RS-422, and Centronics parallel devices. Also described is an IEEE-488 bus analyzer/monitor for diagnosing GPIB problems quickly

National Instruments

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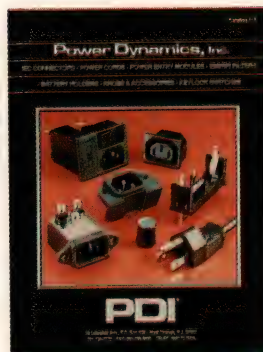
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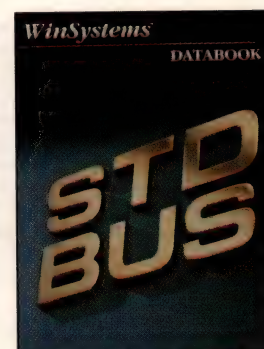
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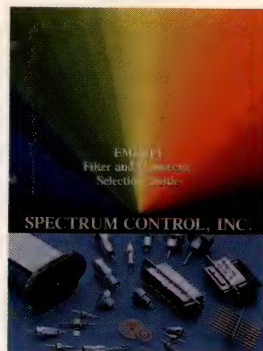
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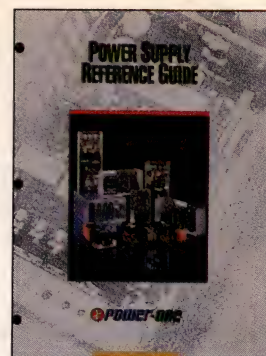
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RAYOVAC LITHIUM BATTERY GUIDE

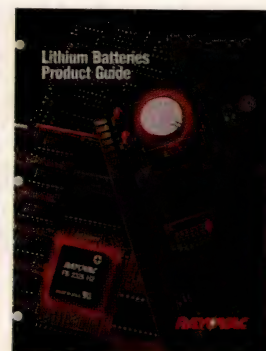
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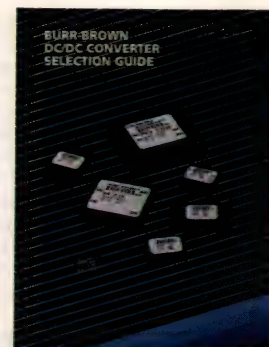
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This selection guide provides an overview of over 500 DC/DC Converters offered by Burr-Brown Power Convertibles. It illustrates innovation in power density, small size packaging and surface mount manufacturing. Products are available in miniature SIP and DIP packages as well as other industry standard pin outs. With output power ranging from .450 watts to 25 Watts they come in regulated and unregulated units. Input voltages vary from 5, 9, 12, 15, 24, 18, 48 and output configurations are in single and dual voltages at 5, 9, 12, 15.



Circle # 233



POWER SUPPLIES

SCR-REGULATED DC POWER SUPPLIES



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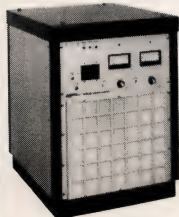
- 4 power levels 600 W - 1,000 W - 1,800 W - 2,800 W
- DC outputs variable over full range of 0 to 7.5 V DC through 0 to 2,500 V DC
- Regulated and metered (V and A)

- CV/CC with automatic crossover
- Fully programmable and remote sense
- Complies with VDE 875-N and VDE 871-A
- 5-year warranty



THREE PHASE TCR

- 3 power ranges 2,500 W - 5,000 W - 10,000 W
- DC outputs variable over range from 0 to 6 V DC through 0 to 600 V DC
- Regulated and metered (V and A)
- CV/CC with automatic crossover
- Complies with VDE 875-N and VDE 871-A
- 5-year warranty

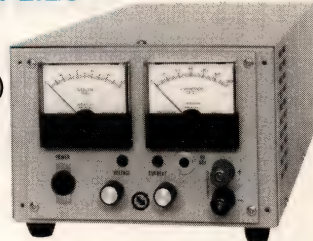


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HCR 250 W DC POWER SUPPLIES

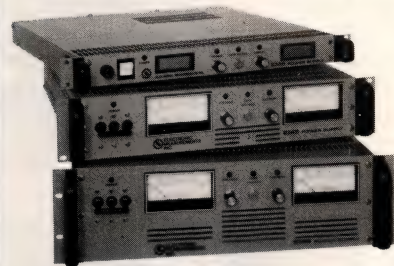
- 9 models 0 to 7.5 V DC through 0 to 300 V DC
- Regulated and metered (V and A)
- CV/CC with automatic crossover
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- 1/2 rack packing
- 5-year warranty
- Output power via rear mounted terminal boards or front panel binding posts



ATR LINEAR DC POWER SUPPLIES

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- Regulated and metered (V and A)

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CIRCLE NO. 52

EDN February 17, 1992 • 211



Training with technology

Sports science and high-tech training equipment have helped our Olympic athletes, but a shortage of funds hinders the program.

JAY FRASER, Associate Editor



Before a rifle or pistol shooter at the US Olympic Training Center pulls the trigger, the coach knows where the bullet will hit the target. Engineers from the Sports Science Division and outside companies have developed a solid-state-laser aiming device that weighs less than two ounces. It's mounted on the gun and directs an infrared beam at the target. A video camera picks up the beam and displays it on a monitor. The coach can determine where the shooter is aiming before the shot is fired.



During bad weather US Olympic rowers train indoors with computerized ergometers. These machines simulate the resistance of water to an oar. They record not only force and stroke rate, but also speed, time, distance, and caloric energy consump-





Sports scientists measure a runner's oxygen consumption, heart rate, and other physiological indicators.

tion. The ergometers can be connected to a monitor that generates a display of boats racing each other. Some colleges use these devices to stage competitions with other schools in the off-season.



One of the unique facilities at the training center in Colorado Springs, CO, is the swimming flume. It's the aquatic equivalent of a wind tunnel. Pumps circulate water through the flume, so someone swimming in it remains in place. The speed and temperature of the water can be controlled, and a window on one

boxer's uppercut. The difference between winning and losing in the Olympic Games is sometimes only a fraction of an inch or a fraction of a second. It's crucial for today's athletes to find some way to gain an edge over their competitors. Sports science and high technology can often provide that edge.

America was slow to understand the importance of technology to training, but after the 1976 Olympic Games Congress finally realized that the US team needed help. That summer, the Soviet Union finished first overall with 125 medals. America came in second with 94. And tiny East Germany, with a population

(USOC) solely responsible for the administration, development, and selection of teams for the Pan-American and Olympic Games. It also funded a variety of research grants and established training centers at Lake Placid, NY, and Colorado Springs.

At the Lake Placid center, athletes train for winter sports in addition to boxing, rowing, canoeing, and kayaking. The much larger center at Colorado Springs deals with all other Olympic sports. Its 33-acre campus encompasses dormitories for 600 athletes and coaches, five gymnasiums, a weight room, an outdoor track, a shooting complex, and the water flume. The center also operates a nearby velodrome and roller-skating racing track.

In order for American athletes to receive technological support and services equivalent to those that Eastern Bloc athletes enjoy, a Sports Science Division was established at the Colorado Springs center. It comprises five departments: psychology, physiology, biomechanics, computer science, and engineering and technology. The main purpose of the division is to analyze and evaluate athletes' performances to help them maximize their efforts.

The engineers and scientists in the Sports Science Division use high-speed video cameras, laser timing systems, and various sensing devices such as ergometers in their work. One of their on-going projects is refining the data-acquisition system they use to monitor an athlete's aerobic capacity, muscle strength, lung function, and heart rate. From time to time the staff hauls its equipment to Lake Placid to test the athletes there. In 1990 they provided 8640 evaluations for US athletes.

The director of the Engineering and Technology Department is Andrew Zolnay. He studied medicine before he earned his PhD in nuclear engineering from Ohio State Uni-



Physiologists monitor a runner's breathing to determine how efficiently he uses oxygen during exercise.

side allows the swimmer to be observed and videotaped. It's the only such flume in the US.



The engineers and scientists who work with the US Olympic Team are using sophisticated technical equipment to measure and analyze everything from the angle of a sprinter's feet to the force of a

of only 17 million, almost edged out the US by winning 90.

The success of the Eastern Bloc countries was largely credited to their extensive sports-science programs, which they had begun in the 1950s. Convinced at last of the need for a similar program for US athletes, Congress passed the Amateur Sports Act in 1978.

This legislation was far reaching. It made the US Olympic Committee



versity (Columbus, OH). Then he worked at Lawrence Livermore National Laboratory (Livermore, CA) where he designed instrumentation to detect and measure radiation. In his spare time he tinkered with the prototype of a data-acquisition system he had devised for use with athletes.

Zolnay had long been involved in rowing, so his system was specifically designed for that sport, although it could be adapted for others. The basis of the system he envisioned was a series of sensors attached to the athlete and the boat. The sensors would take data every sixtieth of a second and transmit it to a video camera. The data would be encrypted on the video tape to make a correlated record of the image of the athlete with the measurements of his or her performance.

Zolnay organized a team of volunteers at Lawrence Livermore to help him develop his prototype. "I had a reputation for being able to convert more scientists to peaceful purposes than all the demonstrators combined," he says with a smile. He also contacted the USOC and offered the system to them. He received some encouragement, but not much.

Then the head of the Sports Science Division and a colleague took a trip to East Germany to study their athletic programs. When they asked the rowing coach how he trained his teams, he described using a data-acquisition system very similar to Zolnay's. After the two American officials returned to Colorado Springs, they quickly offered Zolnay the directorship of the Engineering and Technology Department. He accepted.

Zolnay feels strongly that the primary purpose of his department isn't to design pieces of hardware. "Engineering's function here is not to build gizmos and widgets for other people," he says, "but to be involved in the actual analysis of

sport from the viewpoint of rigorous engineering discipline. That way you get answers to some of the puzzling problems that occur in sport, rather than thinking that the only thing that wins medals is team spirit or some other nebulous concept."

Soon after he arrived at the Colorado Springs center, Zolnay had a chance to apply some engineering thinking and optimization theory to a training situation. "I went down to weightlifting, and a biomechanist was taking 3-D video photographs of the athletes as they lifted and was digitizing the trajectory of the bar. The staff then compared the trajectories to those of medal-winning weightlifters and tried to duplicate them. I told him that even if you duplicate the trajectories of successful weightlifters perfectly, at best you're only going to be as good as the person you're duplicating. And the idea in the Olympics is not to be "as good as" but to be better.

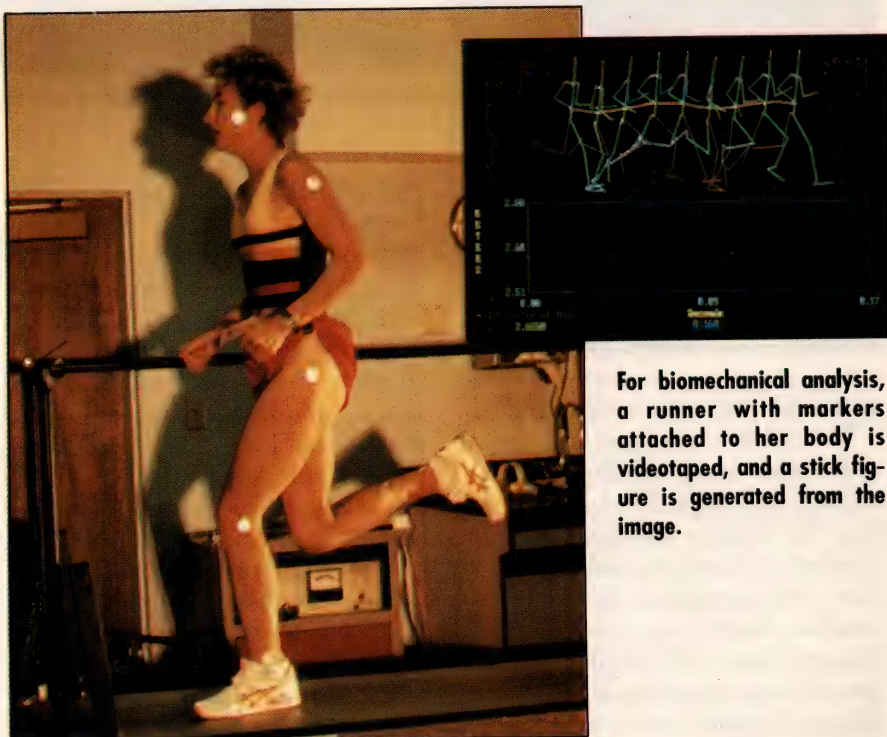
"You have to calculate the optimum trajectory for each athlete,"

Zolnay explains. "You have to take into account the body dimensions, muscle strengths, linkages, and bone dimensions and sizes of each individual. Then you can say that for this particular athlete, this is the optimum."

Intermingling disciplines

The functions of the departments within the Sports Science Division often overlap and intermingle. Tanya Wheeler, head of the Computer Science Department, says, "We're very much integrated. My department works closely with the others. We find out what they need, and we try to design software that lets the engineers optimize their use of the equipment." Wheeler's background reflects the integration of the disciplines. She holds degrees in both sports science and computer science from the University of Western Ontario.

Because its needs are so specialized, the Computer Science Department can't buy much software off the shelf. Wheeler and her staff have written almost all the pro-



For biomechanical analysis, a runner with markers attached to her body is videotaped, and a stick figure is generated from the image.



grams the Sports Science Division uses. They even work closely with the psychologists. "We've written some applications for statistical analysis to help the psychologists," says Wheeler. "They maintain a very personal one-on-one level of consultation with the athletes, but we provide an avenue for them to get some of the basic information they need."

When an athlete arrives at the Colorado Springs training center, the first step in the testing and

athlete's performance is to create computerized representations of the athlete's movements.

To analyze a runner's style, markers are placed on his head, shoulder, hip, knees, and feet. As he runs on a treadmill, he is videotaped with a high-speed camera. The image is digitized and a computer program connects the dots corresponding to the markers to generate a stick figure for display. The figure can be run in slow motion or stopped for closer examination.

plete, a sports scientist will sit down with the athlete and coach and suggest how they could improve their training program. Then they return home. Few athletes stay at the Colorado Springs center for an extended length of time.

Both Zolnay and Wheeler are reluctant to claim credit for any athlete's success because so many factors besides input from the Sports Science Division are involved. But some athletes have shown dramatic improvement after visiting the Colorado Springs center.

"There are some specific instances of athletes who have come through here and improved by leaps and bounds," says Wheeler. "We hope we can say we were a small part of that improvement. For example, with some of the figure-skating athletes we've been able to determine that they have so much angular acceleration going into a jump that they should be able to rotate four or five times before they land. When we tell them that they might say, okay, maybe I'll try it. Then they try it and do it. We were able to provide a little bit of information that helped them, but it's their success. They're the ones who worked for it."

The annual budget for the Sports Science Division is less than \$2 million. Although Congress established the USOC, it doesn't fund it. No tax money goes to support the US Olympic team.

The USOC raises some funds by licensing the Olympic symbols to companies for use on their products. The companies pay royalties to the USOC on sales. The USOC also has 40 corporate sponsors, firms that make donations of either cash or equipment. (The amount of the donation necessary to qualify as a corporate sponsor is confidential.) Otherwise, America's Olympic effort depends on donations from individuals.

"[The Sports Science Division] is



A sprinter gets set to run through a series of electronic timing lights, which measure his rate of acceleration.

evaluation process is usually a lengthy interview with someone on the Sports Science staff. "I listen carefully to all aspects of their performance as they see it," says Zolnay. "An athlete's sense of what's going on is more sensitive than anything I can ever build."

The athlete may get a physical and dental exam, advice about nutrition, and psychological counseling. The athlete also goes through a series of laboratory and field exercise tests to measure his or her respiration, heart rate, power, and efficiency. One of the methods the engineers and scientists of the Sports Science Division use to evaluate an

The stick figure may reveal aspects of an athlete's movements that aren't readily apparent. Correcting flaws will improve performance and reduce the risk of injuries. For example, Mark Fenton, an Olympic race walker, was videotaped, and his computer image showed that his stride was too long. By shortening it slightly to keep his feet closer to his center of gravity, he improved his time in the 20-km race by approximately 5%.

After the tests are finished, people from departments other than engineering and technology might be called in to help evaluate the results. When the evaluation is com-

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pitifully underfunded," says Zolnay. "I have less staff and resources here than I had with the volunteers back at Lawrence Livermore. This is ludicrous." Right now the entire engineering and technology department consists of him, a senior design engineer, and "two thirds of a research assistant."

Asked what the USOC would need to bring the American effort in sports science up to that of other countries, Zolnay quickly replies, "Fifty million dollars to build a 5-story sports science building, an entire floor for each discipline of the division, along with the instrumentation required to do a first-class analysis, and the appropriate staff."

Today a total of 28 people work full time for the Sports Science Division. By contrast, the Soviet Olympic team is supported by a staff of more than 1800. Before Ger-

many's reunification, the East German team had more than 500 people working with it.

The USOC's budget constraints are almost certain to create problems in the future. Because the Sports Science staff is so small, it only has the time and resources to work with America's elite athletes. The younger, developing athletes may not get the level of training they'll need to compete successfully someday against world-class athletes from other countries.

Underlying the immediate problems of lack of funding and personnel is the deeper problem of lack of national commitment. "It's just an excuse when people from the US say other countries do much better because they pay their athletes," says Zolnay. "We have the resources here, but they're squandered. Things like facilities and

training, diet and nutrition, technical support, and respect for sport all have to come together. We just don't have the discipline to use what we have. It's sad."

(Since this article was written, Andrew Zolnay has left his position with the USOC by mutual consent.)

EDN

Jay Fraser, Associate Editor, can be reached at (617) 558-4561, FAX (617) 558-4471.



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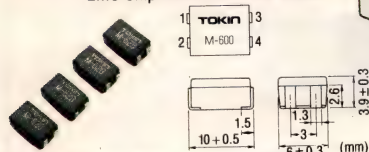
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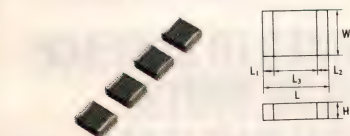
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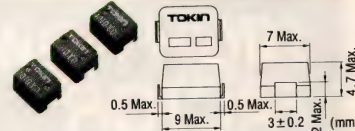
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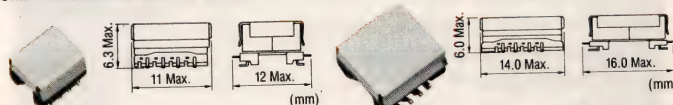


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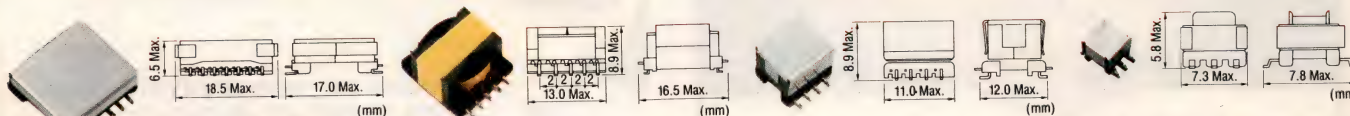
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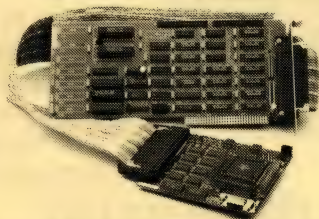
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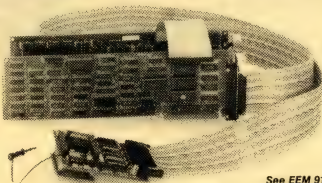
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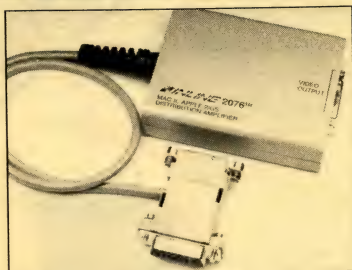


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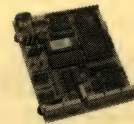
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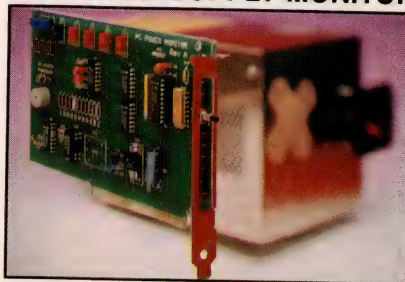


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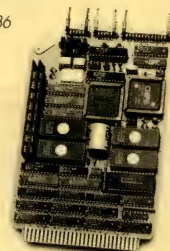
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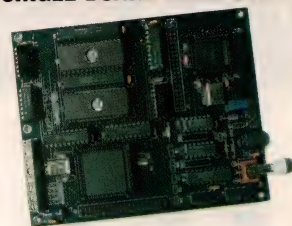
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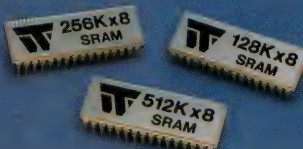
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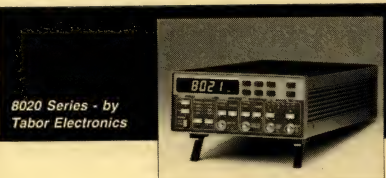
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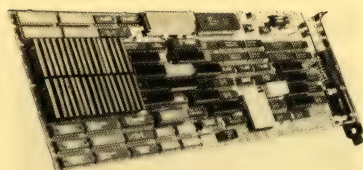
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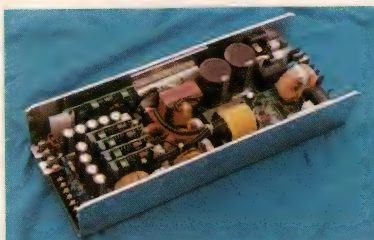
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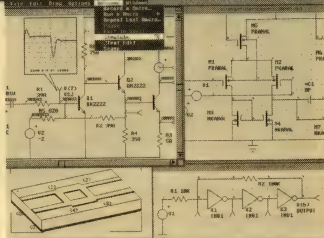
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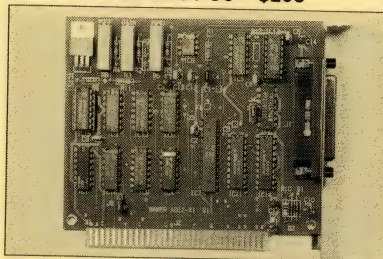
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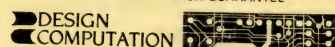
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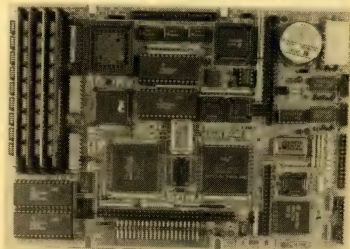


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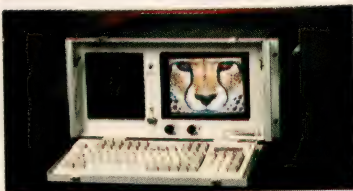
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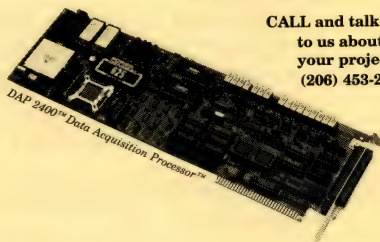
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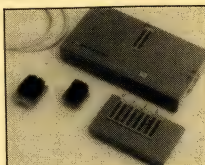
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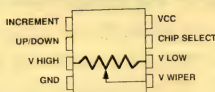


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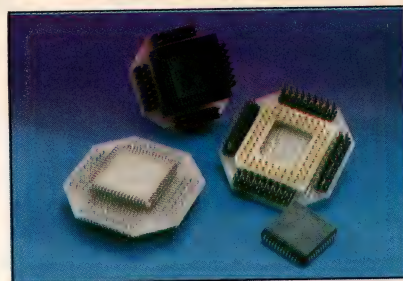
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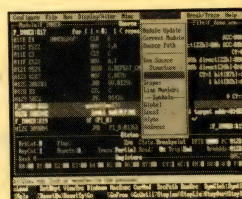
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Magazine Edition	Mar. 16	Feb. 20	COMPUTER & PERIPHERAL SPECIAL ISSUE • Multimedia • Components • Memory Technology • Computer Peripherals • International Technology Update—Japan
News Edition	Mar. 19	Mar. 5	DSP Software • Communications • Regional Profile: New York, New Jersey, Pennsylvania
Magazine Edition	Mar. 30	Mar. 5	Microprocessors • Analog Circuits • CAE • Test & Measurement
SOFTWARE ISSUE	Mar. 30	Mar. 5	SOFTWARE ENGINEERING SPECIAL ISSUE • (To be polybagged with the March 30th Magazine Edition issue)
News Edition	Apr. 2	Mar. 19	ICs & Semiconductors • Multimedia Software/Development Tools • Engineering Management Special Series
Magazine Edition	Apr. 9	Mar. 19	CAE • EDN Hands-on Special Project—Part I: Field-programmable Gate Arrays • Software • Memory Technology
Magazine Edition	Apr. 23	Apr. 2	Portable Computer Design • EDN Hands-on Special Project—Part II: Field-programmable Gate Arrays • Electromechanical Devices • Computer Peripherals
News Edition	Apr. 30	Apr. 16	ASICs SPECIAL ISSUE • FPGAs and EPLDs • CICC Hot Products • ASICs • Regional Profile: Northern California
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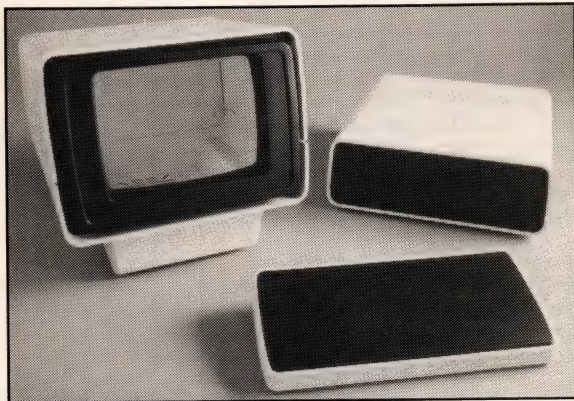
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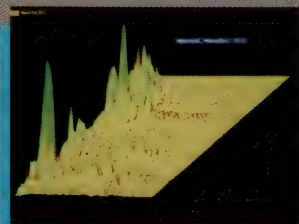
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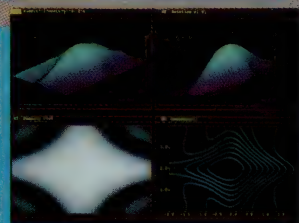
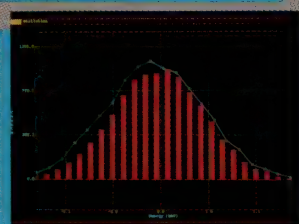


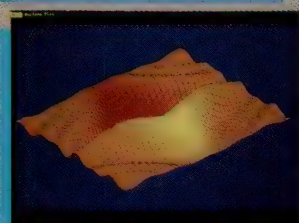
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ASIC—application-specific integrated circuit
ATE—automatic test equipment
ATPG—automatic test-pattern generator
BILBO—built-in logic-block observer
BIST—built-in self test
CAE—computer-aided engineering
CD—compact disc
CMOS—complementary metal-oxide semiconductor
CMRR—common-mode rejection ratio
DAC—digital-to-analog converter
DFT—design for test
DMM—digital multimeter
DUT—device under test
ECL—emitter-coupled logic
EC—European Community (Belgium, Denmark, France, Germany, Greece, Ireland, Italy, Luxembourg, The Netherlands, Portugal, Spain, and the UK)
EDIF—Electronic Design Interchange Format
EFTA—European Free Trade Association (Austria, Finland, Iceland, Norway, Sweden, and Switzerland)
FFT—fast Fourier transform
FPGA—field-programmable gate array
HDL—hardware description language
JFET—junction field-effect transistor
JTAG—Joint Test Action Group
NRE—nonrecurring engineering
PECL—positive emitter-coupled logic; referenced to 5V
PLA—programmable logic array
PLD—programmable logic device
PLL—phase-locked loop
rms—root-mean-square
SMT—surface-mount technology
SMU—source-measure unit; four instruments in one: a voltage source, a voltmeter, a current source, and a current meter
THD—total harmonic distortion
TPG—test-pattern generator
TTL—transistor-transistor logic
VCO—voltage-controlled oscillator
VHDL—VHSIC Hardware Description Language
VHSIC—very-high-speed integrated circuit

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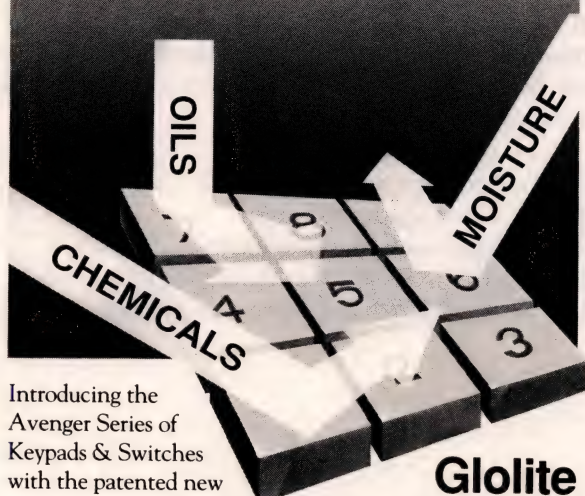
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CIRCLE NO. 126

Book and software unravel the intricacies of the chaos theory

In James Gleick's book *Chaos: Making a New Science*, he tells a story about quantum physicist Werner Heisenberg. On his death bed, Heisenberg declared that he would have two questions for God: Why relativity and why turbulence. He said, "I really think He may have an answer to the first question."

Chaos theory may not answer the second question, but it does offer a way to model the behavior of nonlinear systems, in which quantities vary over time or change from place to place in a manner that is not strictly proportional. The equations for such systems generally cannot be solved or added together. These equations model the real world—instead of idealizing it—by including nasty nonlinear variables such as friction.

In such seemingly random systems as the weather, the swinging of a pendulum, the fluctuations in wildlife populations, and even the bobbing of stock prices and the dripping of a faucet, researchers have discovered patterns. Universal laws appear to be buried in what scientists once viewed as turbulence and disorder—an impenetrable quality of the real world.

Science writer Gleick worked with Autodesk to create *James Gleick's Chaos: The Software*, a series of six interactive programs that bring to life the relationships he described in his best-selling book.

Computers played a crucial role in the founding of the science of chaos. Instead of merely speeding

problem solving, scientists used computers as tools—much as biologists use microscopes and engineers use oscilloscopes—to explore the graphical landscapes generated by seemingly simple equations.

The programs in this package are fully realized versions of the programs that gave rise to the most important discoveries of the science of chaos. The six programs are the Mandelbrot sets, magnets and

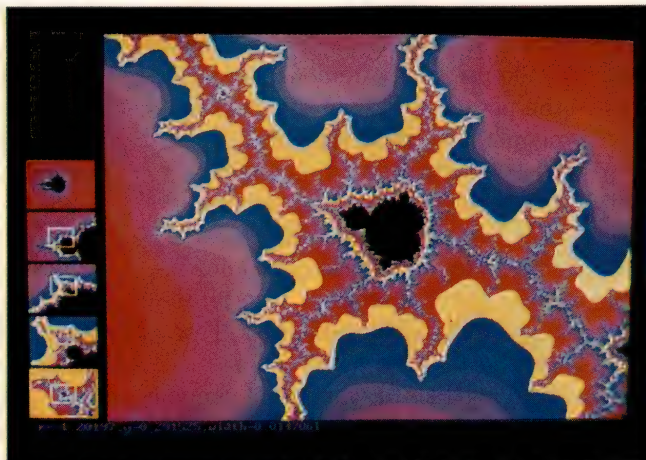
chapter is a discussion of the mathematics of that particular program.

The second chapter of the manual describes the Mandelbrot set, which looks like a snowman with smaller and smaller heads attached all over it. Upon closer look, the edges of the heads look like a fine, intricate lace whose pattern never repeats. Users can pan across the set scanning the boundary, then zoom in closer and closer, revealing layer upon layer of complexity.

The actual set is a collection of points shown as black on screen. For each complex number n , the computer computes the sequence of numbers n , $n^2 + n$, $(n^2 + n)^2 + n$, If the numbers get larger and larger, running away toward infinity, the original point is not part of the Mandelbrot set. If the point is in the set, the numbers remain locked in a repeating loop or bounce chaotically from one point to the next but do not approach infinity.

The colors of the image are like the colors of a contour map—they show how steeply the rest of the terrain falls away from the set. Points not in the set escape to infinity at varying rates, which the program shows using different colors.

The geometry of the Mandelbrot set shows that processes that are simple in themselves can create complexity through repetition and feedback. The set also shows that boundaries between, say, stability and instability in a system are not necessarily smooth. Such a boundary may be sufficiently complex that a slight change in starting



The colors of this section of the Mandelbrot set show how fast points fall away from the actual set, which is a collection of points shown as black on screen. The smaller boxes on the left show the previous five images.

pendulums, strange attractors, the chaos game, fractal forgeries, and toy universes. Using the programs you can tweak an image's parameters; view preset images; change colors; add sound, and move around an image by zooming, panning, and centering.

Each chapter of the accompanying manual begins with Gleick's introduction to the chaos theory the program demonstrates and his suggestions of things to try with the program. Next are step-by-step instructions for using the program and information about its features and options. Wrapping up each

conditions may throw the system off into a different region.

One drawback to this software package is that it's slow. To draw an image, the program paints the screen four times going from a coarse to an increasingly fine resolution. On my coprocessor-less 286-based computer, the first screen takes about 9 sec, the second 25 sec, the third 1 minute and 25 sec, and the fourth almost 6 minutes. However, you don't have to wait for the program to finish an image before you make a change to that image or start a new one.

Chaos runs on IBM PC/XT, PC/AT, PS/2, and compatible computers that have an EGA or VGA display and 640 kbytes of memory. Autodesk recommends a math coprocessor, although one is not required. The software package includes the illustrated 238-pg manual, 5¼- and 3½-in. program disks, and quick-reference cards.

—Julie Anne Schofield

James Gleick's Chaos: The Software, Autodesk Inc, 2320 Marinship Way, Sausalito, CA 94965. Phone (800) 688-2344, (415) 332-2344. FAX (415) 331-8093. \$59.95.

Chaos: Making a New Science, by James Gleick, Viking Penguin Inc, New York, NY, 1987, 354 pgs. ISBN 0-14-00.925-1. Hardcover, \$22.95; paperback, \$14.95.

Finding a map and a compass for leaders and managers

Author Stephen R Covey has taken the ideas from his book *The Seven Habits of Highly Effective People* and applied them to the arts of leadership and management in an excellent book, *Principle-Centered Leadership*. Covey's approach is fundamental. He is more

concerned with character than personality, with principles than practices. Covey writes: "Practices are the *what to do's*, ... Principles are the *why to do's*."

If you're looking for a map to guide you across the managerial terrain, Covey refuses to provide one for you. Business terrains change daily, making maps quickly obsolete. However, if you're looking for a metaphysical compass with which to lead your people, you'll find one in this book. That compass is constructed from Covey's seven habits, which urge you to be principle-centered instead of procedure-centered; procedures can change but fundamental principles won't.

Skeptics may immediately see the potential flaw in this reasoning: people have different ideas about what constitutes a fundamental principle. Covey notes, however, that certain fundamentals are shared by all. These principles include fairness, equity, justice, integrity, honesty, and trust. Few could argue the point. Who wouldn't like to work at a company governed by these principles?

Such a world sounds utopian, though. At first glance, aligning the corporate world with the true North of fundamental principles sounds impossible and that may well be the case. Instead, Covey urges you to make these principles work at your company by internalizing and living them yourself.

Many people feel that things would be great if only that bozo over there or those clowns in that other department would shape up. Covey's philosophy won't let you off the hook that easily. You can always choose your response to any situation, and your choice should be based on these fundamental principles, not emotions or unthinking adherence to procedures. At a stroke, Covey puts you at the center of all of your problems and makes you the

sole solution. His ideas are at the very least thought-provoking.

Unfortunately, the book is not without flaws. It sometimes resembles a patchwork because several of its chapters were created by contributing authors. The topics ramble from you, to business, to your family, and then to educational institutions. One chapter in the book seems to be little more than an advertisement for the Covey Leadership Center; it talks about who the center has worked with but says nothing about what was done.

In addition, small offers appear at the bottom of several pages in the book, urging you to call a toll-free number to obtain free worksheets or audio cassettes. I wish that those worksheets had been included in the book, perhaps in appendices. I can only conclude that Covey took this approach to obtain names for his newsletter's and leadership center's mailing lists. The offers are free so the inconvenience isn't great. Even so, I liked the book.—Steven H Leibson

Principle-Centered Leadership, Summit Books, New York, 1991, \$20.

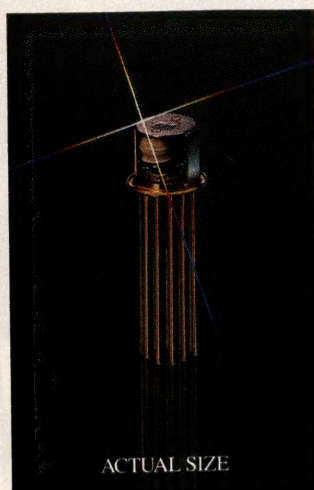
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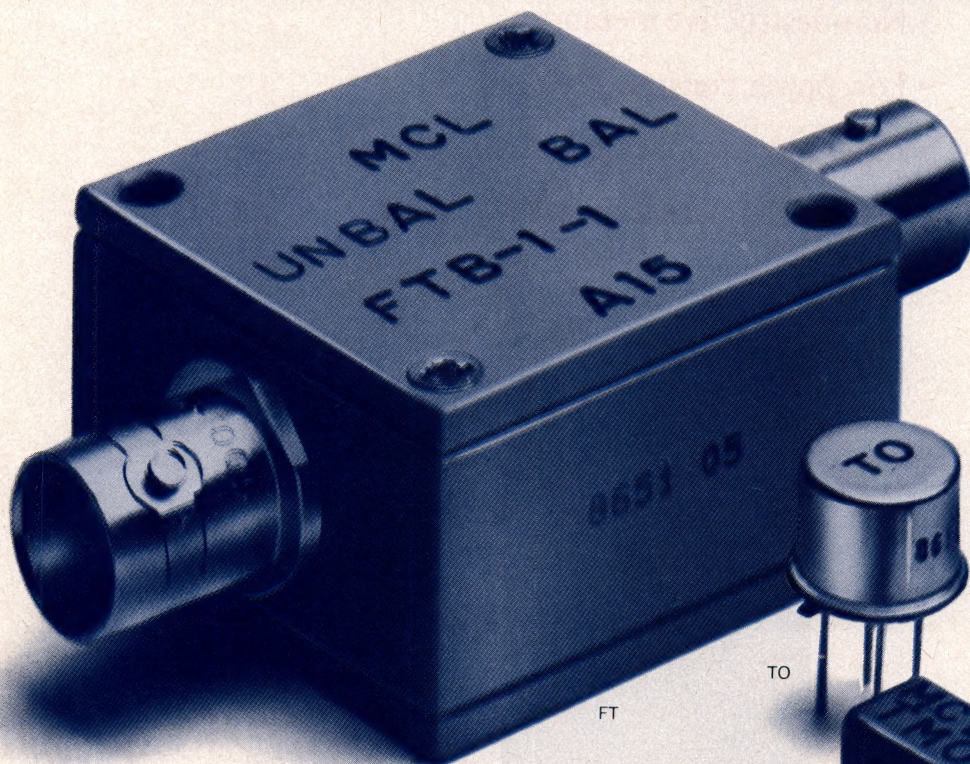
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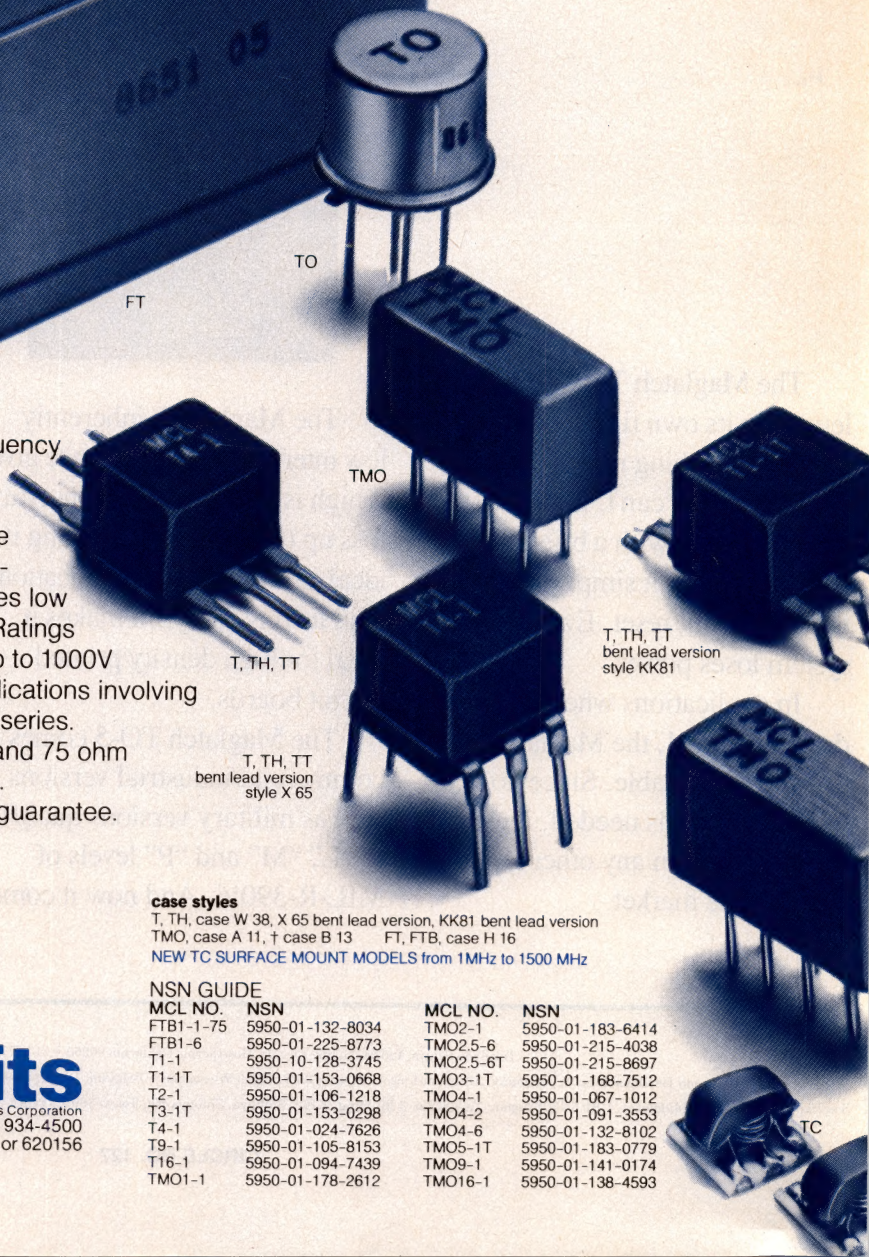
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T2-1	5950-01-106-1218	TMO4-1	5950-01-067-1012
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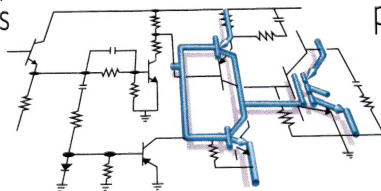
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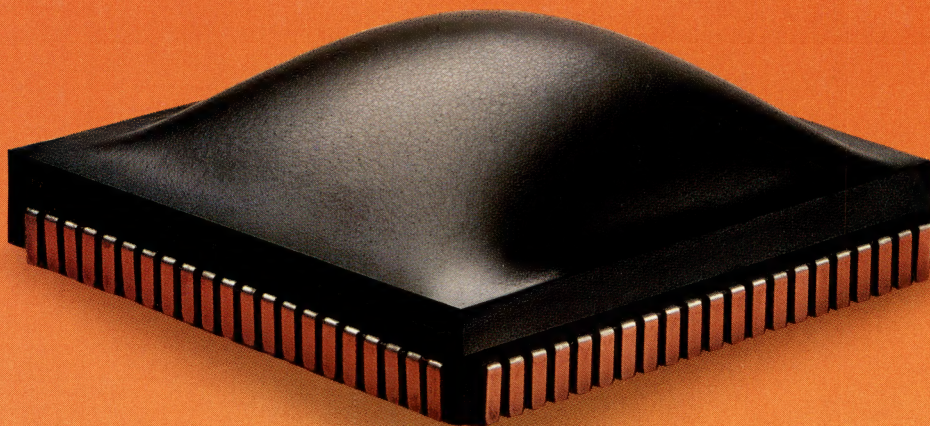
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